

# On the Queue Number of Planar Graphs

GD2021

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1. University of Tübingen, Germany

2. Osnabrück University, Germany

3. National Technical University of Athens, Greece

Tübingen, 16/09/2021

# Definitions

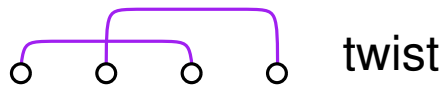
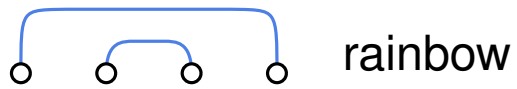
## Linear Layout

- vertices along the *spine*
- edges on *pages*

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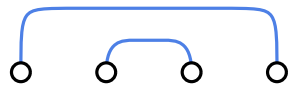
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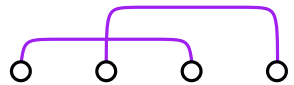
- vertices along the **spine**
- edges on **pages**



necklace



rainbow



twist

queue layout

yes

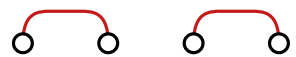
no

yes

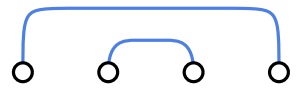
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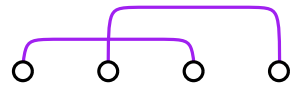
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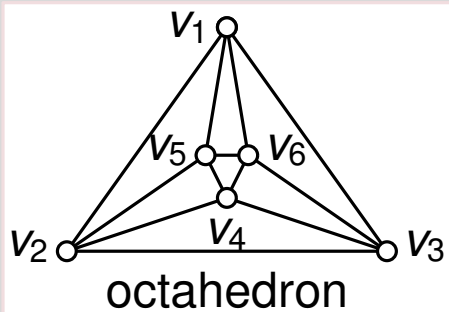
twist

queue layout

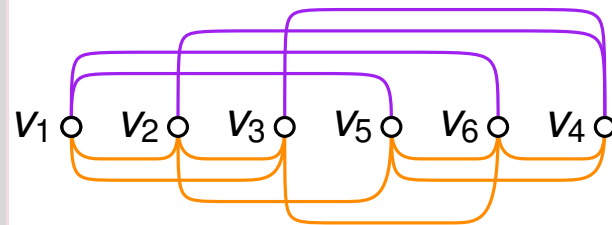
yes

no

yes



octahedron



queue layout

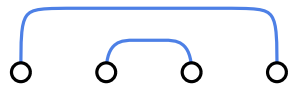
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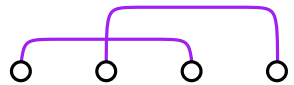
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### queue layout

yes

no

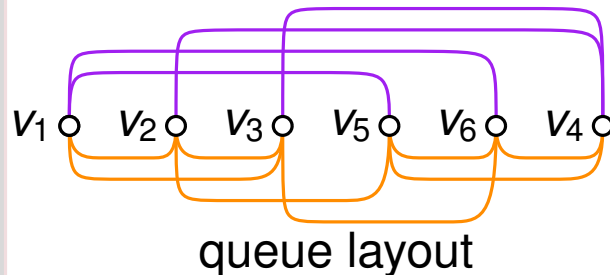
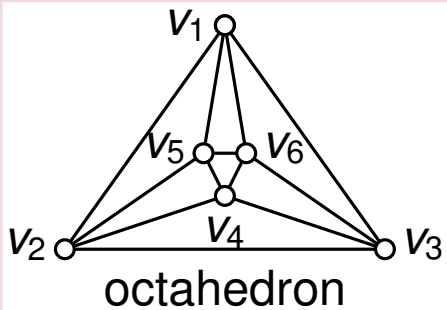
yes

## Queue number of graph

minimum number of pages  
over all queue layouts

## Queue number of graph family

maximum queue number  
over all elements



# Problem: Queue number of Planar Graphs

## Theorem<sup>[1]</sup>:

Planar graphs have queue number at most 49.

[1] Dujmović, Joret, Micek, Morin, Ueckerdt, Wood *Planar graphs have bounded queue-number* (2020)

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## Theorem<sup>[1]</sup>:

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## Improvement:

Planar graphs have queue number at most 42.

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# Problem: Queue number of Planar Graphs

## Theorem<sup>[1]</sup>:

Planar graphs have queue number at most 49.

## Improvement:

Planar graphs have queue number at most 42.

## Idea:

- Exploit planarity
- Modify existing technique

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# Timeline



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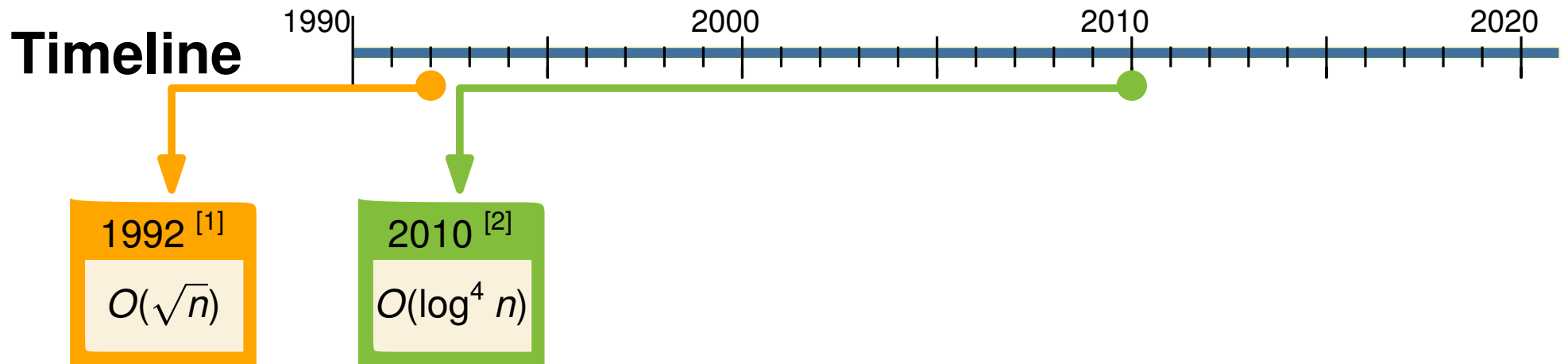
1992 <sup>[1]</sup>

$$O(\sqrt{n})$$

## Conjecture<sup>[1]</sup>:

Planar graphs have bounded queue number.

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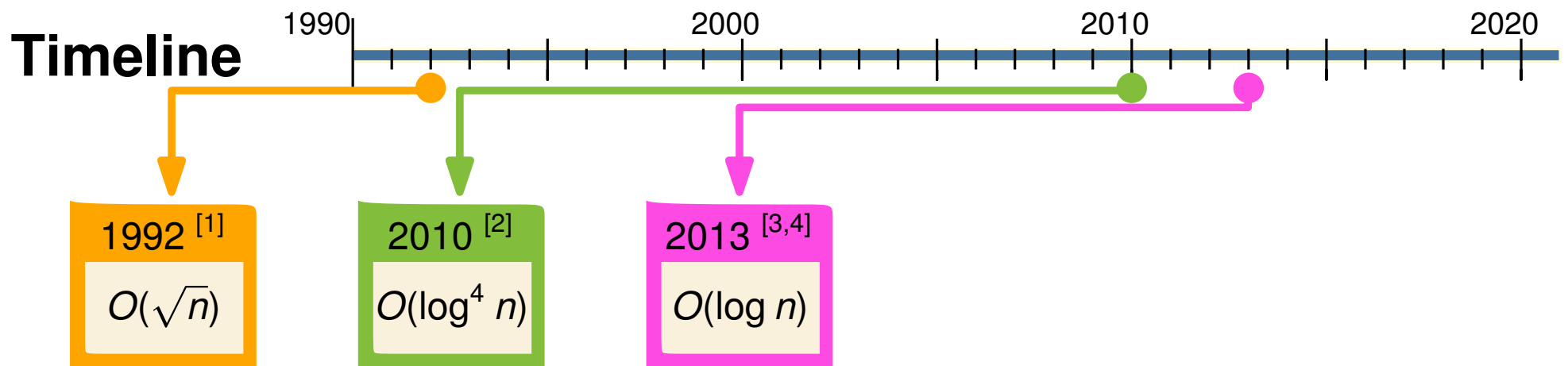


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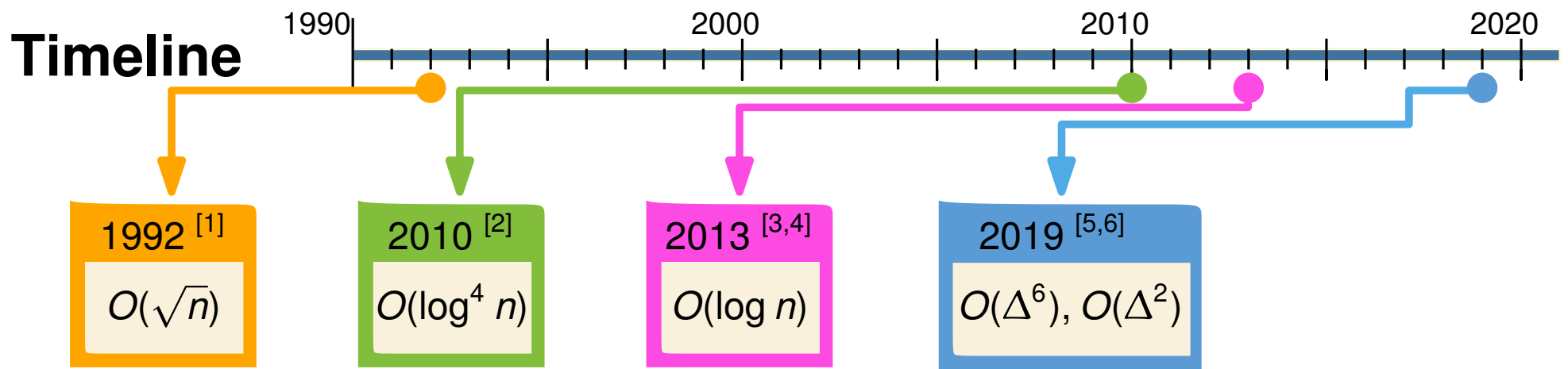
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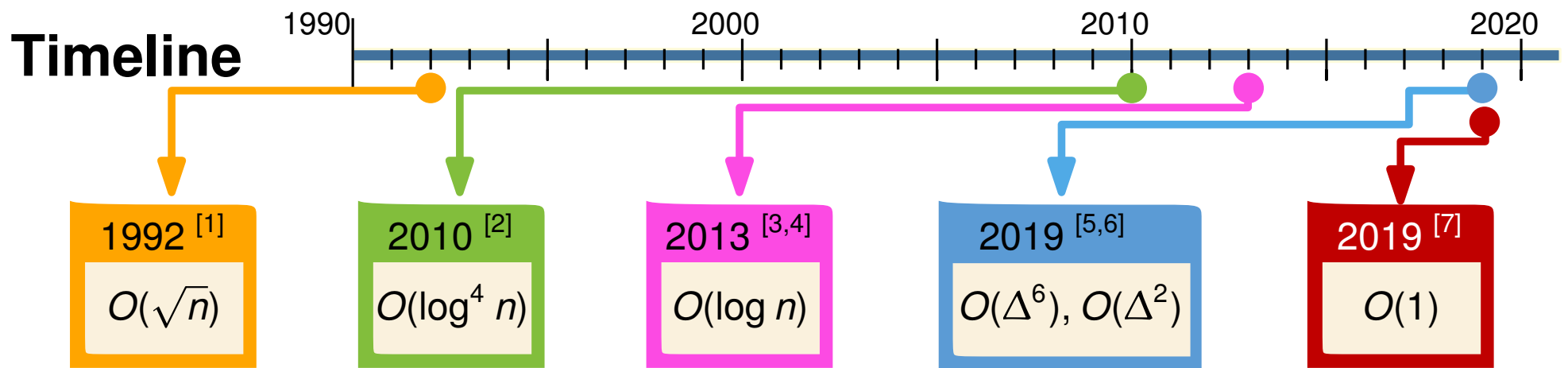
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[5] Bekos, Förster, Gronemann, Mchedlidze, Montecchiani, Raftopoulou, Ueckerdt:

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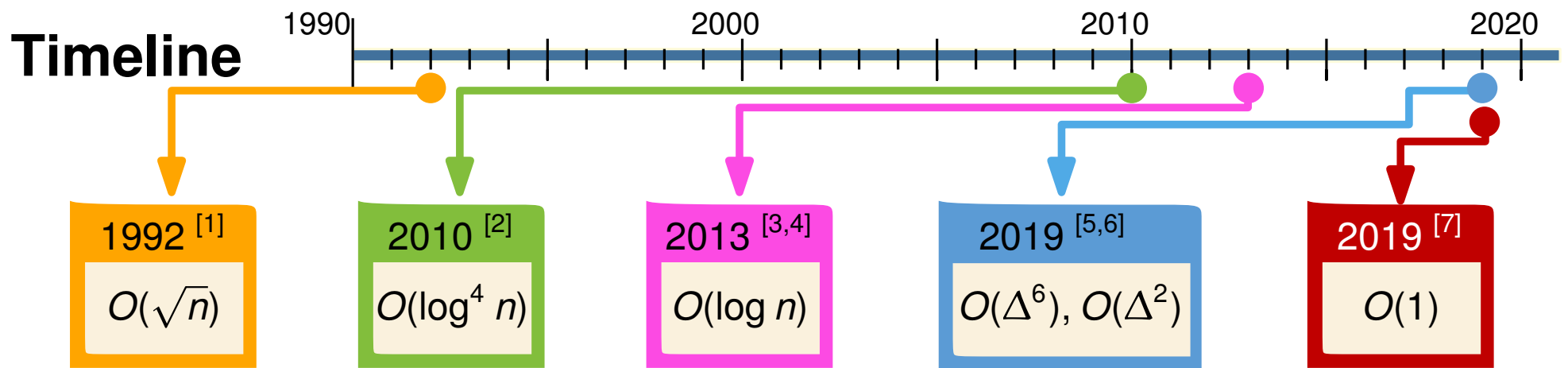
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# Strong Product

**Definition:**  $G \boxtimes H$

strong product of  $G$  and  $H$

(assume that  $G = P_k$ )

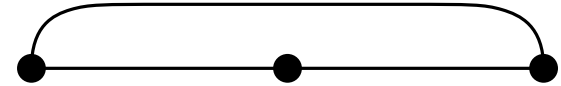
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$H$



$G$



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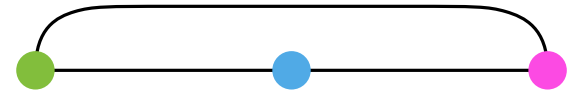
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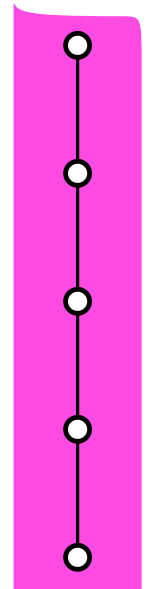
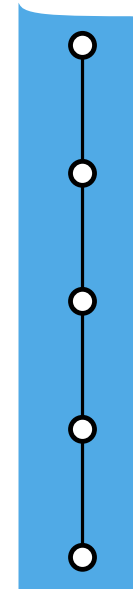
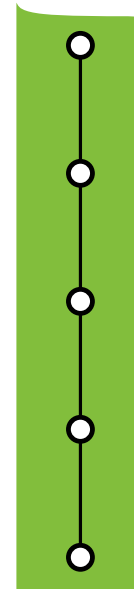
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$G$



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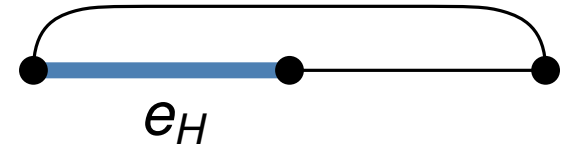
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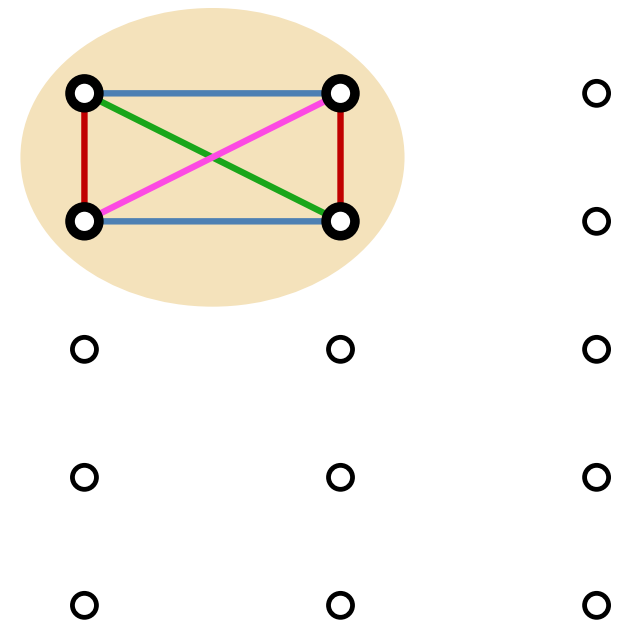
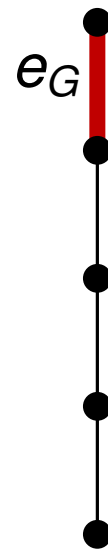
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$G$



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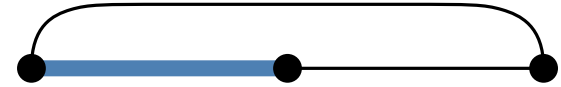
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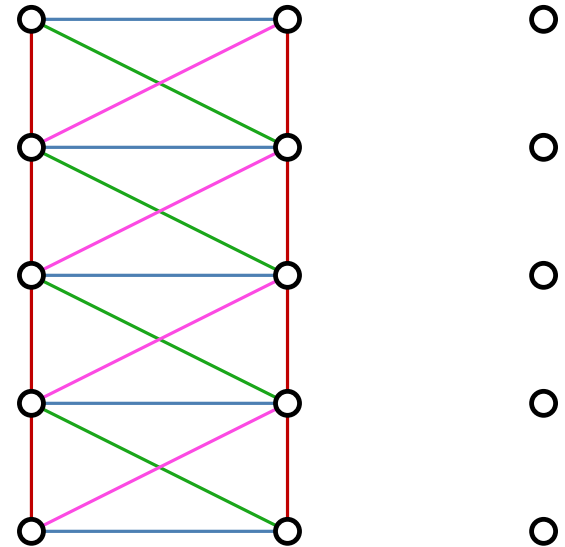
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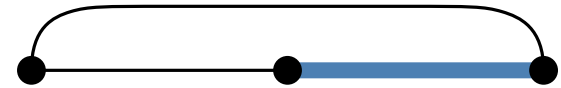
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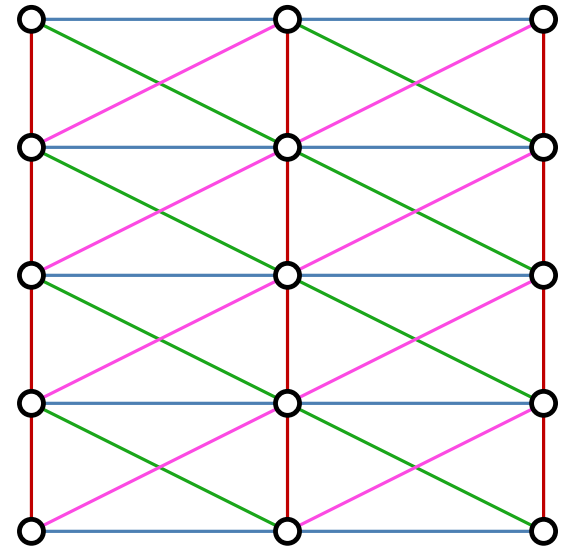
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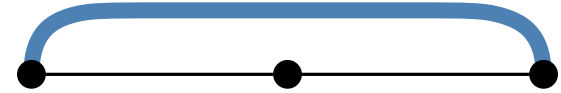
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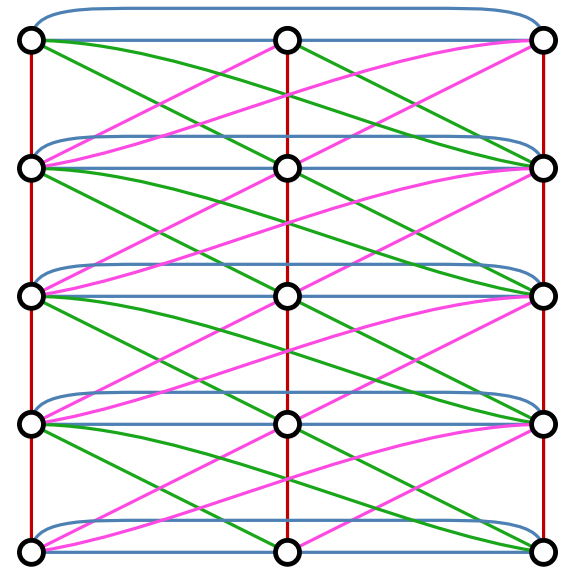
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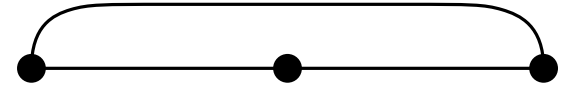
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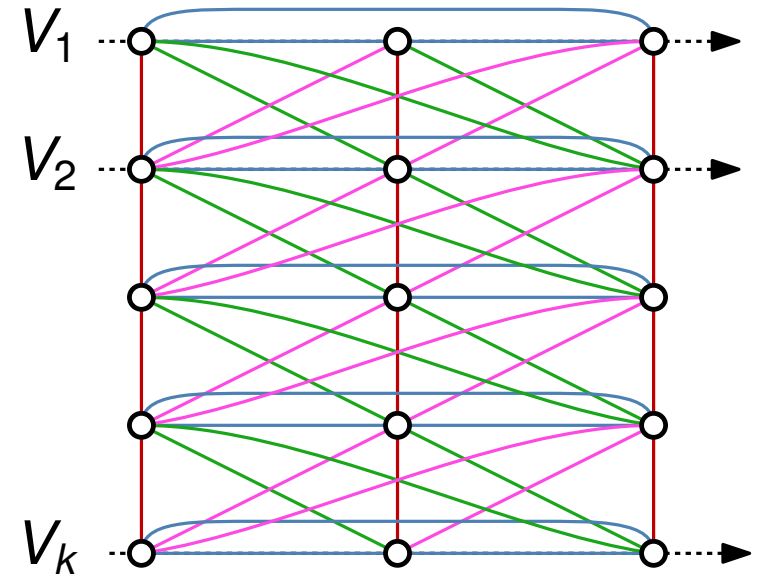
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$P_k$  implies a leveling  $\{V_1, V_2, \dots, V_k\}$

$H$



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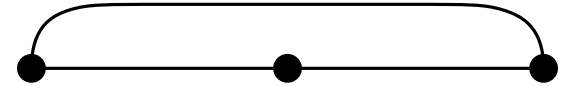
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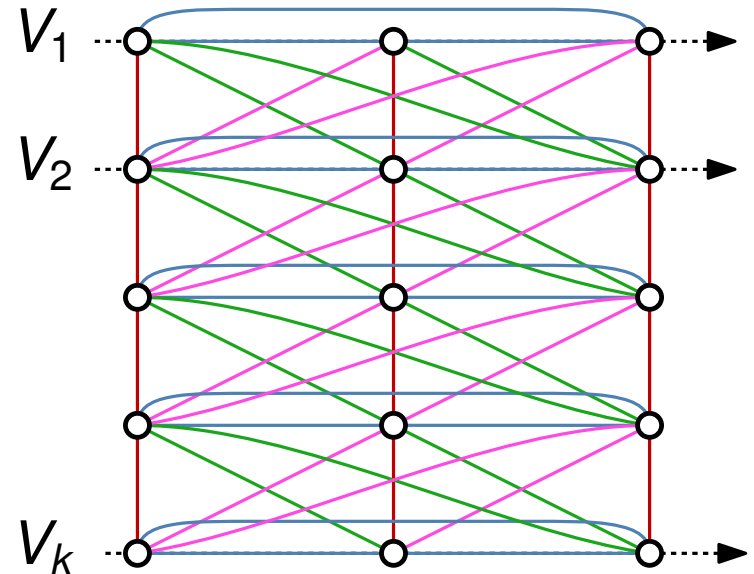
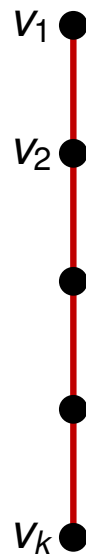
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**Types of edges**

$H$



$G$



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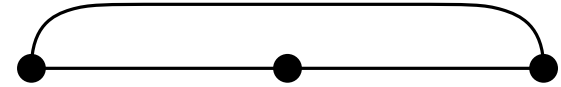
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## Types of edges

level

$H$



$G$

$v_1$

$v_2$

$v_k$

$V_1$

$V_2$

$V_k$



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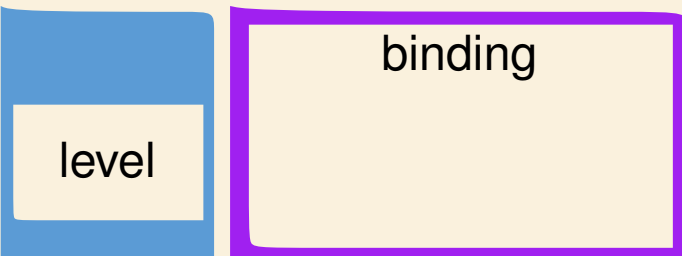
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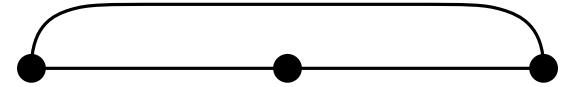
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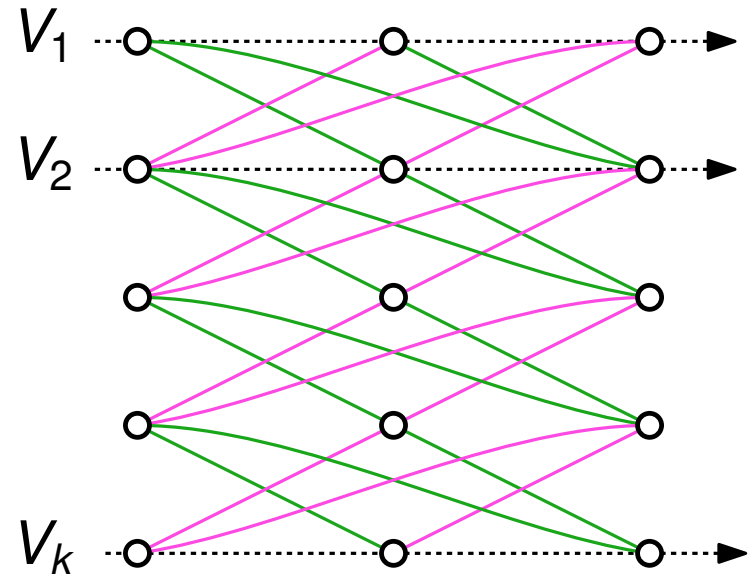
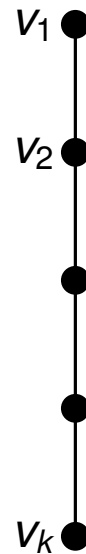
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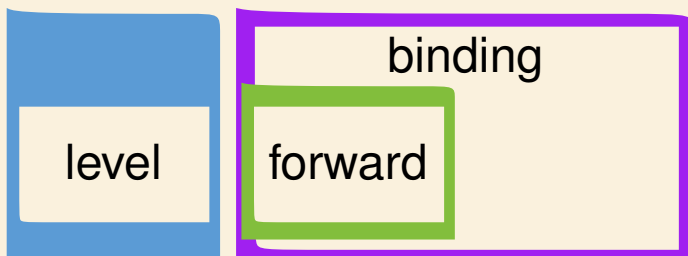
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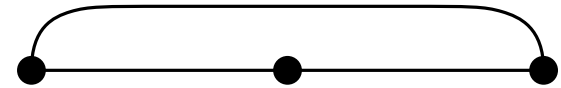
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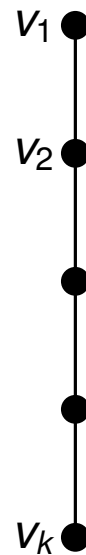
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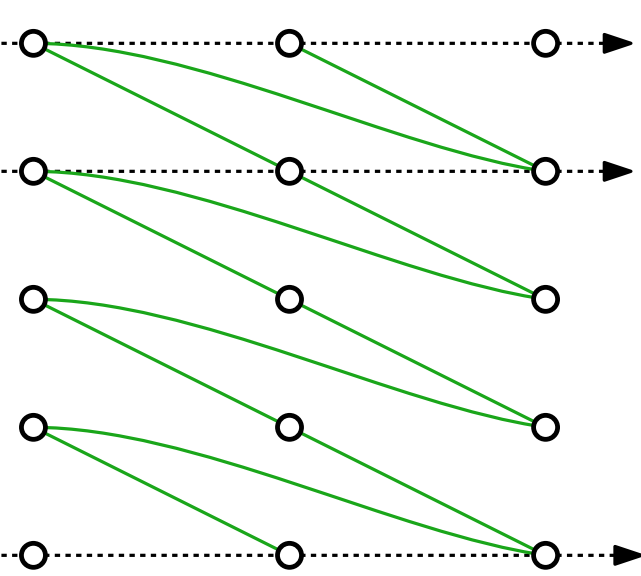
$G$



$V_1$

$V_2$

$V_k$



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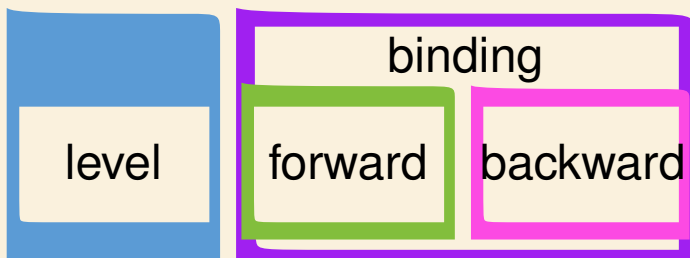
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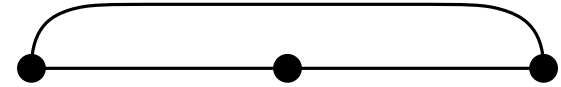
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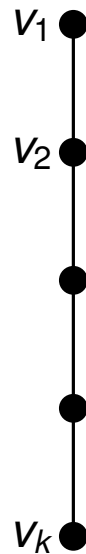
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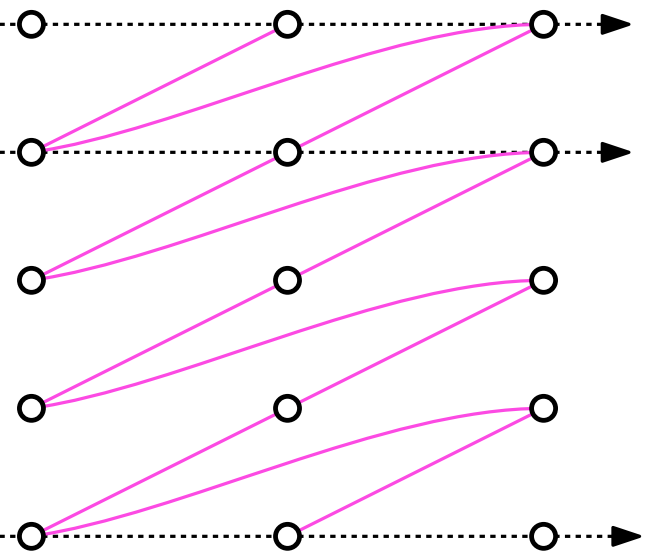
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$V_1$

$V_2$

$V_k$



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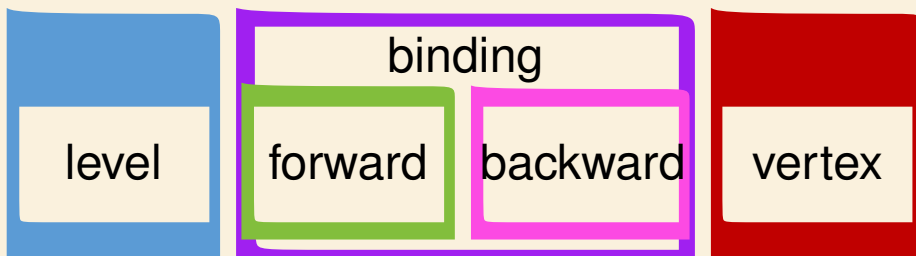
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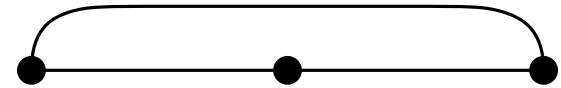
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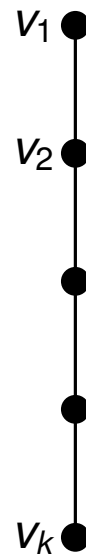
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$H$



$G$



$V_1$



$V_2$



$V_k$



# Strong Product

Queue number<sup>[1]</sup>:  $P \boxtimes H$

$$\text{qn}(P \boxtimes H) \leq 3 \cdot \text{qn}(H) + 1$$

[1] Wood, *Queue layouts of graph products and powers* (2005)

# Strong Product

Queue number<sup>[1]</sup>:  $P \boxtimes H$

$$\text{qn}(P \boxtimes H) \leq 3 \cdot \text{qn}(H) + 1$$

**Theorem** <sup>[2]</sup>:

$\text{qn}(G) = k$  if and only if there is a vertex order with no  $(k + 1)$ -rainbow

[1] Wood, *Queue layouts of graph products and powers* (2005)

[2] Heath, Rosenberg: *Laying out graphs using queues* (1992)



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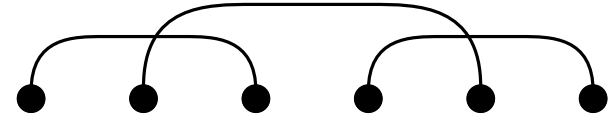
**Theorem** <sup>[2]</sup>:

$\text{qn}(G) = k$  if and only if there is a vertex order with no  $(k + 1)$ -rainbow

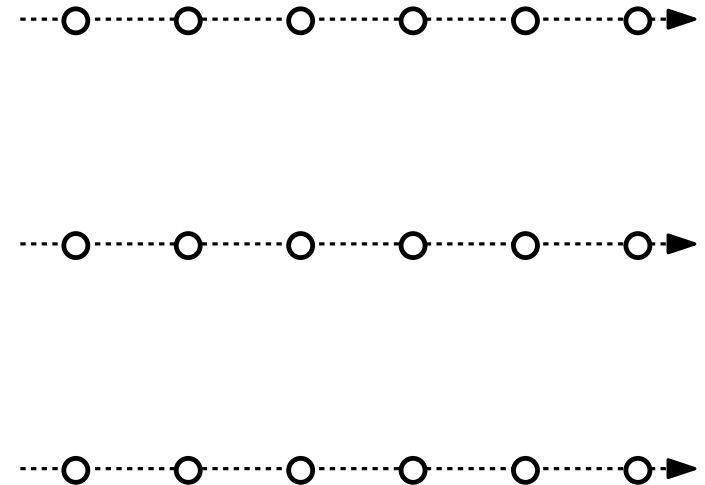
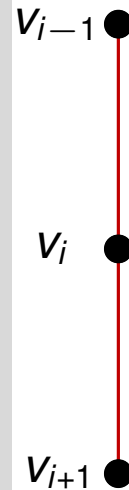
- queue layout of  $H$  with  $\text{qn}(H)$  pages

edges on one queue of  $H$

$H$



$P$



[1] Wood, *Queue layouts of graph products and powers* (2005)

[2] Heath, Rosenberg: *Laying out graphs using queues* (1992)

# Strong Product

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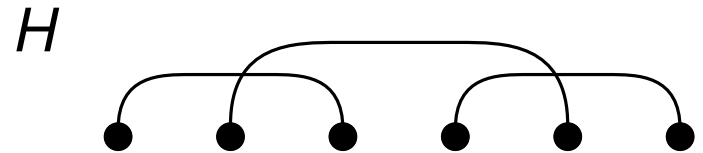
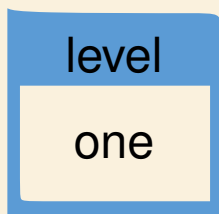
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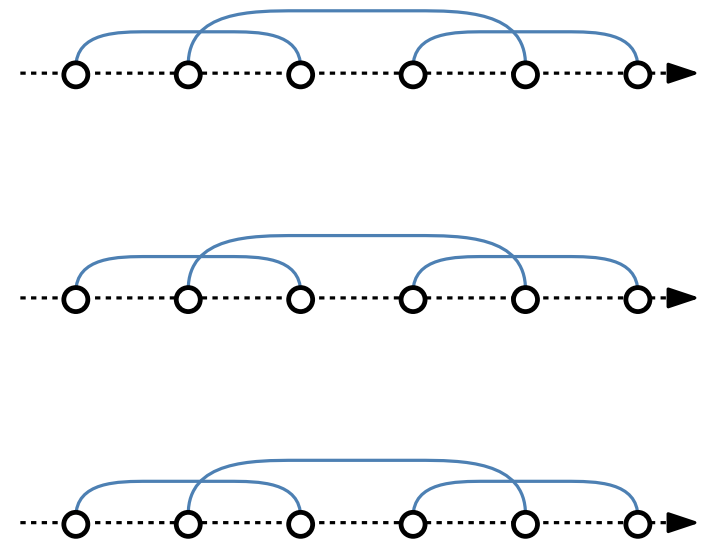


$P$

$v_{i-1}$

$v_i$

$v_{i+1}$



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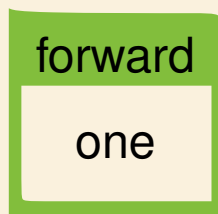
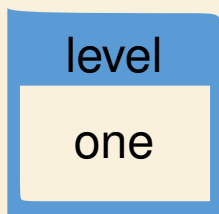
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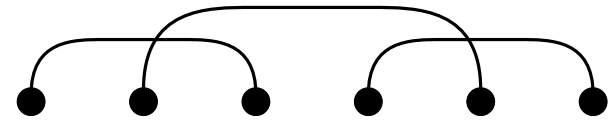
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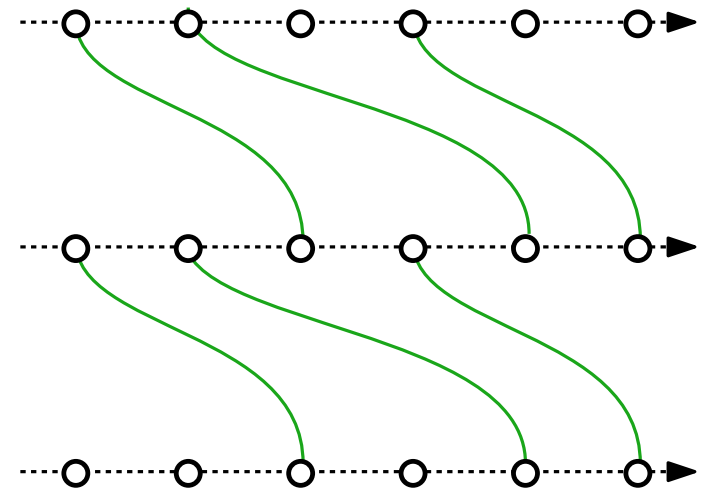
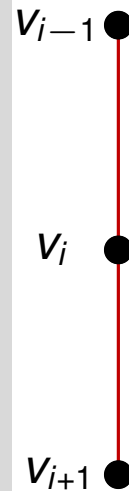
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$H$



$P$



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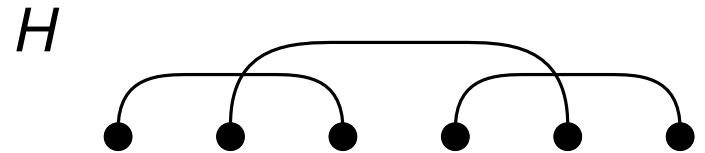
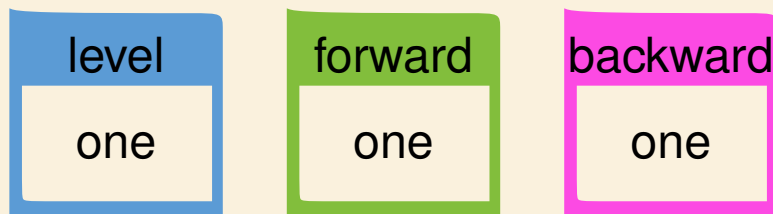
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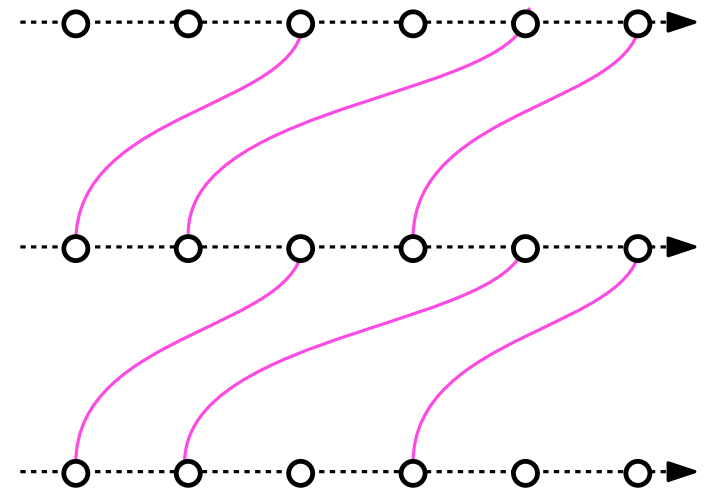


$P$

$v_{i-1}$

$v_i$

$v_{i+1}$



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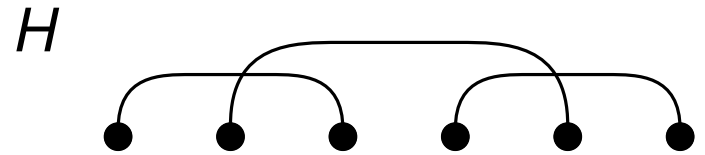
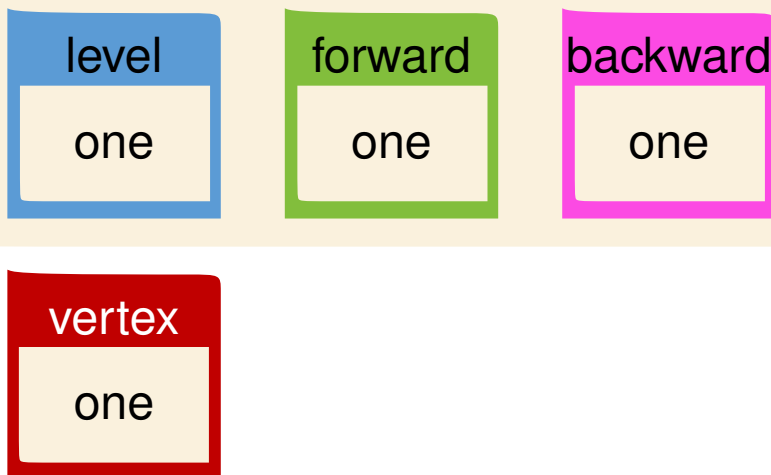
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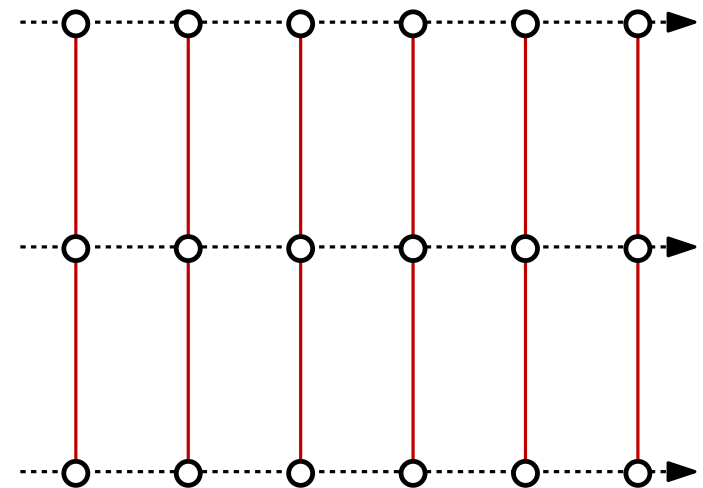
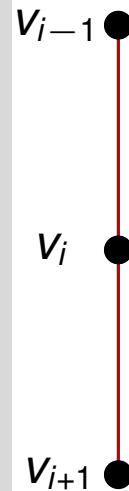
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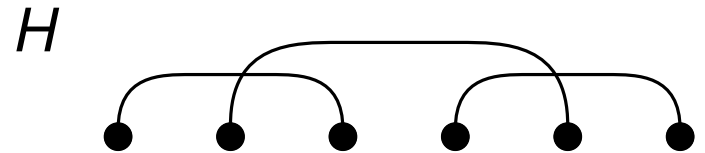
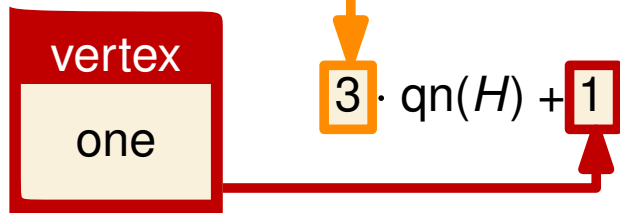
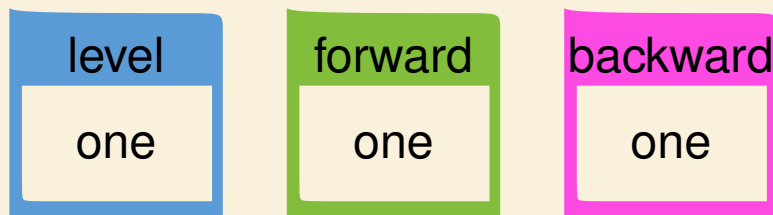
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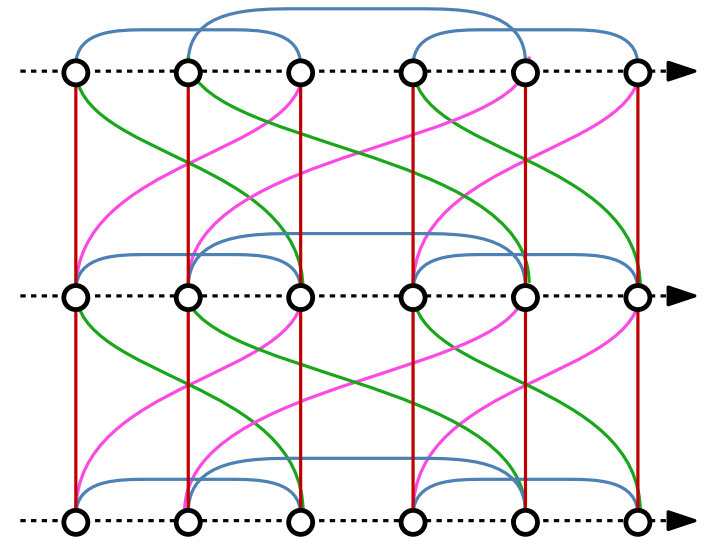


$P$

$v_{i-1}$

$v_i$

$v_{i+1}$



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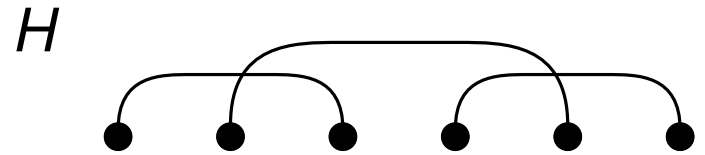
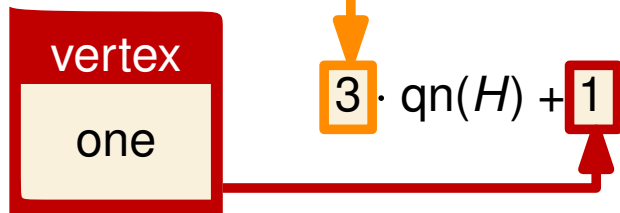
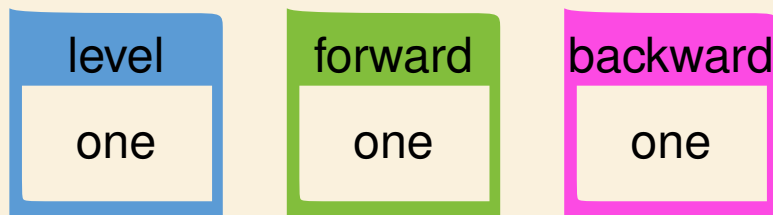
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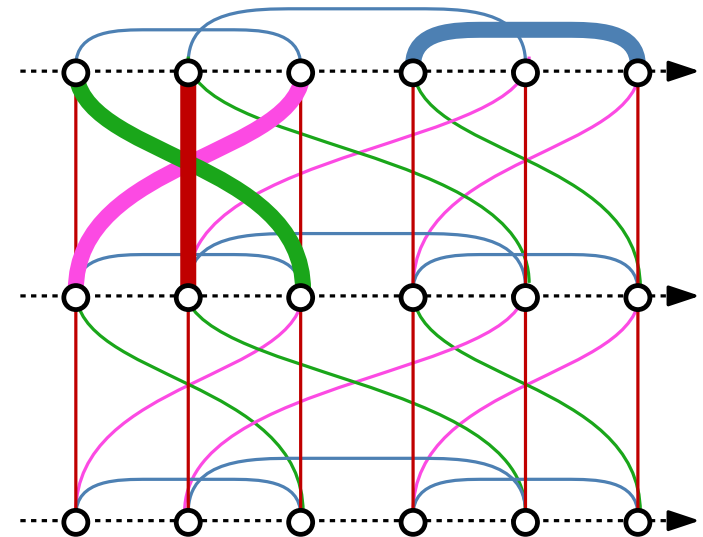


$P$

$v_{i-1}$

$v_i$

$v_{i+1}$



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# Strong Product of planar graphs

## Theorem<sup>[1]</sup>:

$G$  planar subgraph of  $P_k \boxtimes H \boxtimes K_3$

[1] Dujmović, Joret, Micek, Morin, Ueckerdt, Wood  
*Planar graphs have bounded queue-number* (2020)



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$H$

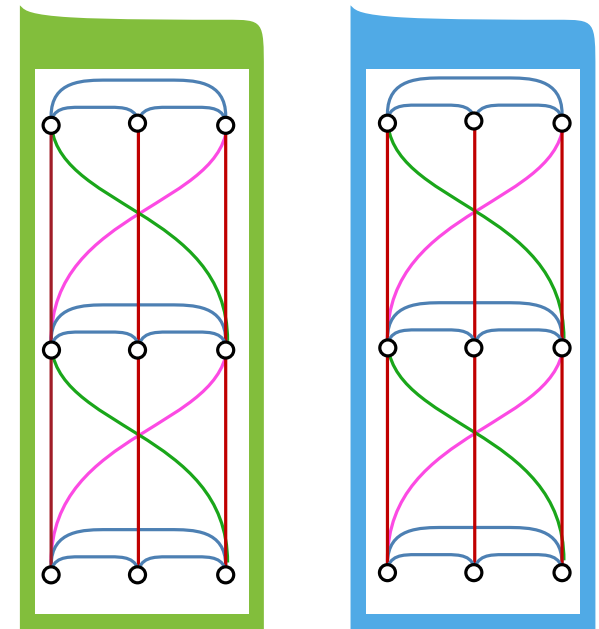


$P_k$

$v_{i-1}$

$v_i$

$v_{i+1}$



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edges on one queue of  $H$

$H$



$P_k$

$v_{i-1}$

$v_i$

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edges on one queue of  $H$

level

three

$H$

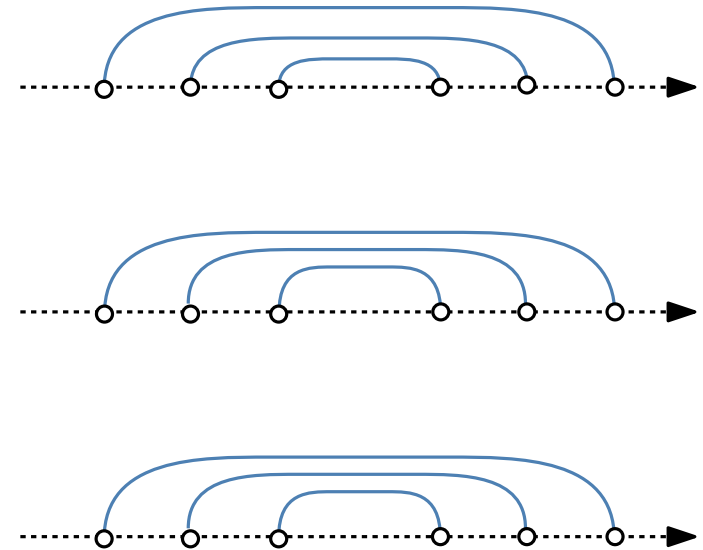


$P_k$

$v_{i-1}$

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level

three

forward

three

$H$

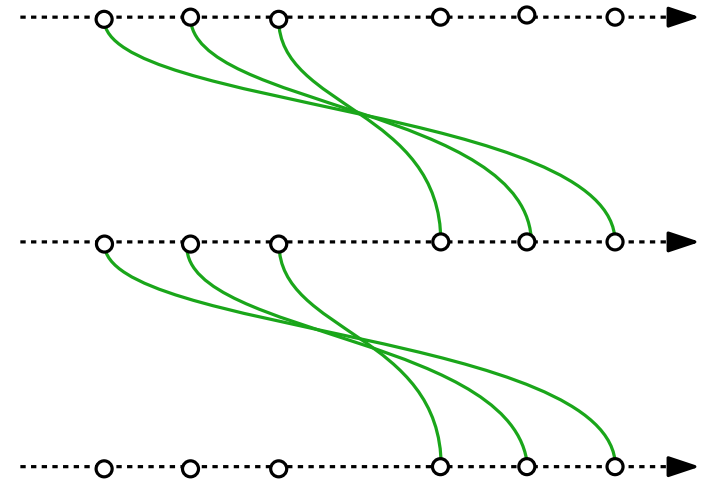


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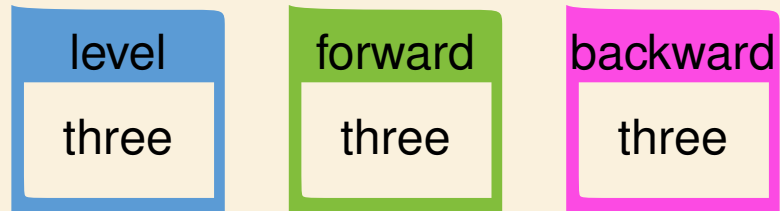
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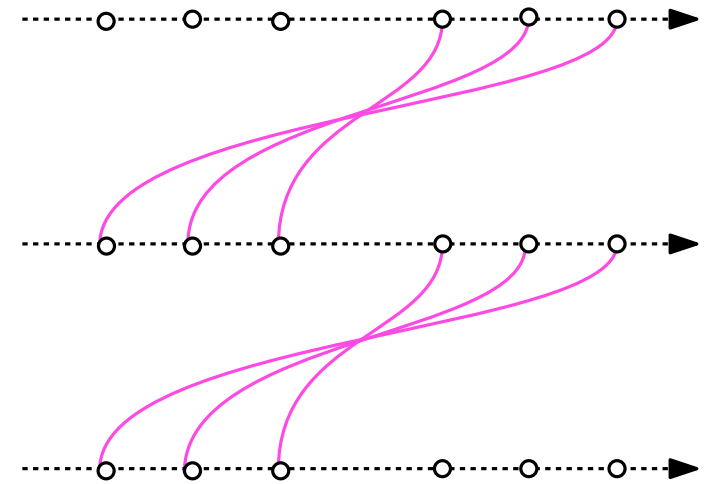
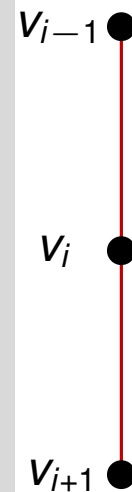
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$H$



$P_k$



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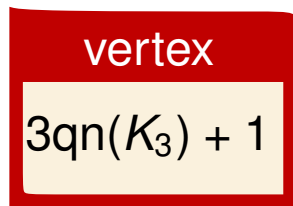
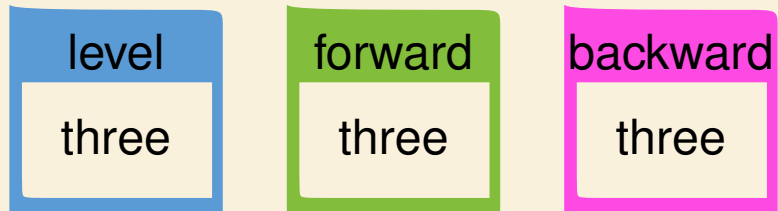
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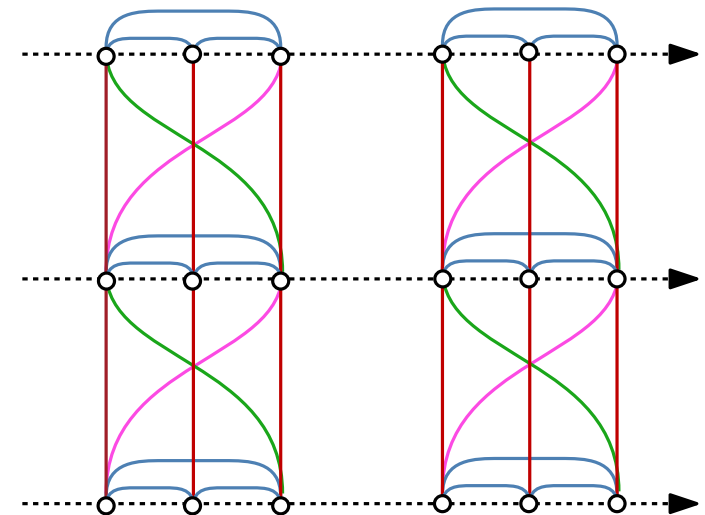
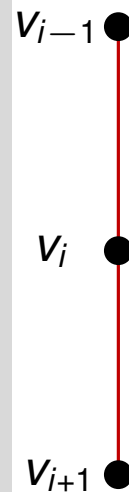
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$H$



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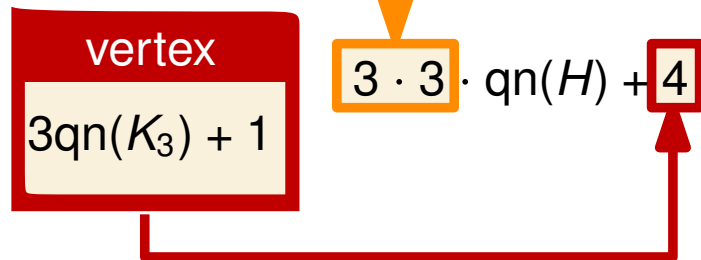
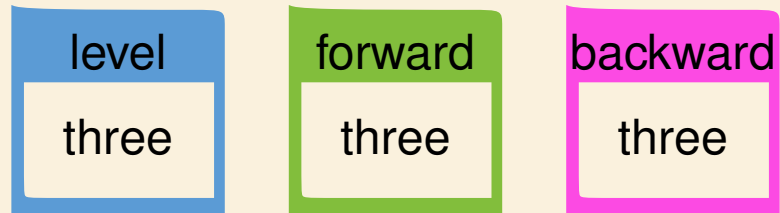
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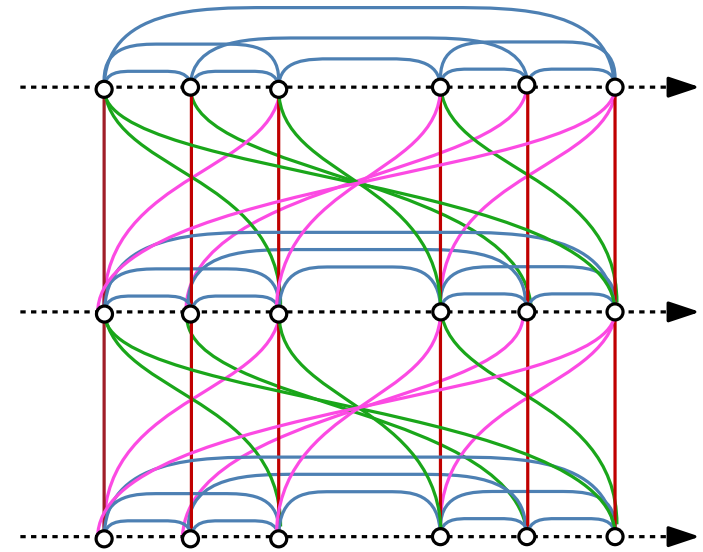
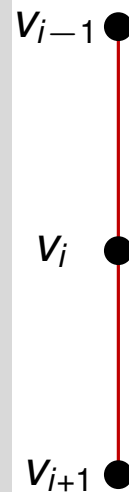
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$H$



$P_k$



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# Step 1: compute graph H

**Theorem** [ Dujmović et al.]:

Planar graph  $G$  subgraph of  $P \boxtimes H \boxtimes K_3$  where  $H$  is a planar 3-tree

$$\text{qn}(G) \leq 3 \cdot 3 \cdot \text{qn}(H) + 4 \leq 49$$

$$(\text{qn}(H) \leq 5)$$



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- BFS-layering

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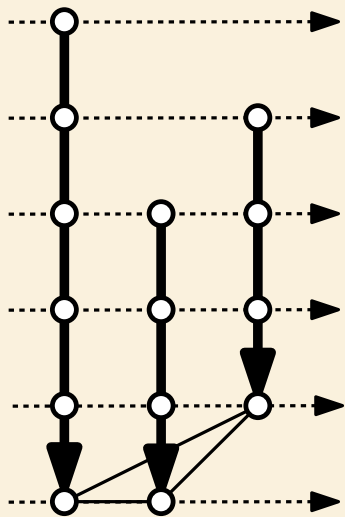
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- BFS-layering

### Definition: Tripod



subgraph of  $P \boxtimes K_3$

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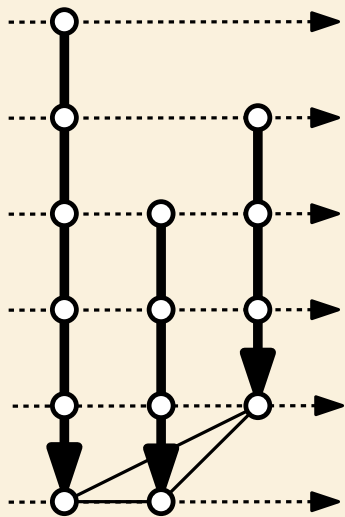
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- vertex partition in tripods

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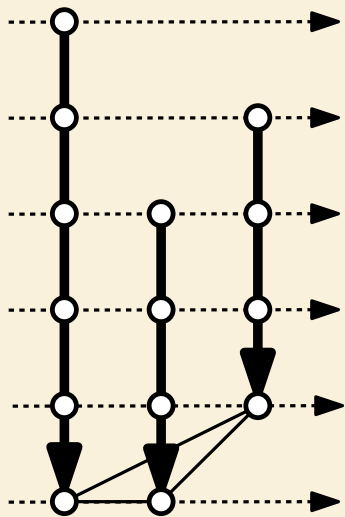
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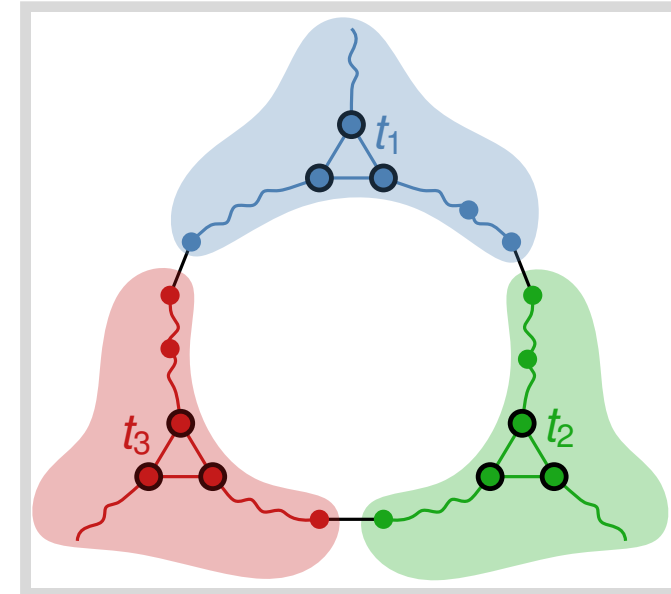
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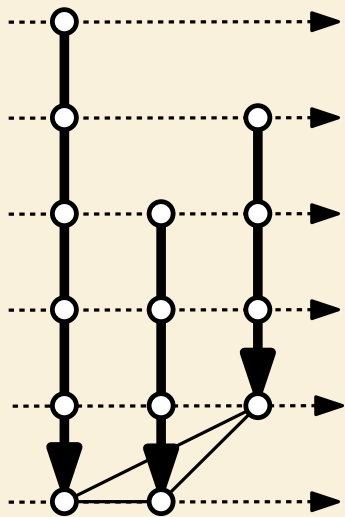
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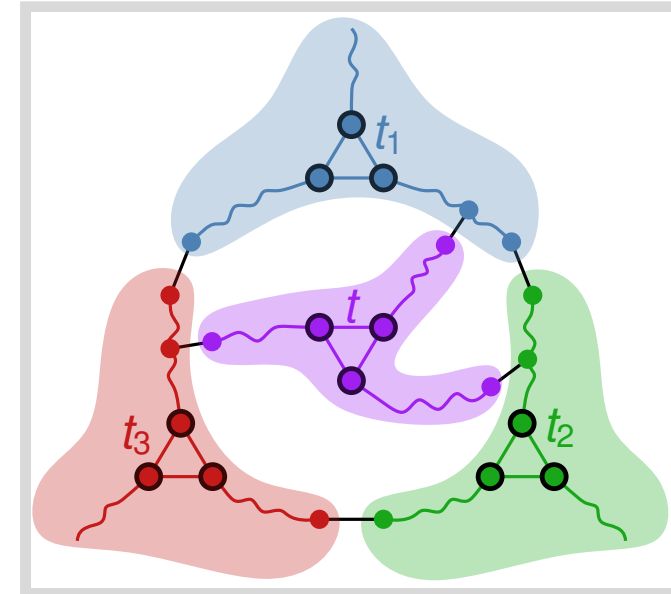
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# Step 1: compute graph H

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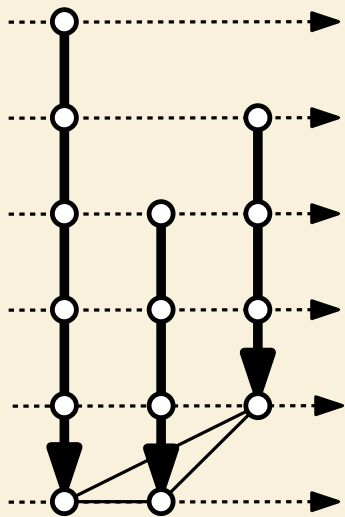
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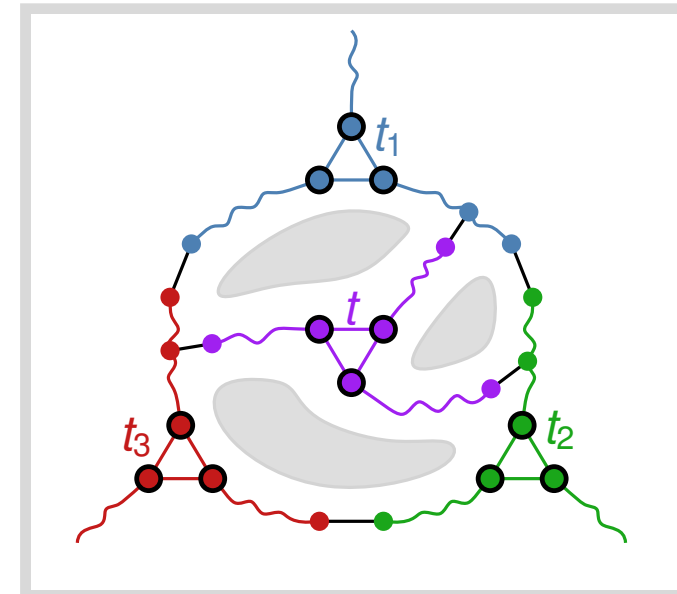
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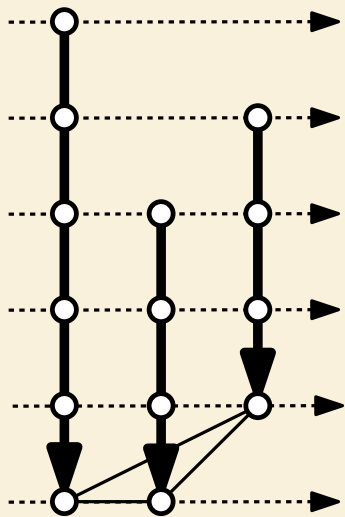
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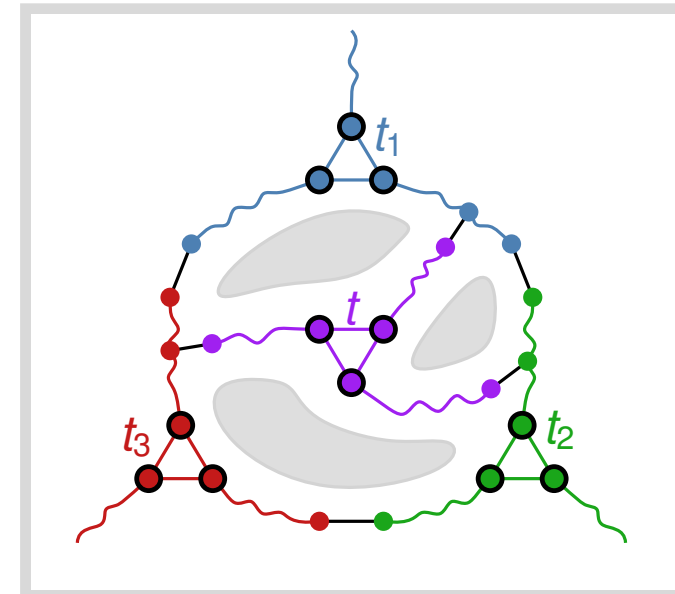
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- $t_1, t_2, t_3$  parents of  $t$



# Step 1: compute graph H

## Theorem [ Dujmović et al.]:

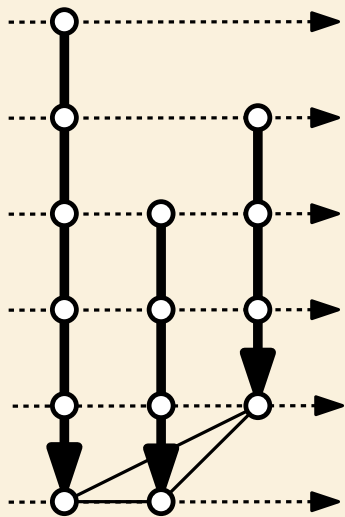
Planar graph  $G$  subgraph of  $P \boxtimes H \boxtimes K_3$  where  $H$  is a planar 3-tree

$$\text{qn}(G) \leq 3 \cdot 3 \cdot \text{qn}(H) + 4 \leq 49$$

$$(\text{qn}(H) \leq 5)$$

- BFS-layering

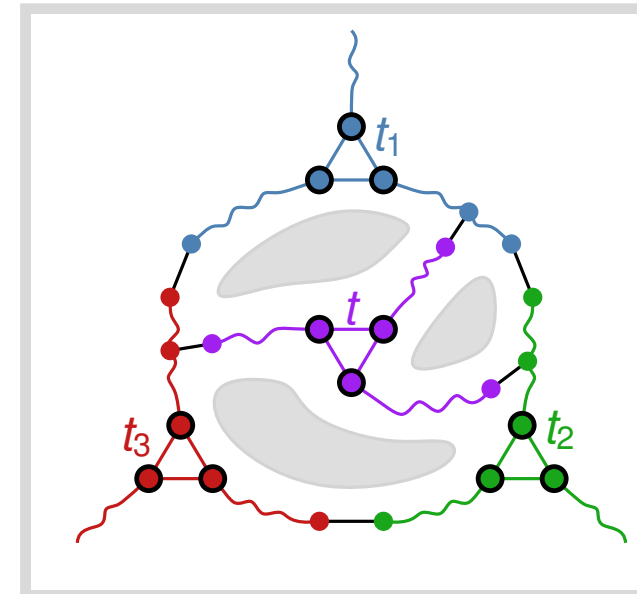
### Definition: Tripod



subgraph of  $P \boxtimes K_3$

### Tripod decomposition

- vertex partition in tripods
  - outerface bounded by  $t_1, t_2, t_3$
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### Graph H



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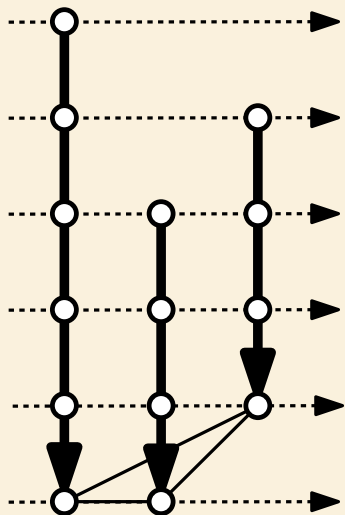
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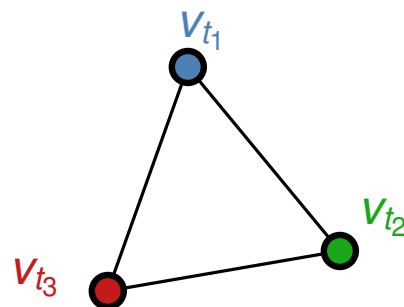
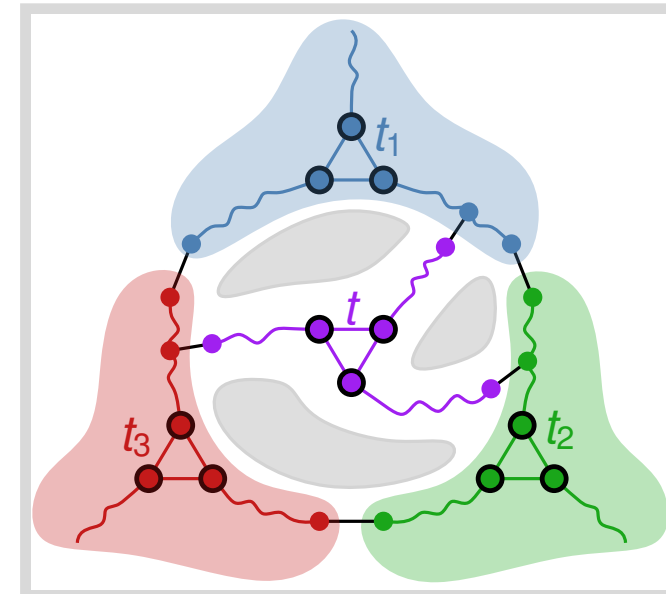
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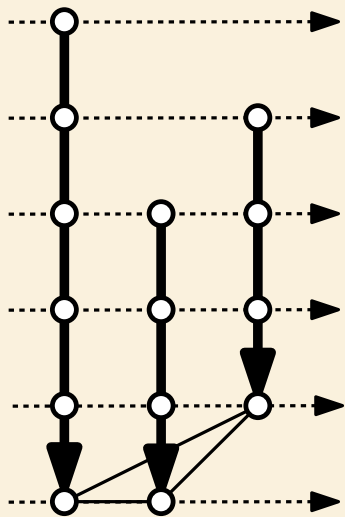
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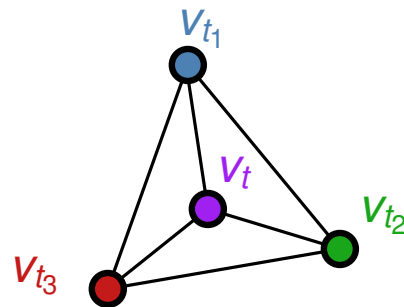
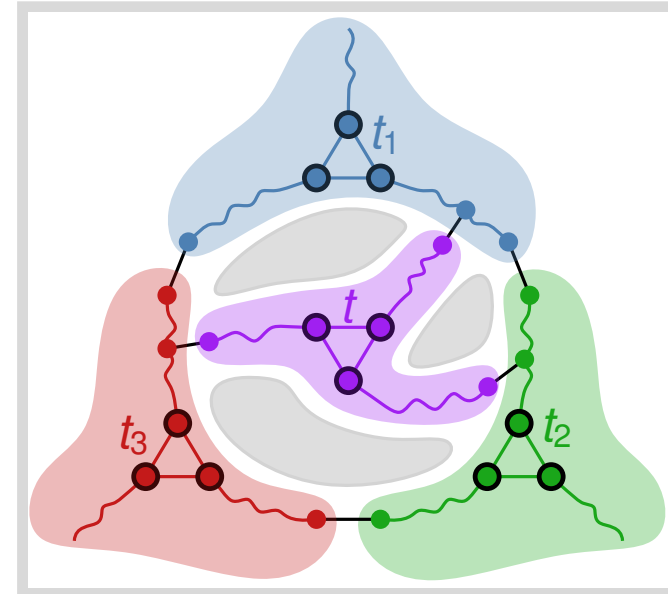
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### Graph H

- vertex  $v_t$  corresponds to tripod  $t$
- $v_t$  adjacent with  $v_{t_1}, v_{t_2}, v_{t_3}$

## Step 2: 5-queue layout of $H$

**Theorem<sup>[1]</sup>:**

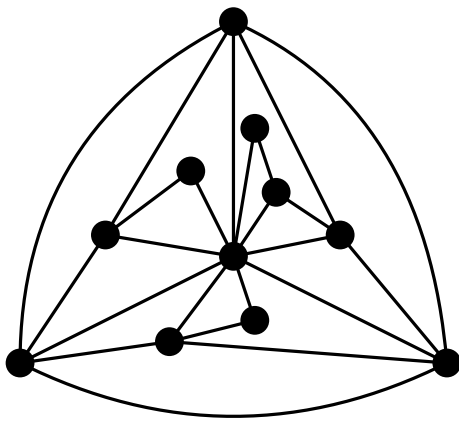
A planar 3-tree  $H$  has  $qn(H) \leq 5$

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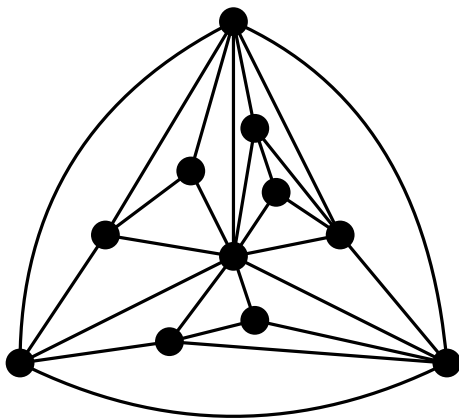
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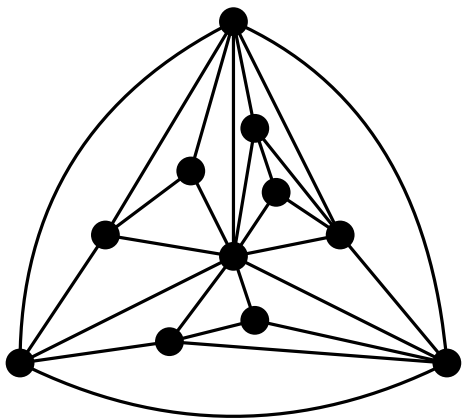
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## Step 2: 5-queue layout of $H$

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- leveling of vertices



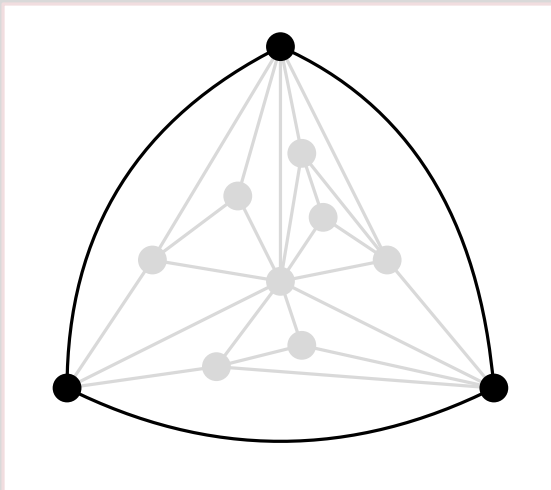
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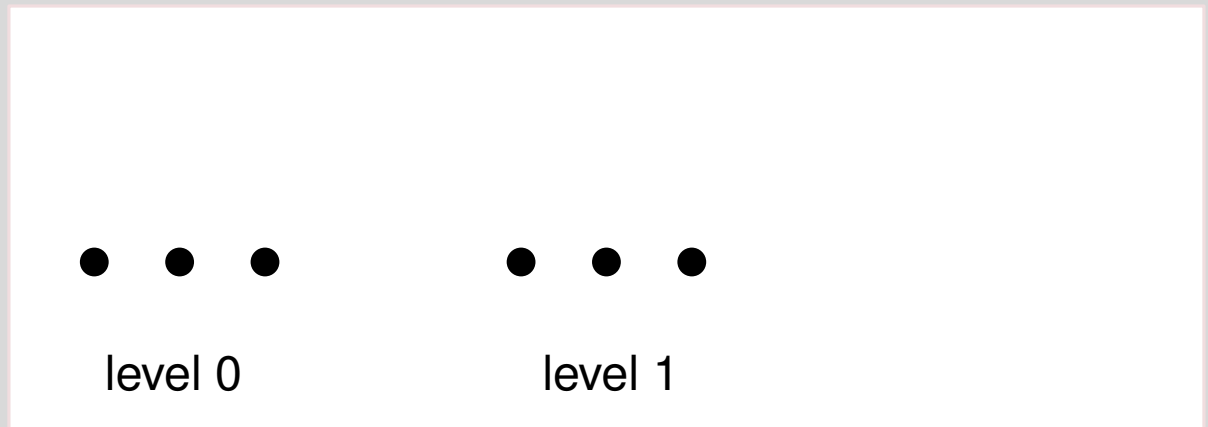
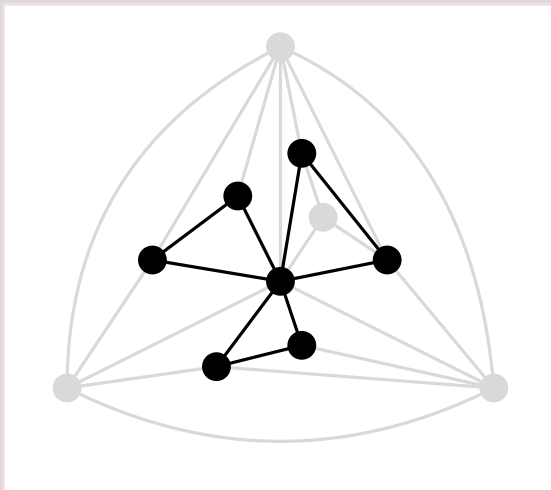
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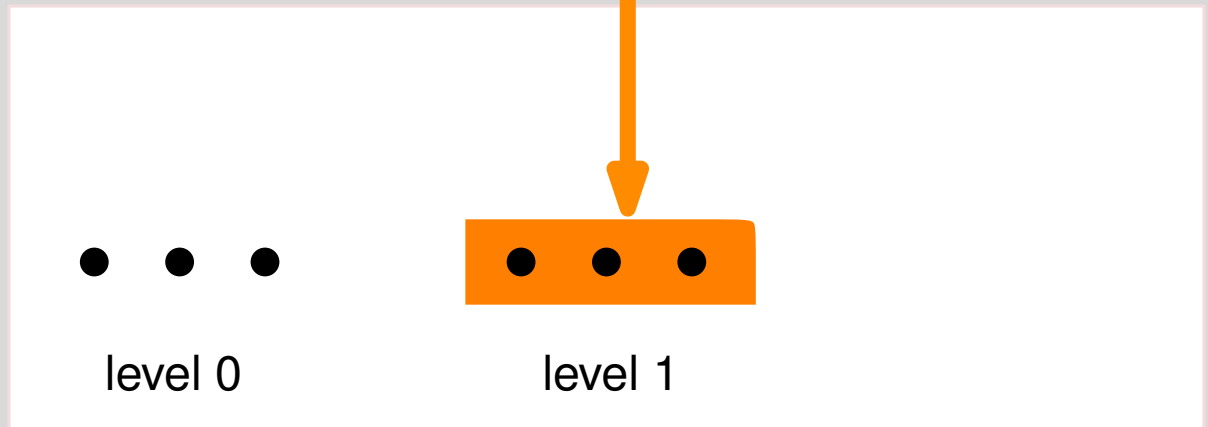
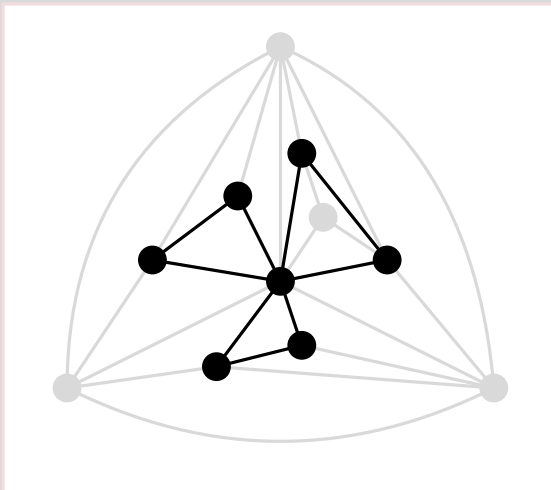
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2-queue layout of outerplanar



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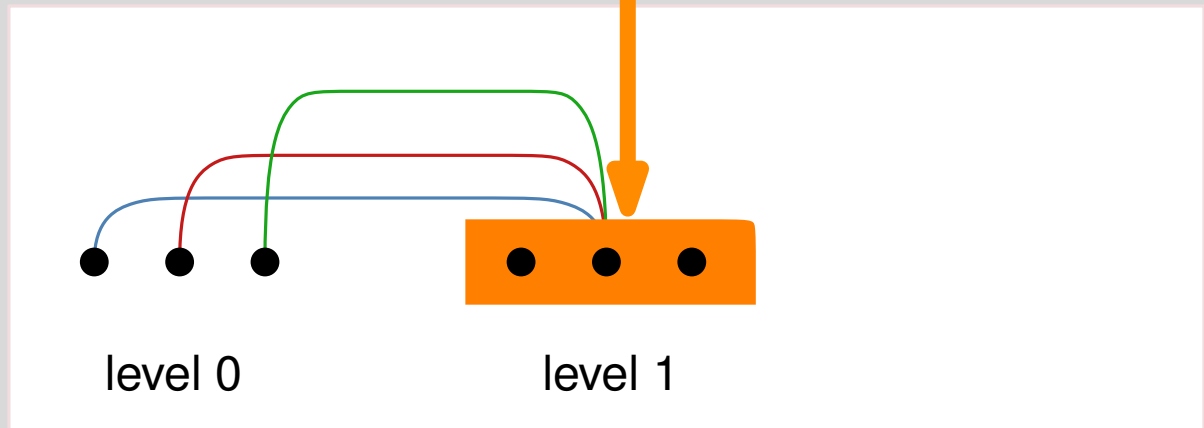
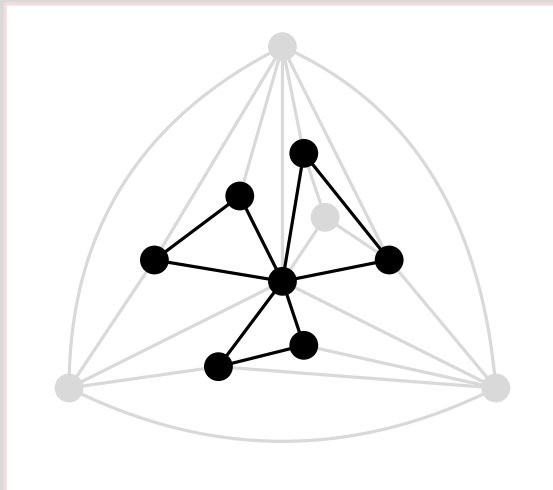
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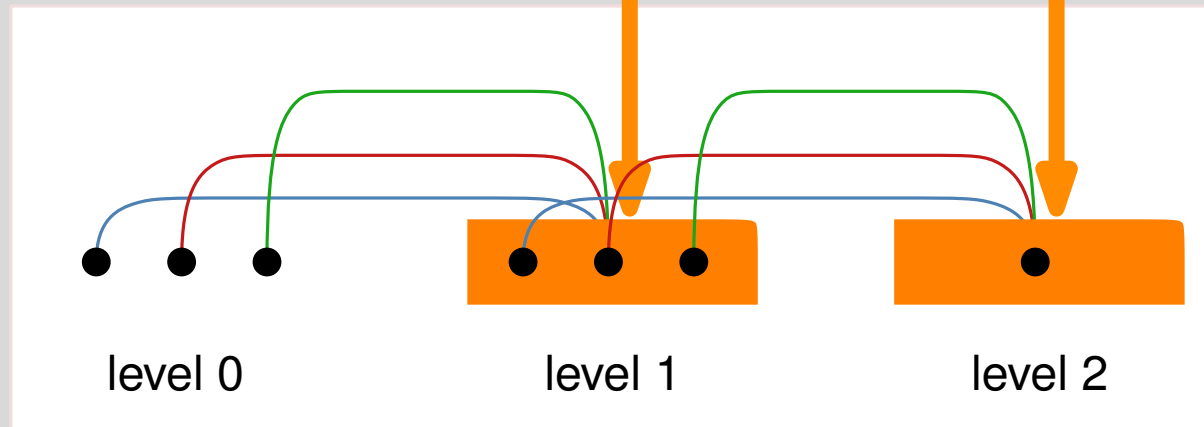
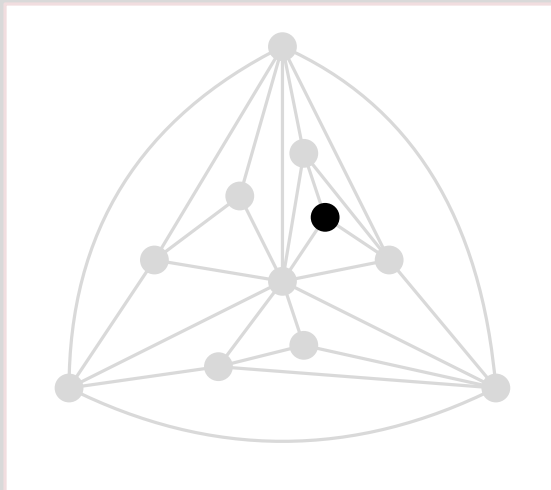
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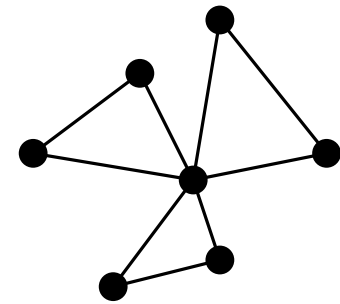
Outerplanar graph  $G$  has  $qn(G) = 2$

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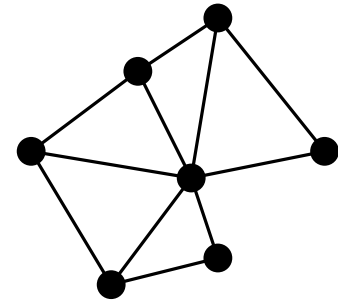
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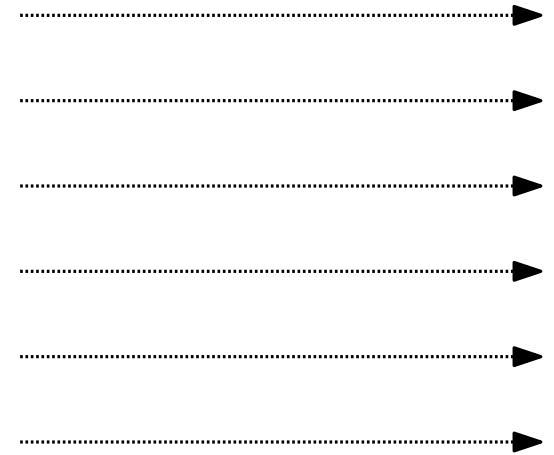
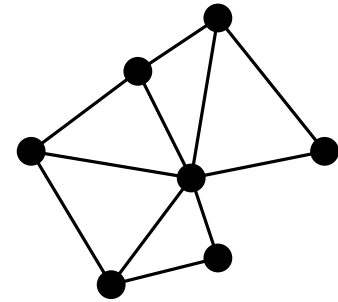
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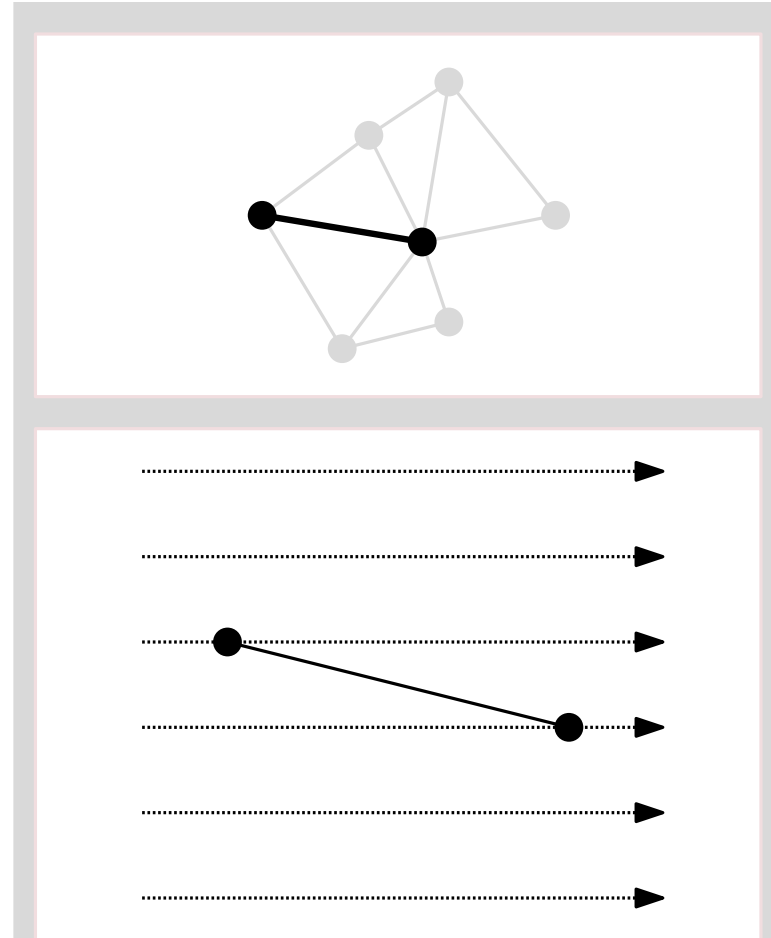
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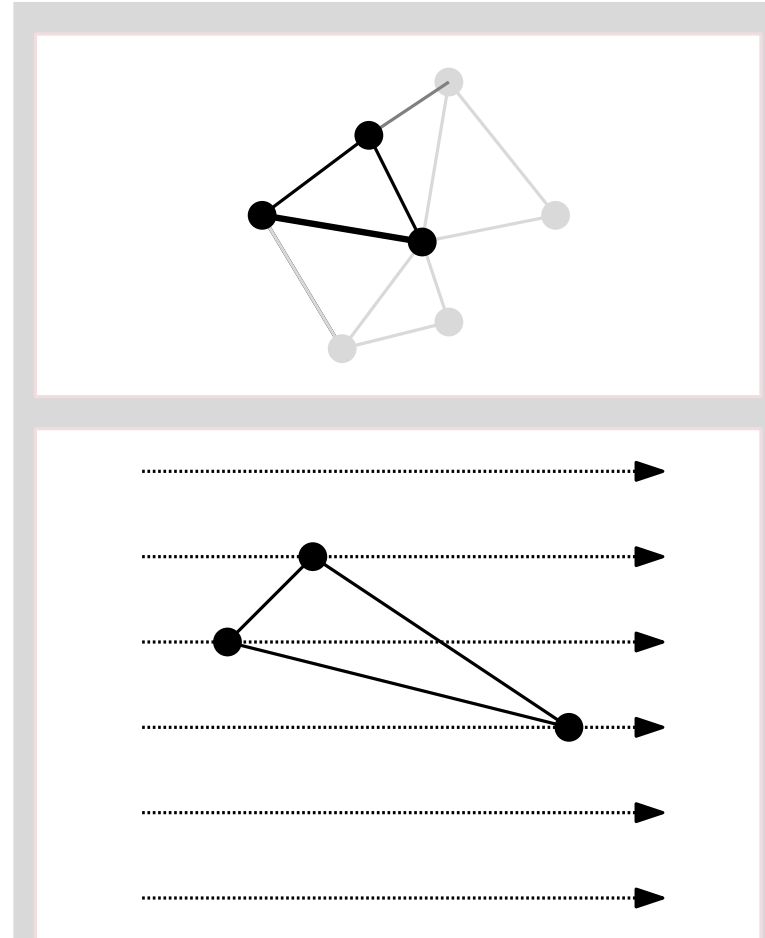


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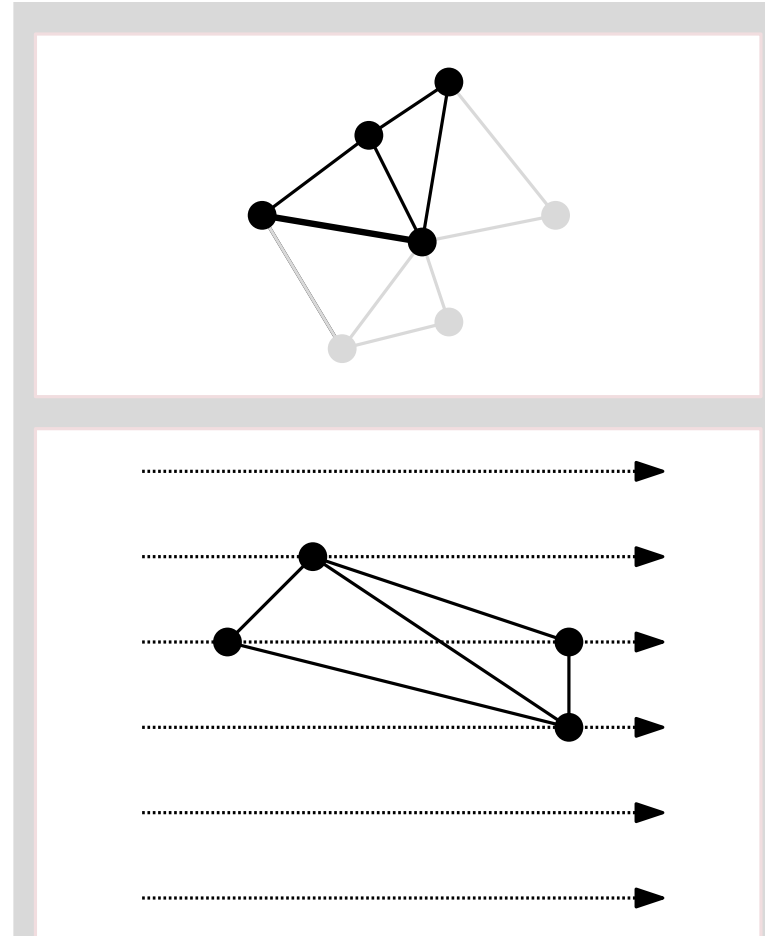
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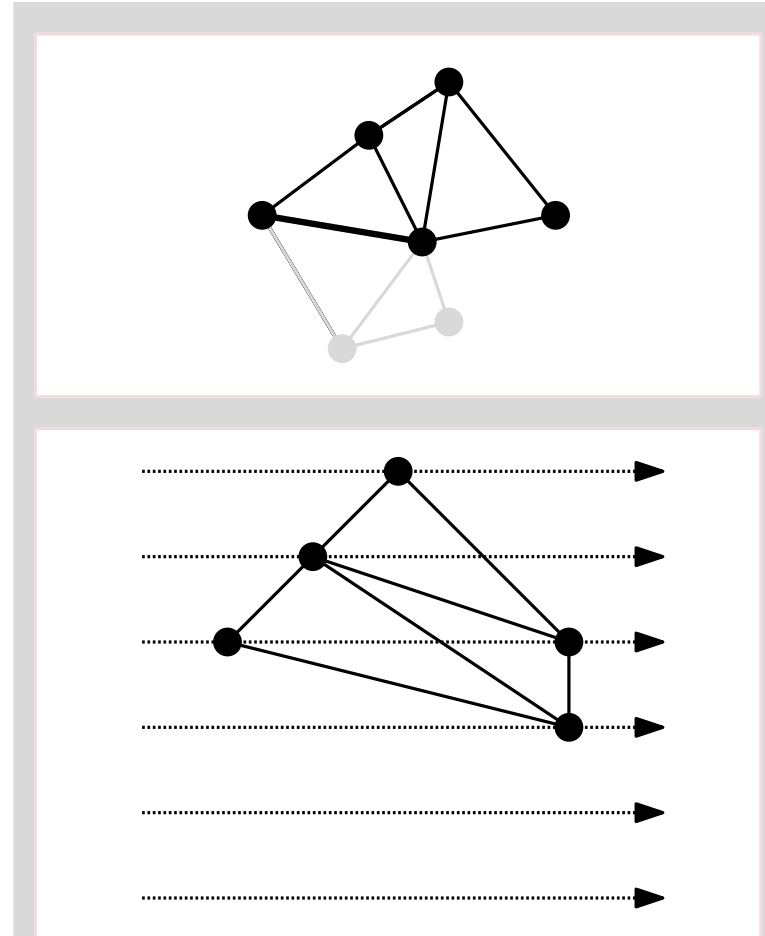
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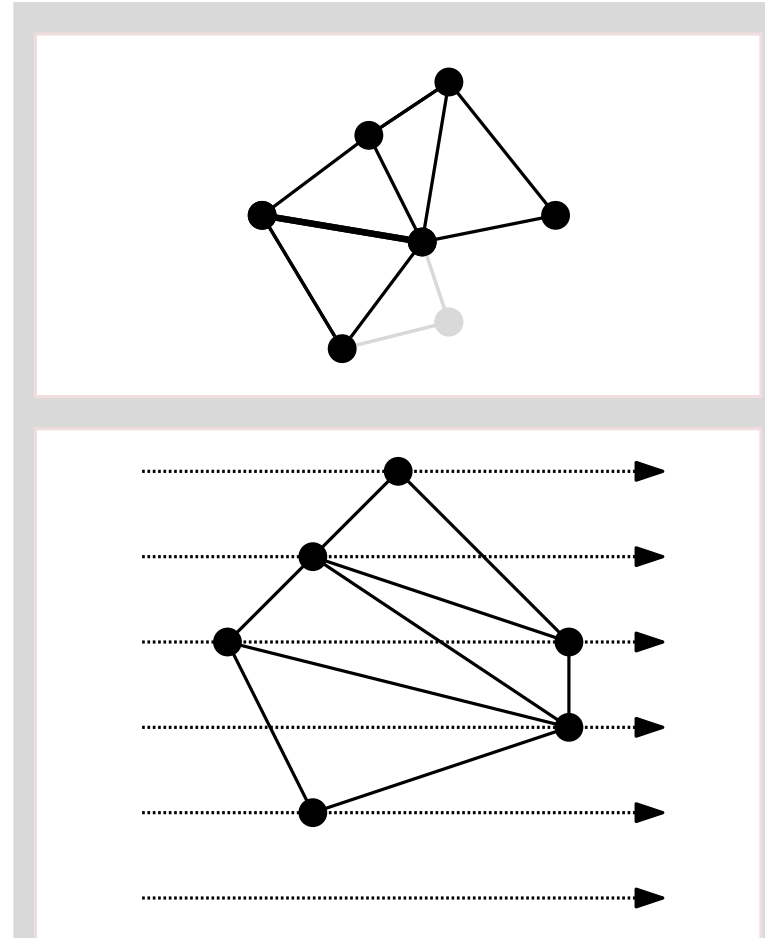
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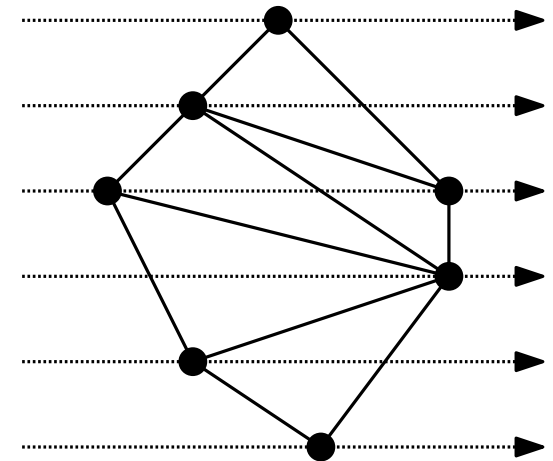
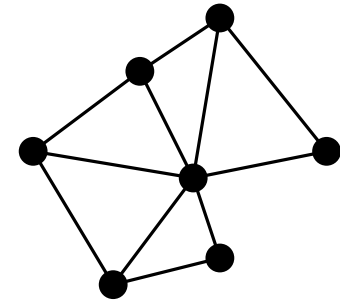
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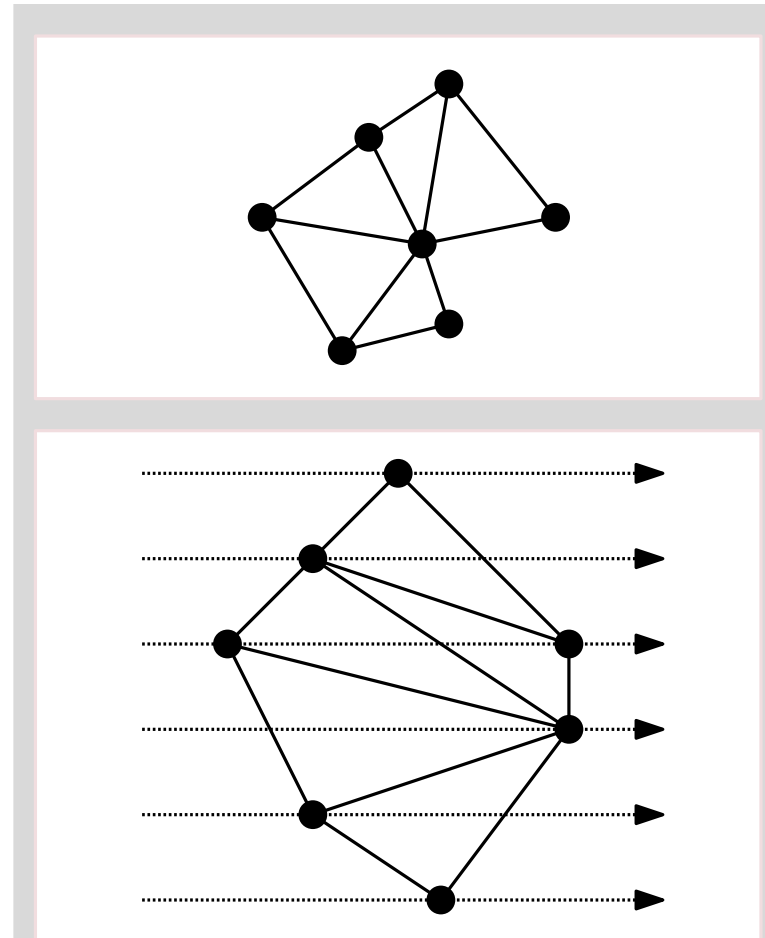
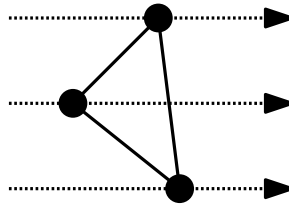
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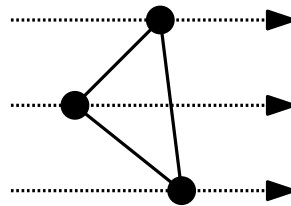
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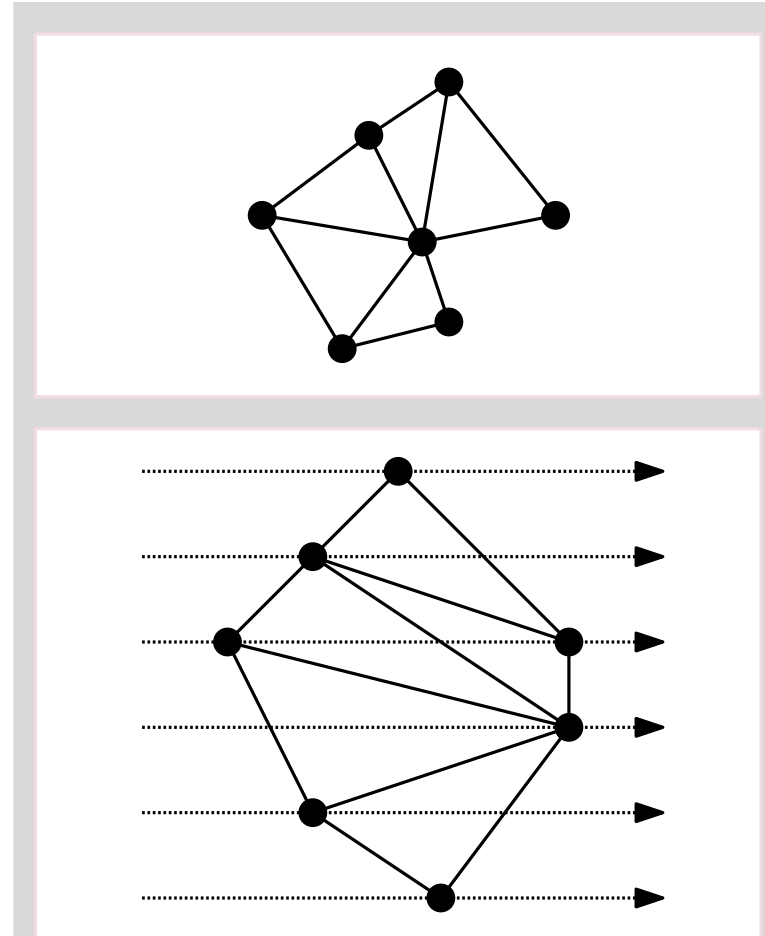
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## 2-queue layout

- span 1 edges on one queue
- span 2 edges on one queue



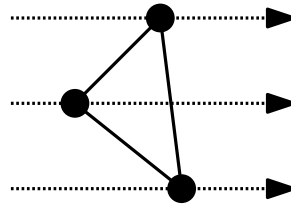
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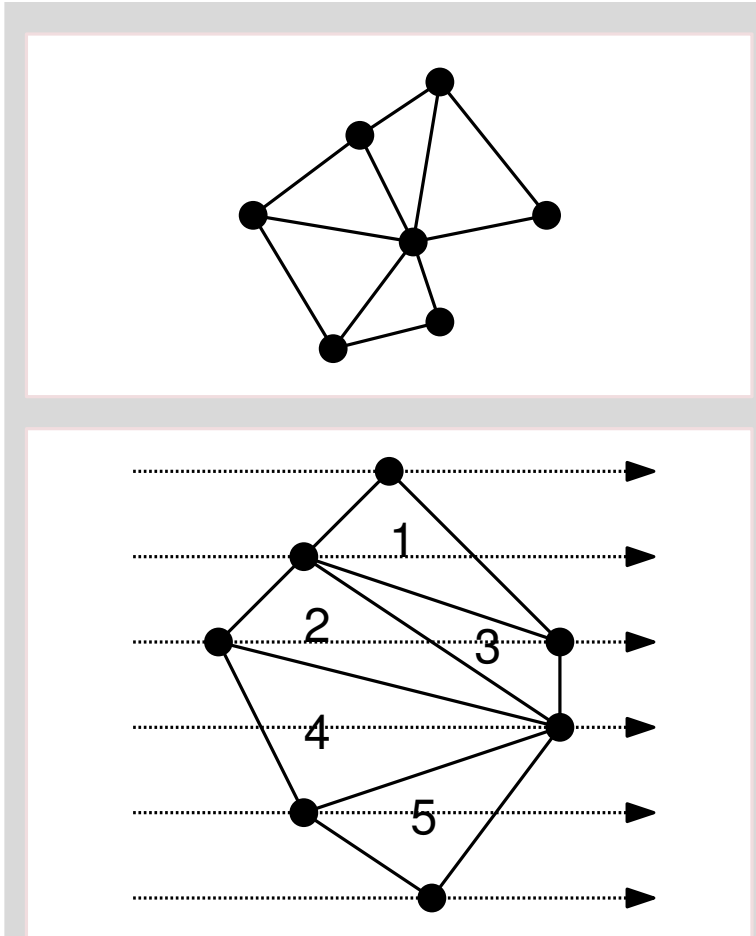
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## 2-queue layout

- span 1 edges on one queue
- span 2 edges on one queue
- faces are ordered



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# Overview

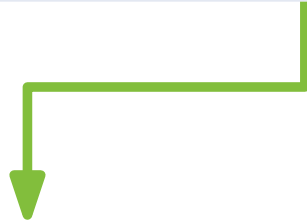
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three types of edges

level

forward

backward

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3-rainbow

an edge of  $H$   
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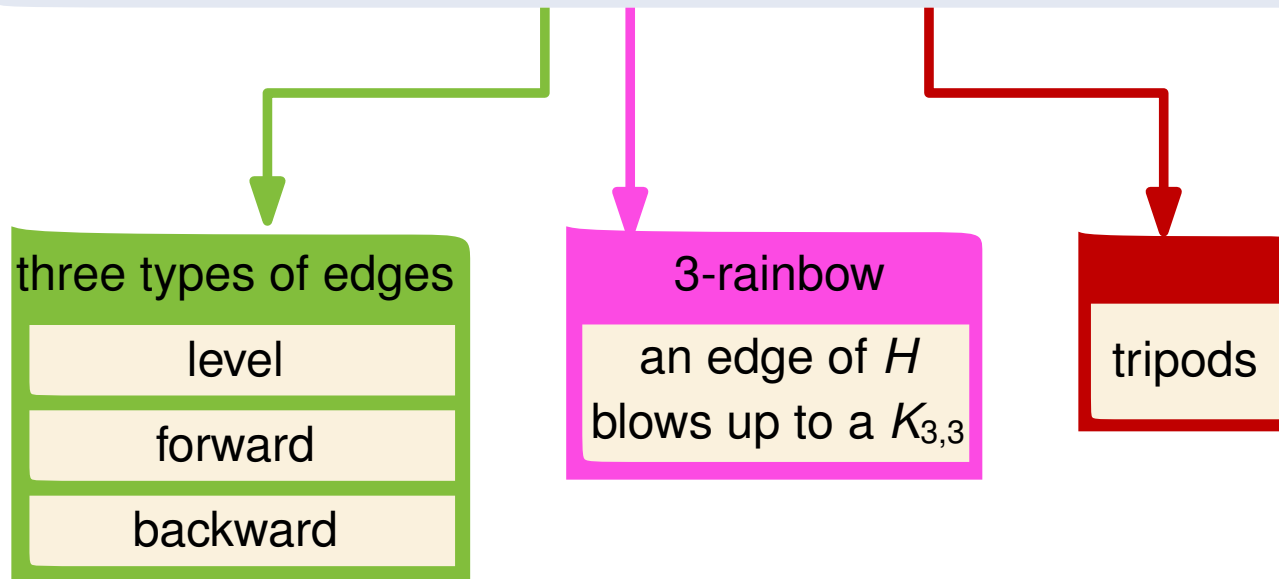
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tripods

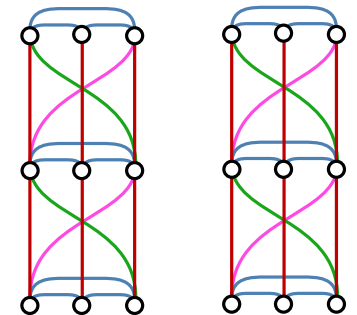
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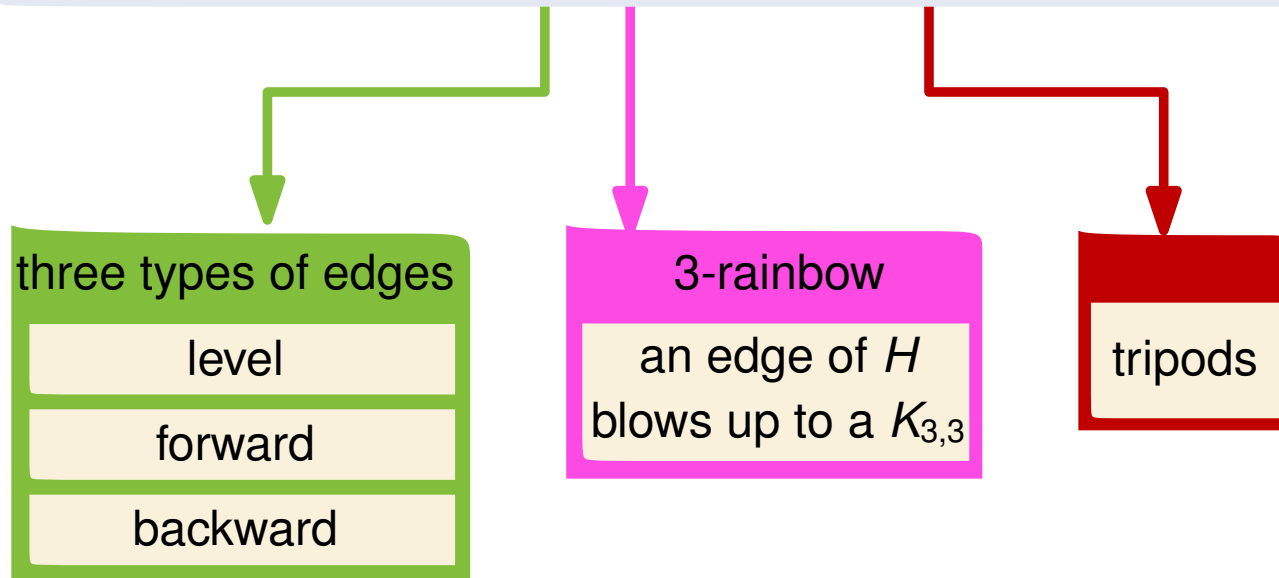
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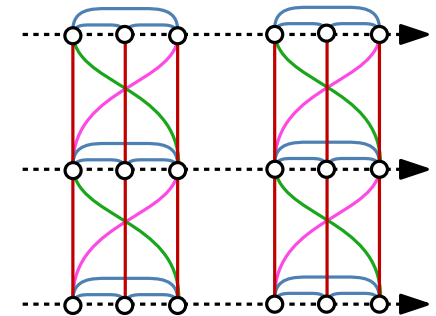
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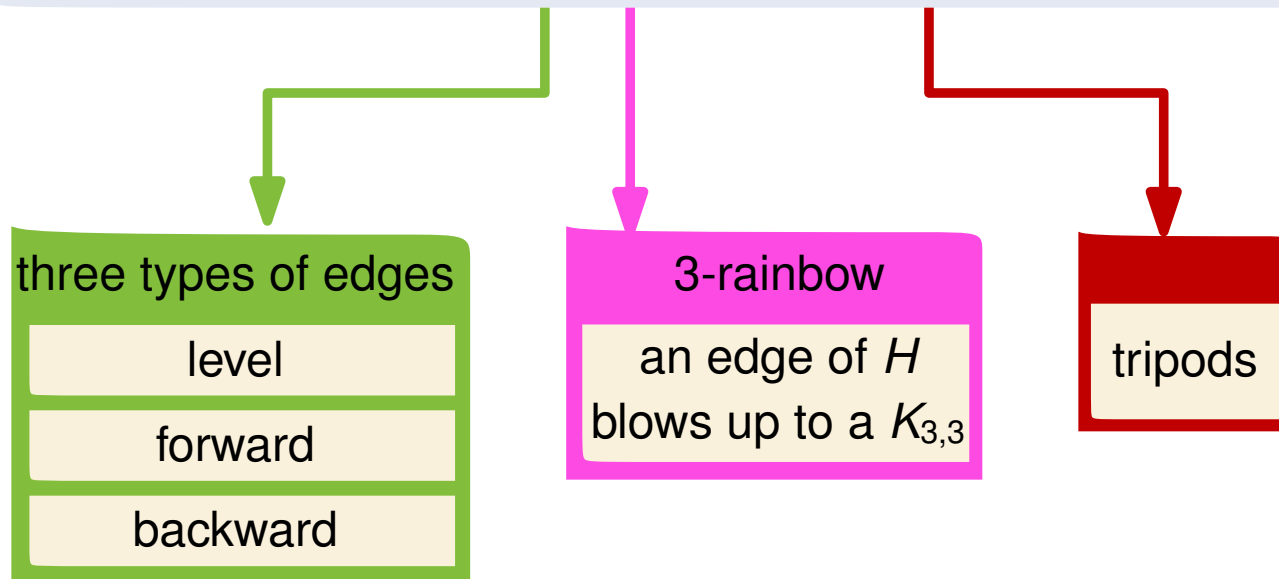
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- BFS-leveling of  $G$  is a partial order



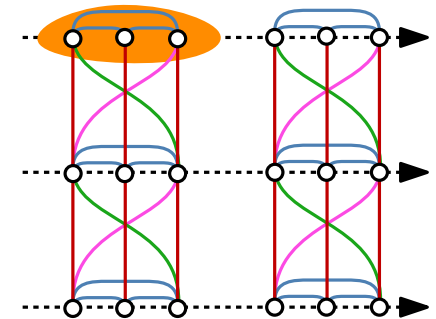
# Overview

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- 5-queue layout of  $H$  determines the order of the tripods
- BFS-leveling of  $G$  is a partial order
- each 3 vertices of the same tripod and on same BFS-level are unordered



# Improvement

## Main Idea:

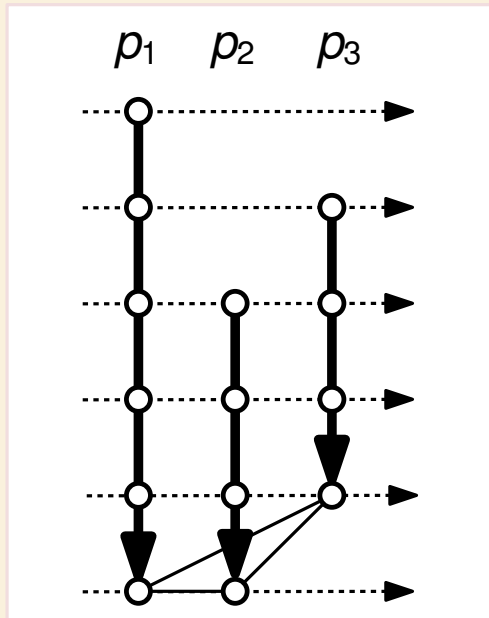
order the paths of each tripod



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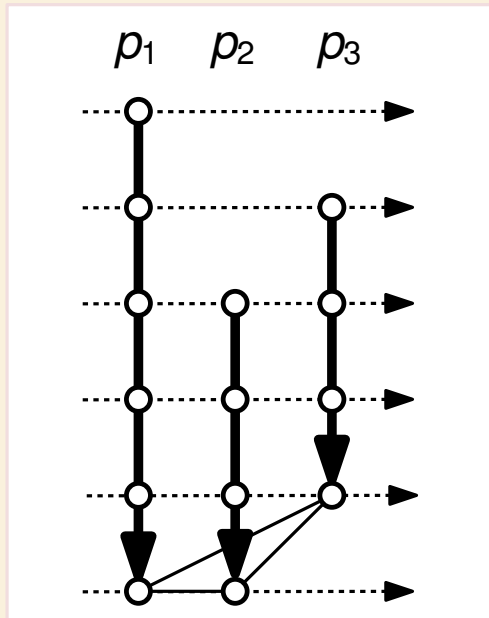
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# Improvement

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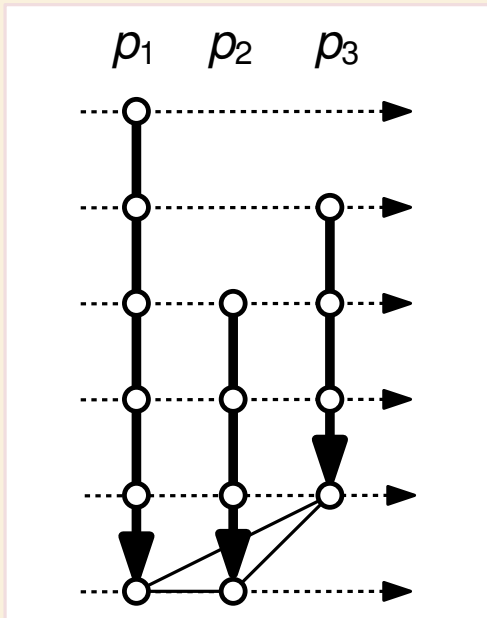


- level edges on one queue  
(level edges of  $P_k \boxtimes K_3$ )

# Improvement

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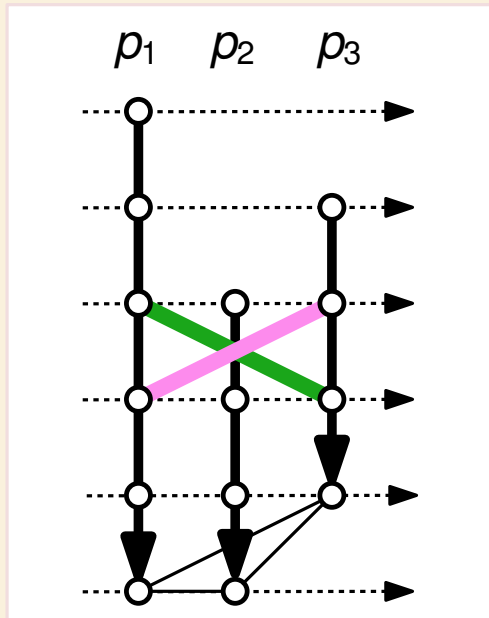
## Claim

- binding (and vertex) edges create no 3-rainbow

# Improvement

## Main Idea:

order the paths of each tripod



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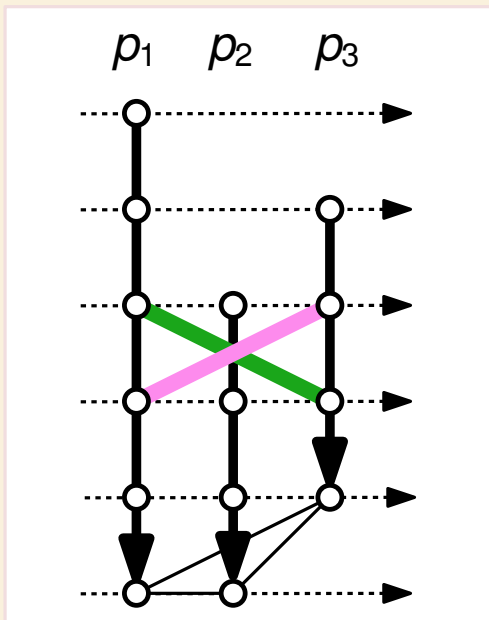
## Claim

- binding (and vertex) edges create no 3-rainbow

# Improvement

## Main Idea:

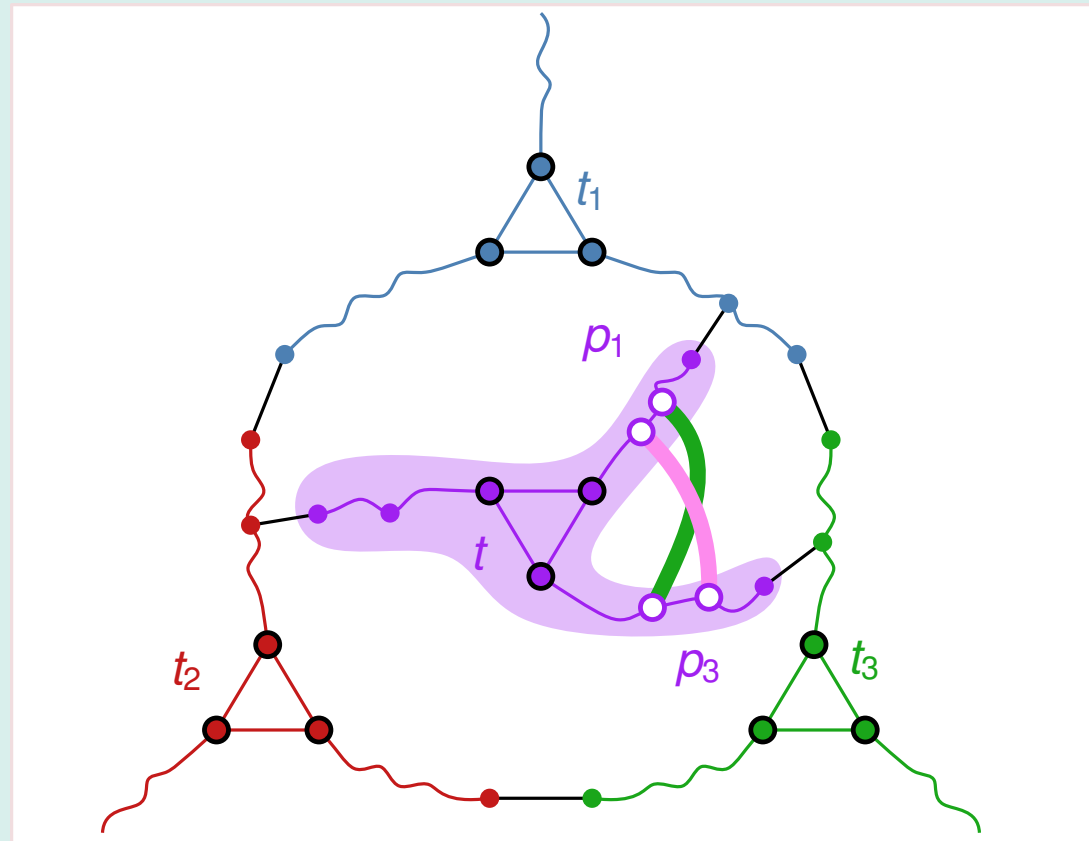
order the paths of each tripod



- level edges on one queue  
(level edges of  $P_k \boxtimes K_3$ )

## Claim

- binding (and vertex) edges create no 3-rainbow

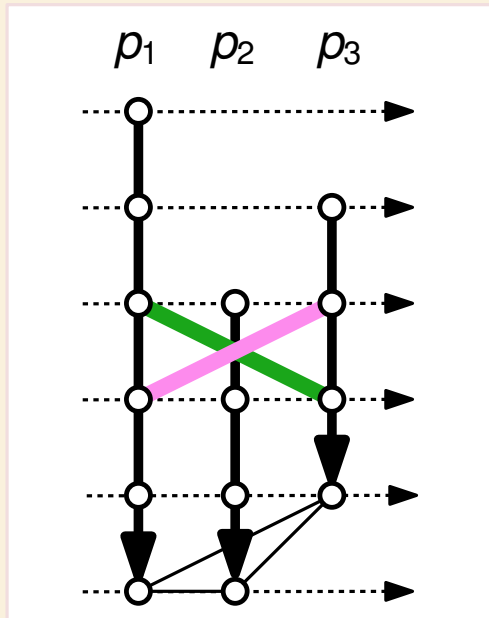


otherwise planarity is violated

# Improvement

## Main Idea:

order the paths of each tripod

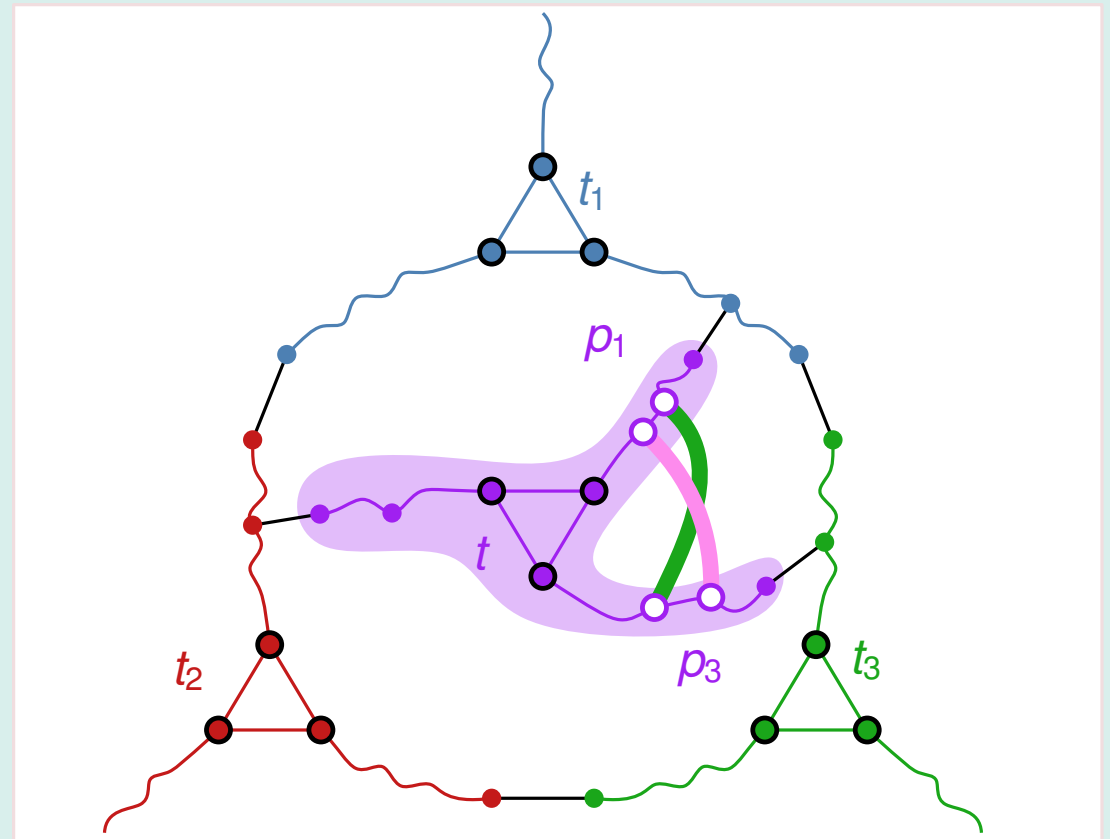


- level edges on one queue  
(level edges of  $P_k \boxtimes K_3$ )

Tripods need 3 queues  
upper bound reduced to 48

## Claim

- binding (and vertex) edges create no 3-rainbow



otherwise planarity is violated

# Improvement

Goal:

order the paths of each tripod to avoid 3-rainbows

# Improvement

Goal:

order the paths of each tripod to avoid 3-rainbows

- focus on level edges on single level



# Improvement

## Goal:

order the paths of each tripod to avoid 3-rainbows

- focus on level edges on single level
- a 3-rainbow contains 3 vertices of the same tripod

# Improvement

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order the paths of each tripod to avoid 3-rainbows

- focus on level edges on single level
- a 3-rainbow contains 3 vertices of the same tripod

## Types of 3-rainbows

# Improvement

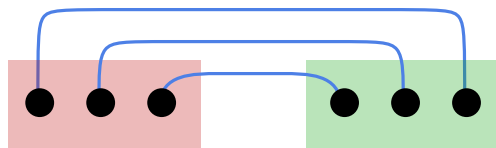
## Goal:

order the paths of each tripod to avoid 3-rainbows

- focus on level edges on single level
- a 3-rainbow contains 3 vertices of the same tripod

## Types of 3-rainbows

one tripod



# Improvement

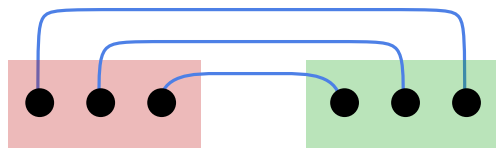
## Goal:

order the paths of each tripod to avoid 3-rainbows

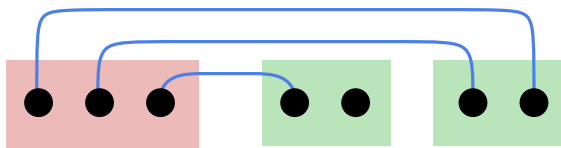
- focus on level edges on single level
- a 3-rainbow contains 3 vertices of the same tripod

## Types of 3-rainbows

one tripod



two tripods



# Improvement

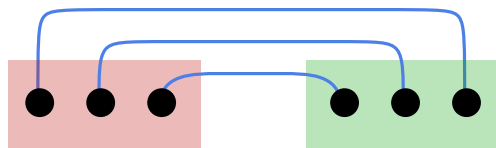
## Goal:

order the paths of each tripod to avoid 3-rainbows

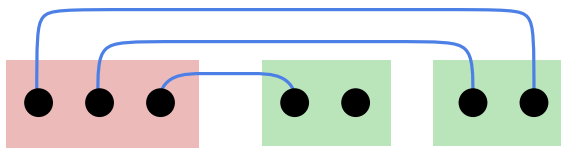
- focus on level edges on single level
- a 3-rainbow contains 3 vertices of the same tripod

## Types of 3-rainbows

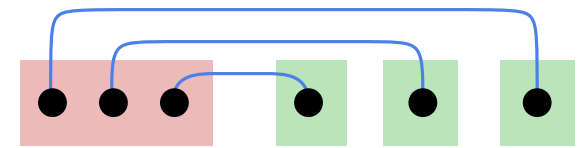
one tripod



two tripods



three tripod



# Improvement

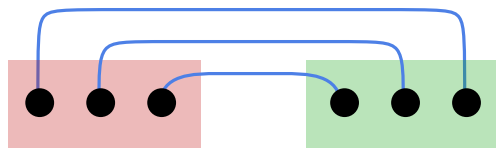
## Goal:

order the paths of each tripod to avoid 3-rainbows

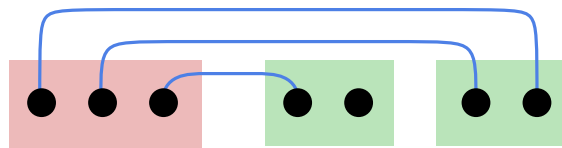
- focus on level edges on single level
- a 3-rainbow contains 3 vertices of the same tripod

## Types of 3-rainbows

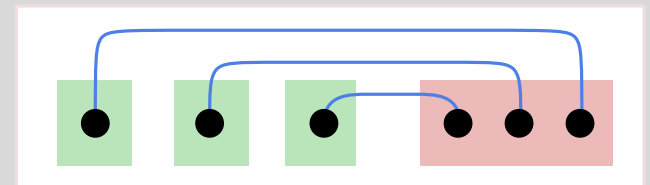
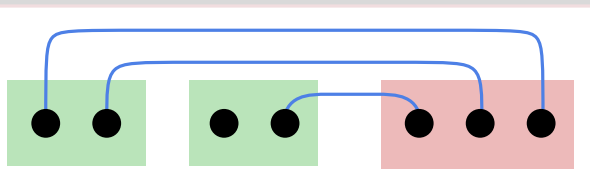
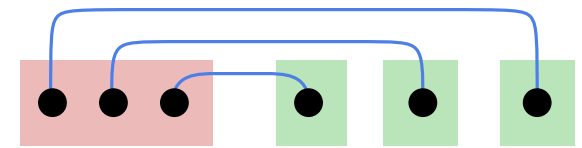
one tripod



two tripods

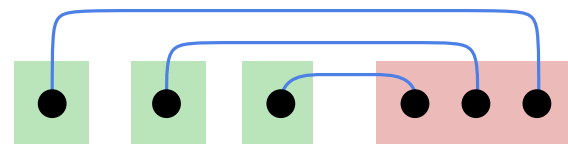
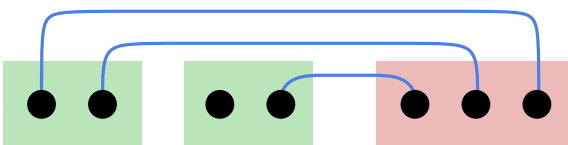
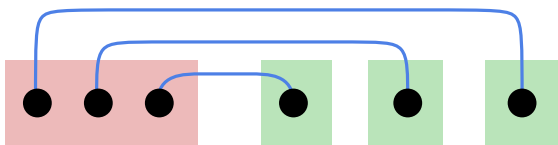
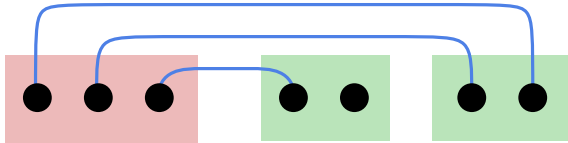
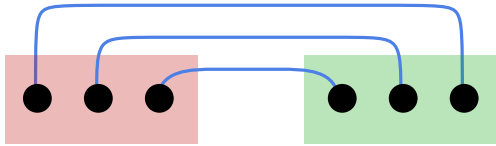


three tripod



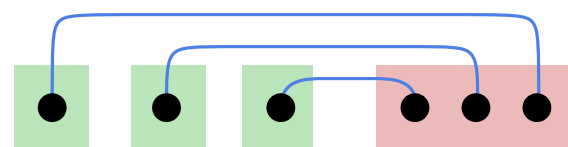
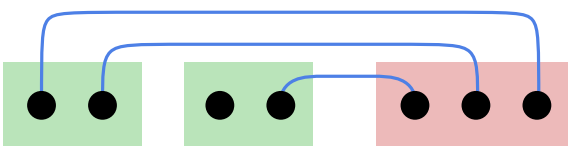
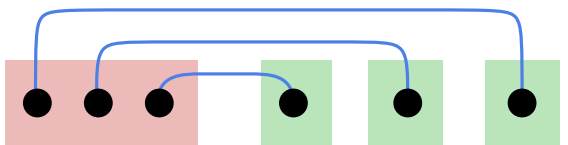
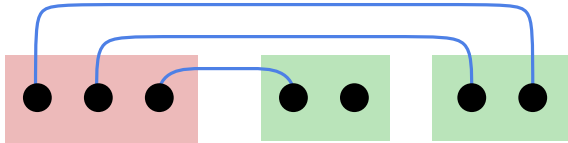
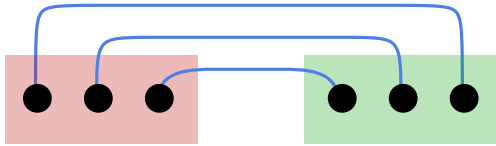
# Improvement

## Types of 3-rainbows



# Improvement

## Types of 3-rainbows

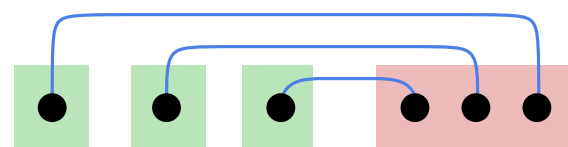
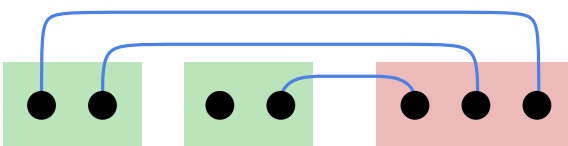
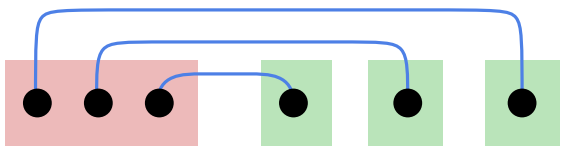
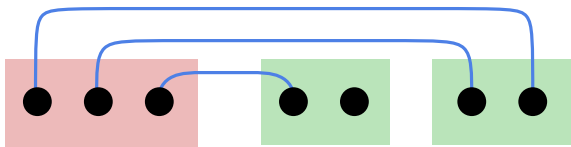
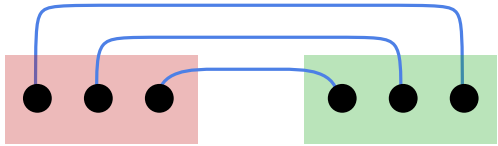


- for two adjacent tripods one is parent of the other

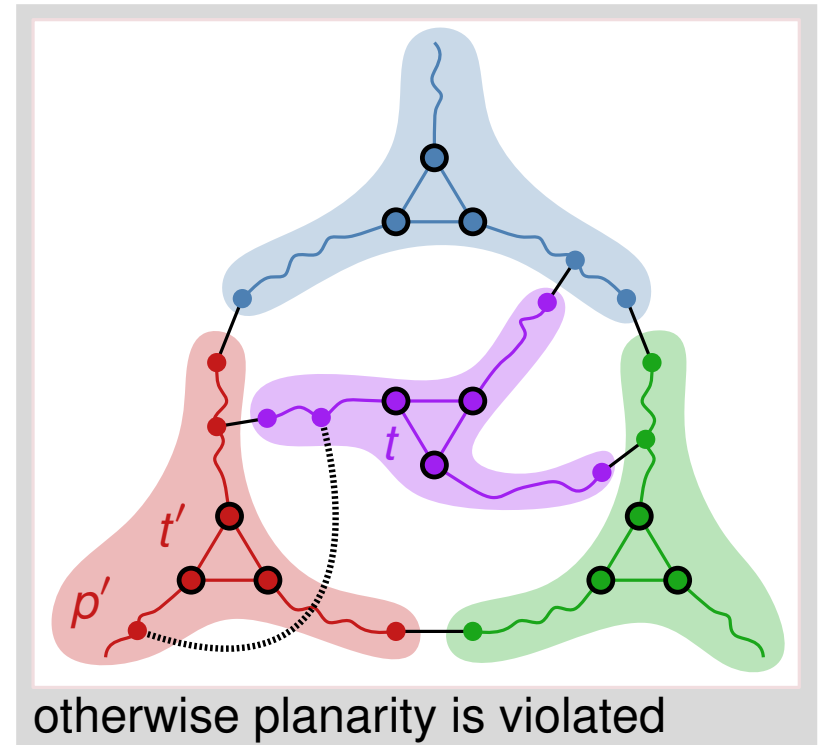


# Improvement

## Types of 3-rainbows

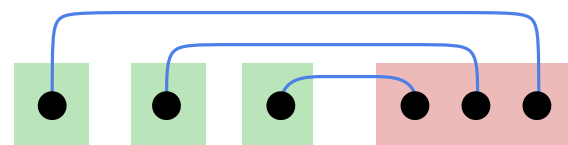
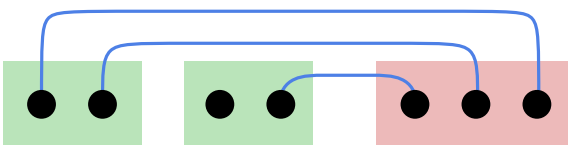
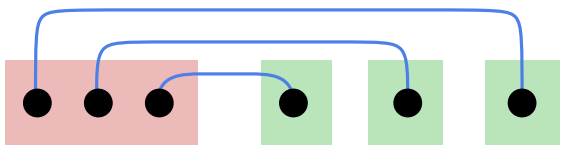
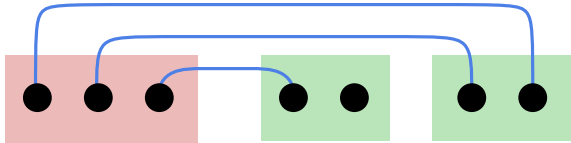
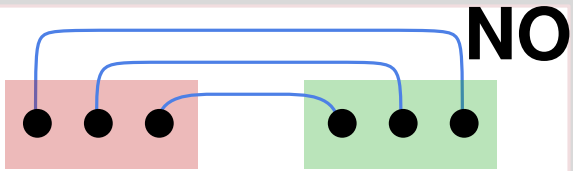


- for two adjacent tripods one is parent of the other
- if  $t'$  parent of  $t$ ,  $t$  is not adjacent to a path  $p'$  of  $t'$



# Improvement

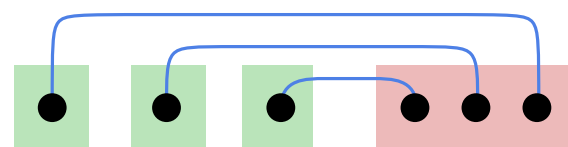
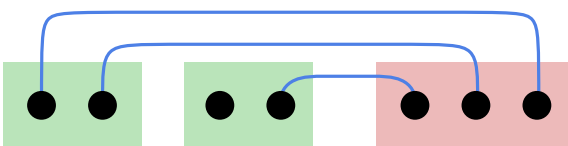
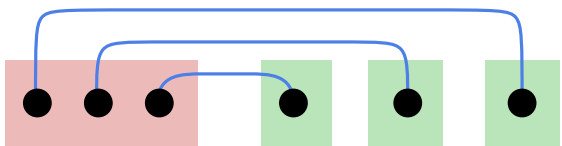
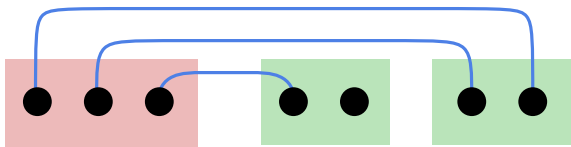
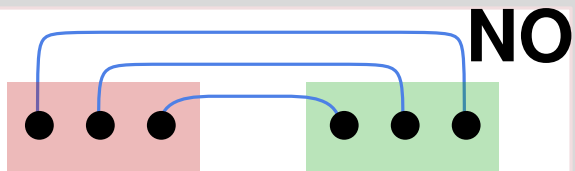
## Types of 3-rainbows



- for two adjacent tripods one is parent of the other
- if  $t'$  parent of  $t$ ,  $t$  is not adjacent to a path  $p'$  of  $t'$

# Improvement

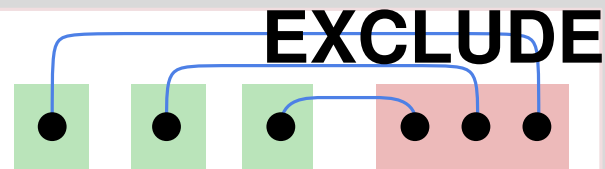
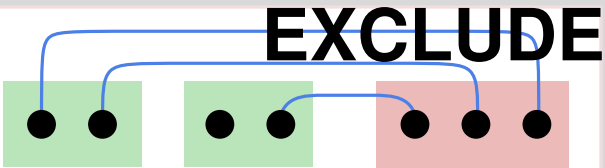
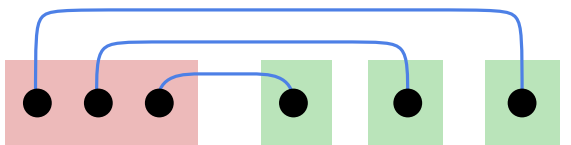
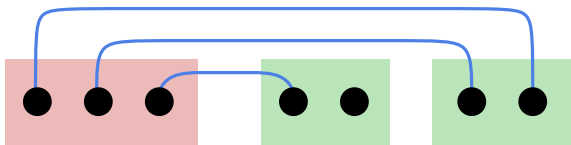
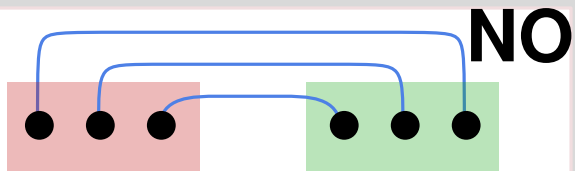
## Types of 3-rainbows



- for two adjacent tripods one is parent of the other
- if  $t'$  parent of  $t$ ,  $t$  is not adjacent to a path  $p'$  of  $t'$
- left and right might conflict

# Improvement

## Types of 3-rainbows

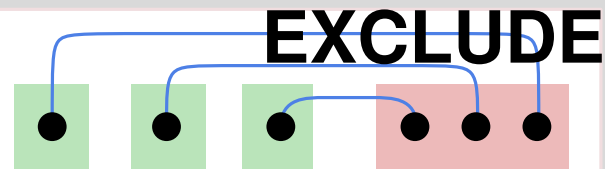
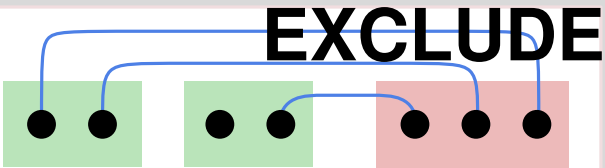
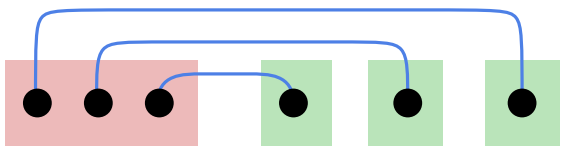
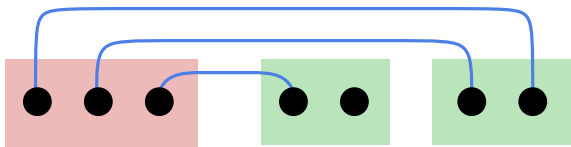
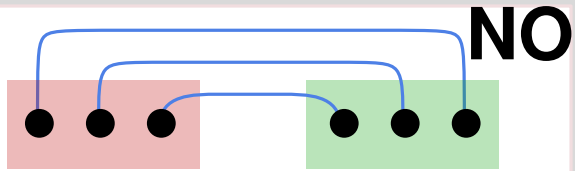


- for two adjacent tripods one is parent of the other
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- left and right might conflict

→ consider only following tripods

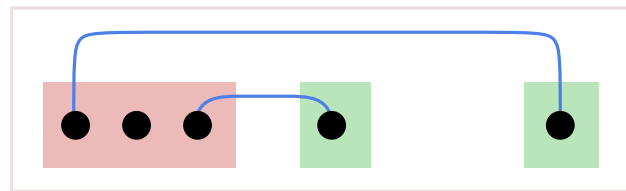
# Improvement

## Types of 3-rainbows



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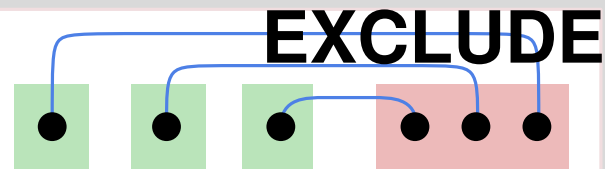
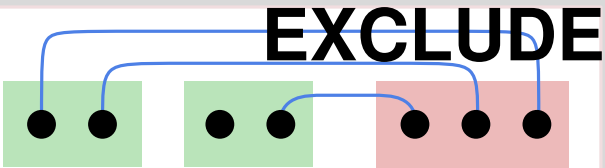
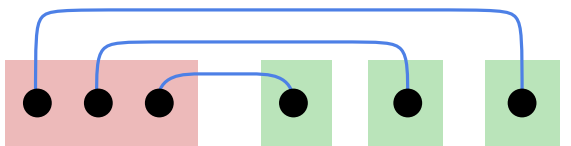
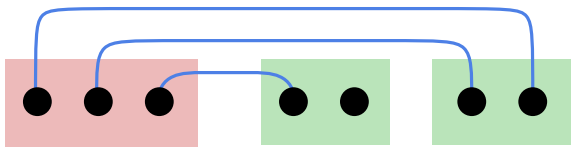
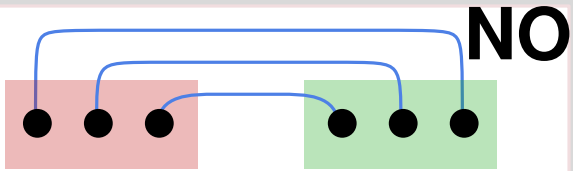
→ consider only following tripods



- avoid one of the two edges

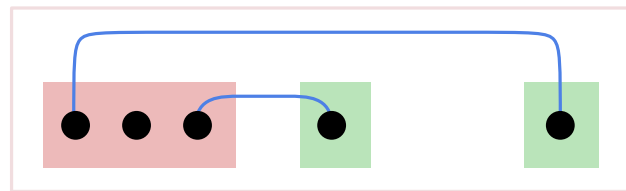
# Improvement

## Types of 3-rainbows



- for two adjacent tripods one is parent of the other
- if  $t'$  parent of  $t$ ,  $t$  is not adjacent to a path  $p'$  of  $t'$
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→ consider only following tripods

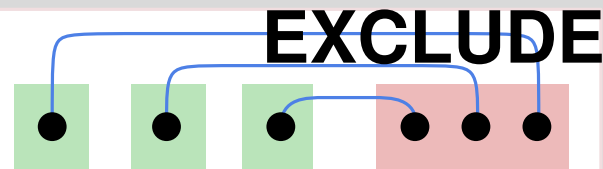
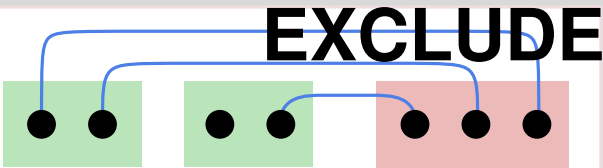
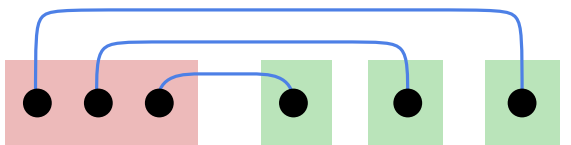
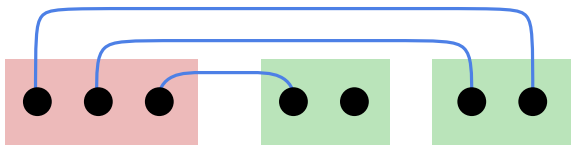
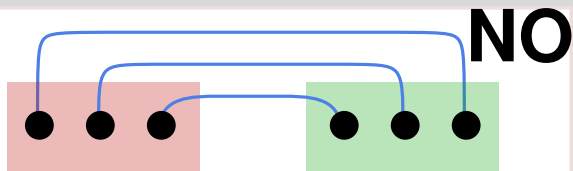


- avoid one of the two edges

→ consider only children

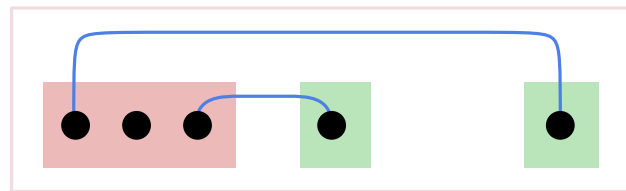
# Improvement

## Types of 3-rainbows



- for two adjacent tripods one is parent of the other
- if  $t'$  parent of  $t$ ,  $t$  is not adjacent to a path  $p'$  of  $t'$
- left and right might conflict

→ consider only following tripods



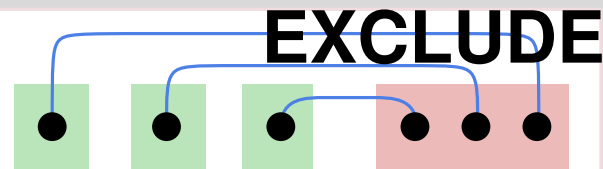
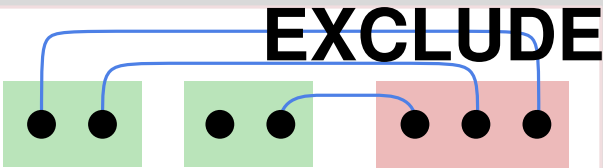
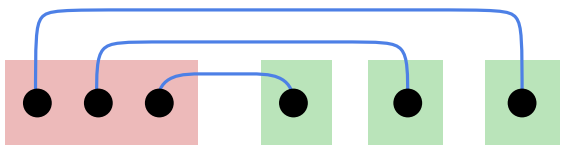
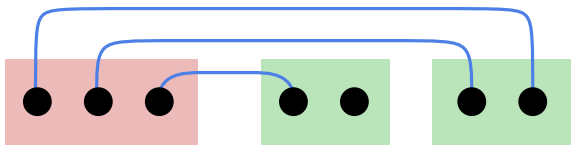
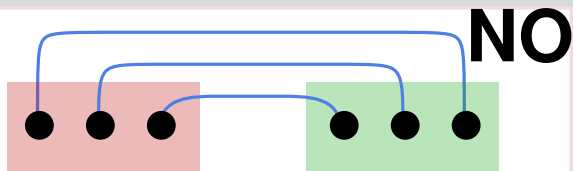
- avoid one of the two edges

→ consider only children

- children are grouped based on which paths they don't see
- following tripods form a series of groups

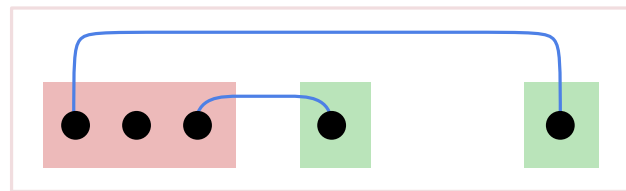
# Improvement

## Types of 3-rainbows



- for two adjacent tripods one is parent of the other
- if  $t'$  parent of  $t$ ,  $t$  is not adjacent to a path  $p'$  of  $t'$
- left and right might conflict

→ consider only following tripods



- avoid one of the two edges

→ consider only children

- children are grouped based on which paths they don't see
- following tripods form a series of groups

→ require two groups



# Restrictions

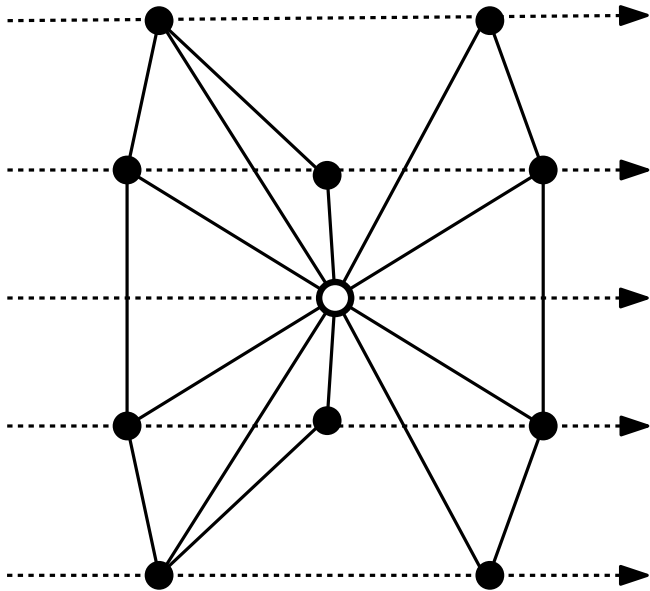
## Restrictions

1. Consider only following tripods
2. Split considered nodes into two groups
3. Consider only children

# Restrictions

## Restrictions

1. Consider only following tripods
2. Split considered nodes into two groups
3. Consider only children

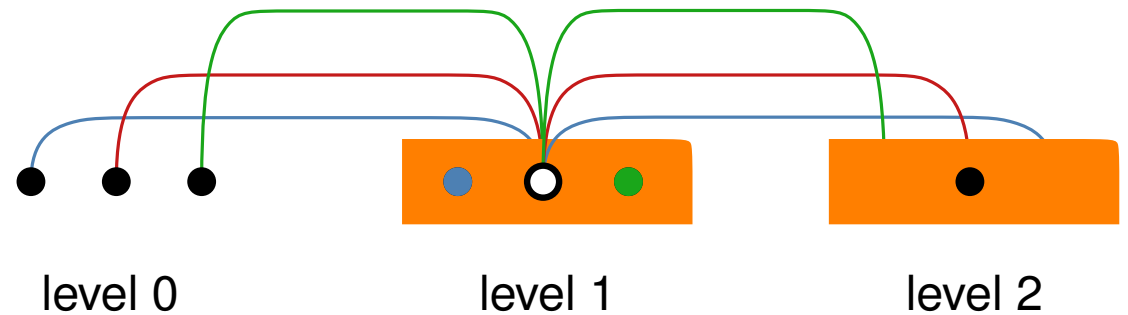
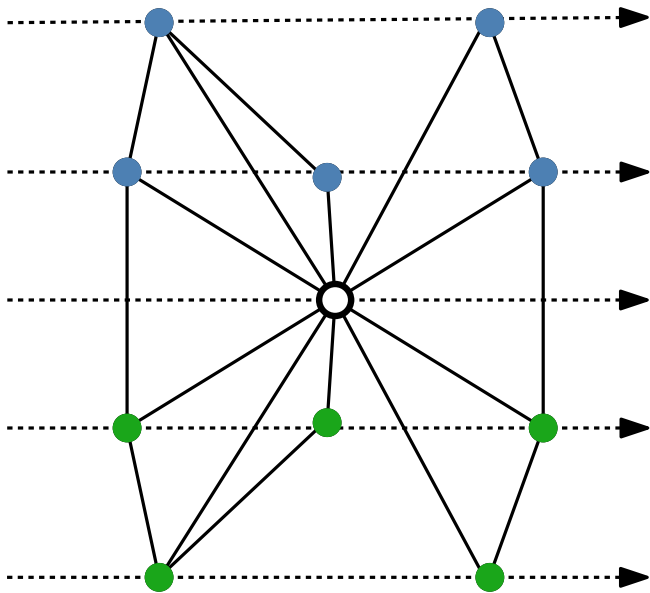


# Restrictions

## Restrictions

1. Consider only following tripods
2. Split considered nodes into two groups
3. Consider only children

- blue vertices precede and green follow
- exclude queues of the outerplanar subgraph
- other queues satisfy 1.

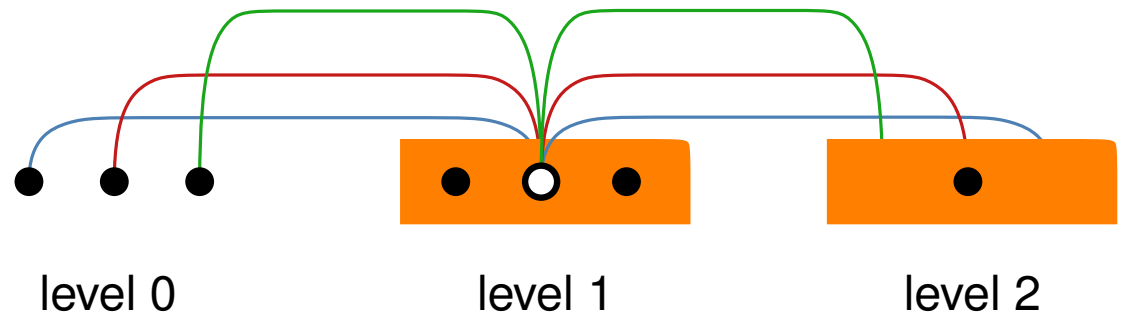
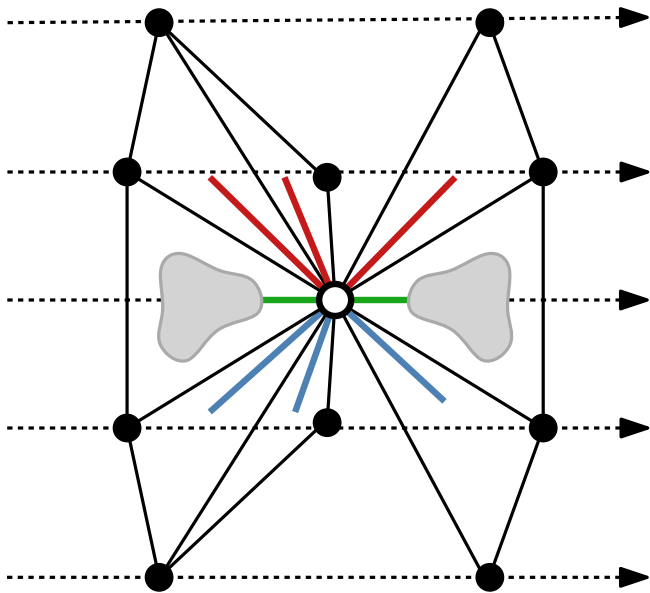


# Restrictions

## Restrictions

1. Consider only following tripods
2. Split considered nodes into two groups
3. Consider only children

- blue vertices precede and green follow
- exclude queues of the outerplanar subgraph
- other queues satisfy 1.
- green neighbors form two clusters

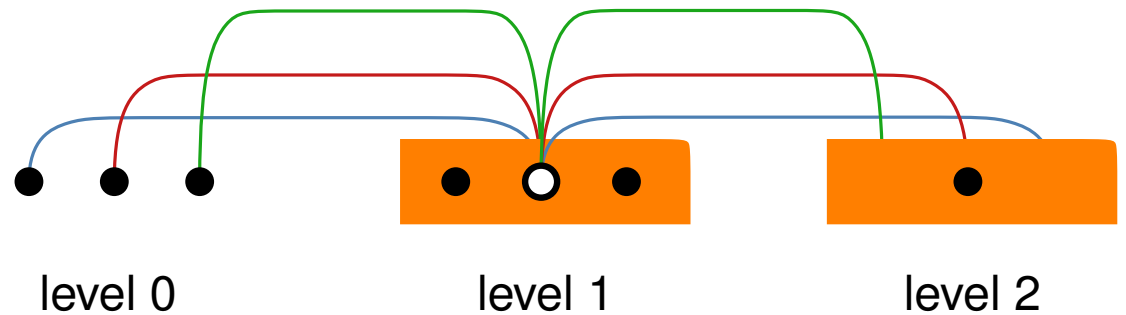
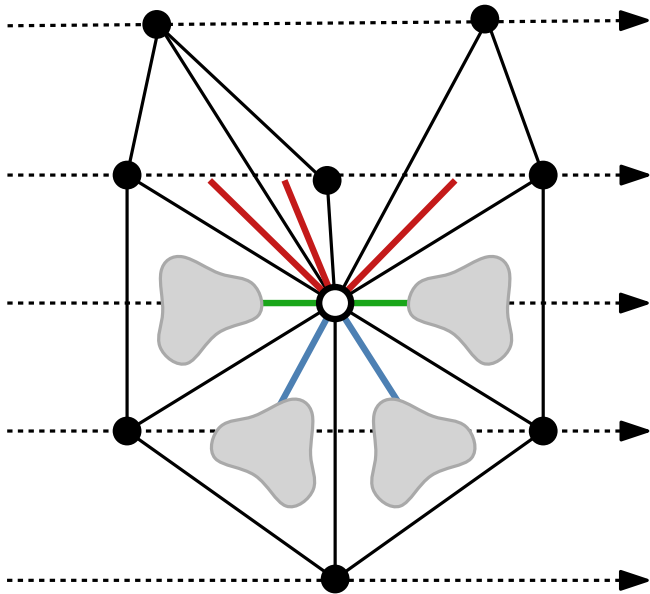


# Restrictions

## Restrictions

1. Consider only following tripods
2. Split considered nodes into two groups
3. Consider only children

- blue vertices precede and green follow
- exclude queues of the outerplanar subgraph
- other queues satisfy 1.
- green neighbors form two clusters
- do the same for the blue

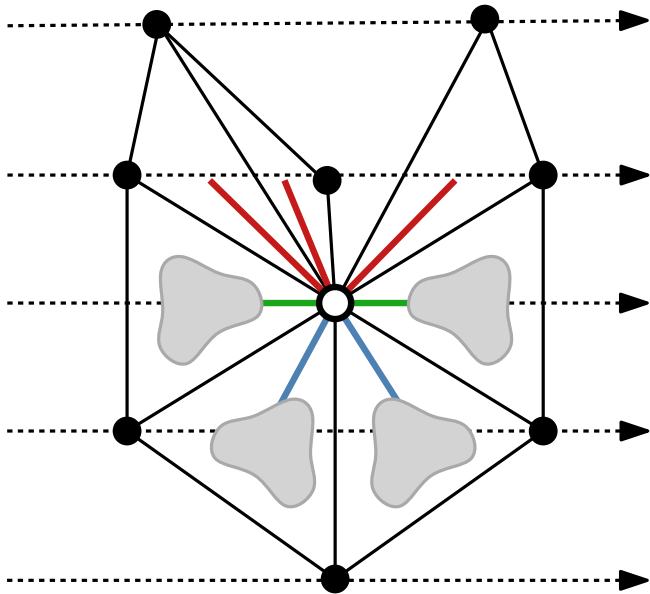


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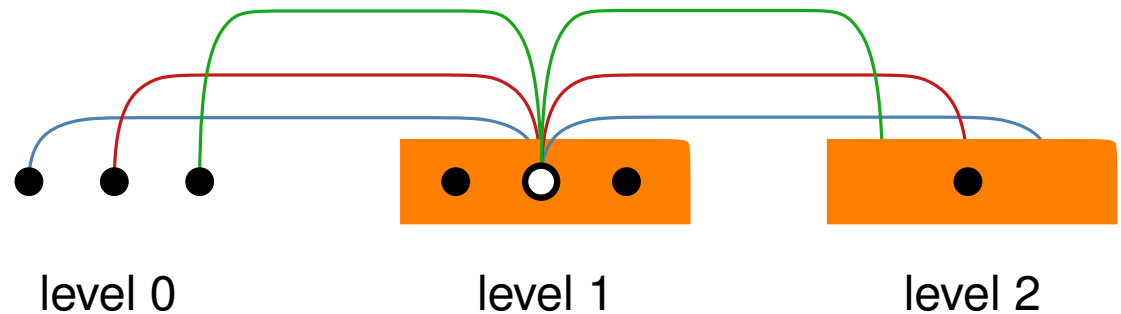
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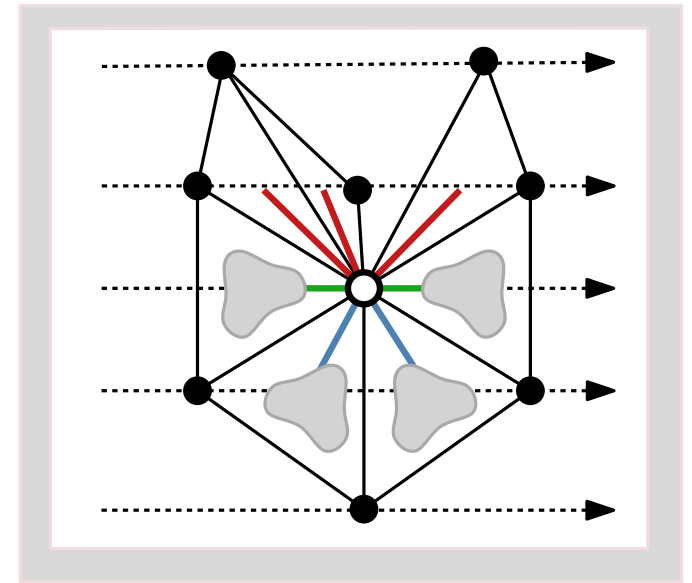
we can improve on two queues of the 5-queue layout of  $H$



# Restrictions

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1. Consider only following tripods
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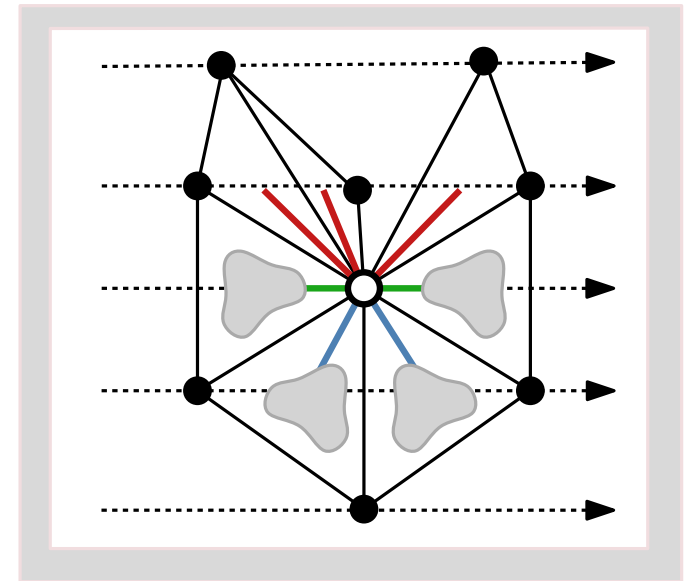


# Restrictions

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- green and blue clusters to be children
- each cluster to form a group,  
i.e. to not see a path of the tripod



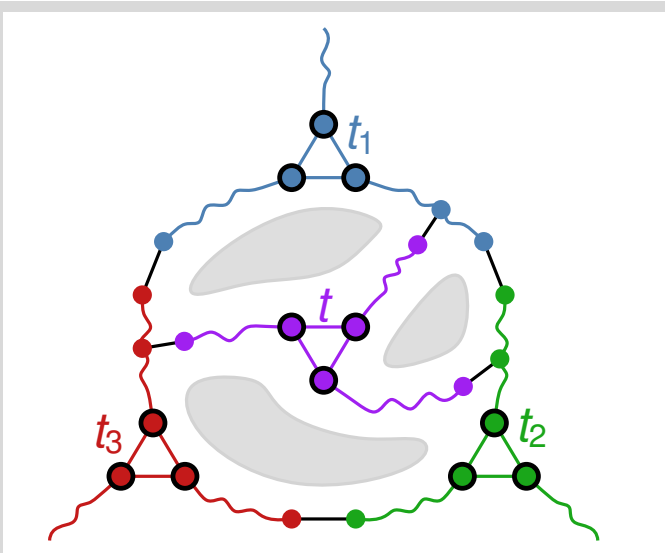
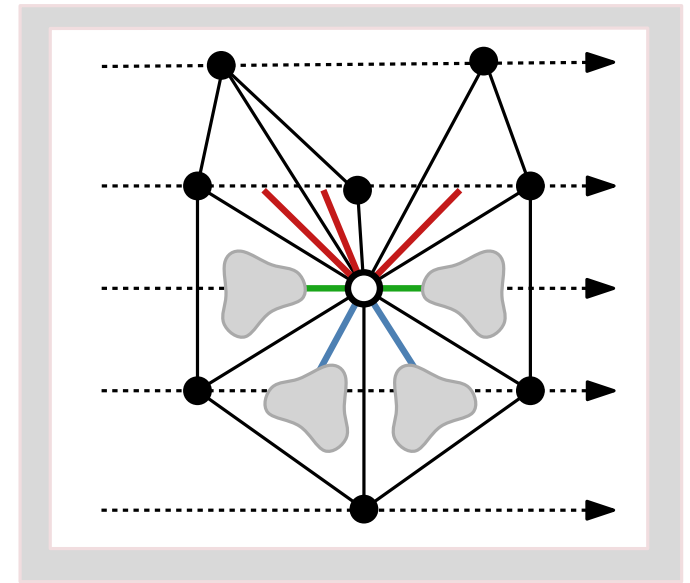


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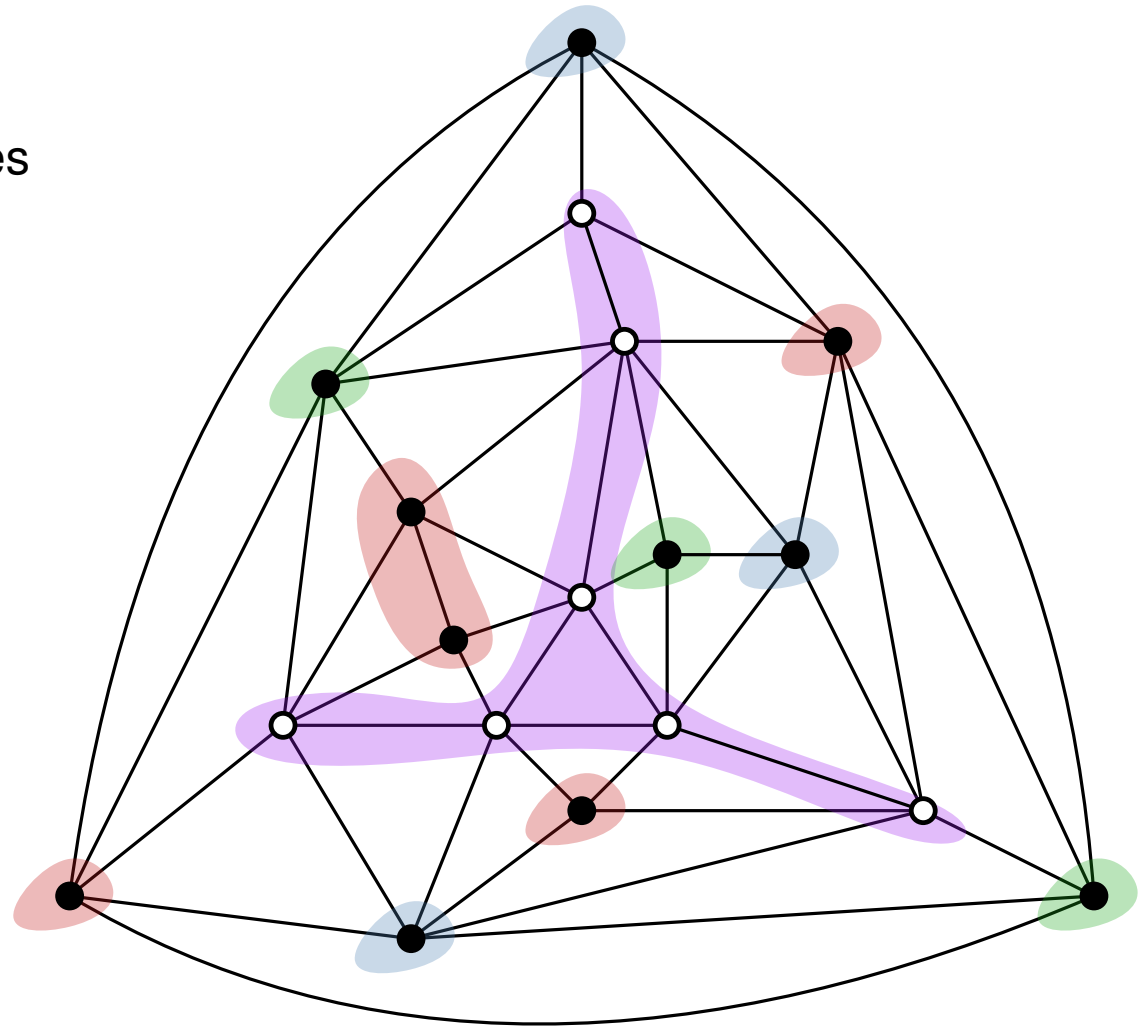
- each cluster to be in a shaded region
- graph  $H$  must reflect planarity of  $G$
- graph  $H$  must respect parent-child relation
- the level of parent can't be greater than the child's

# Improvement

- Contract tripods in  $G$ 
  - preserve embedding
  - remove homotopic parallel edges

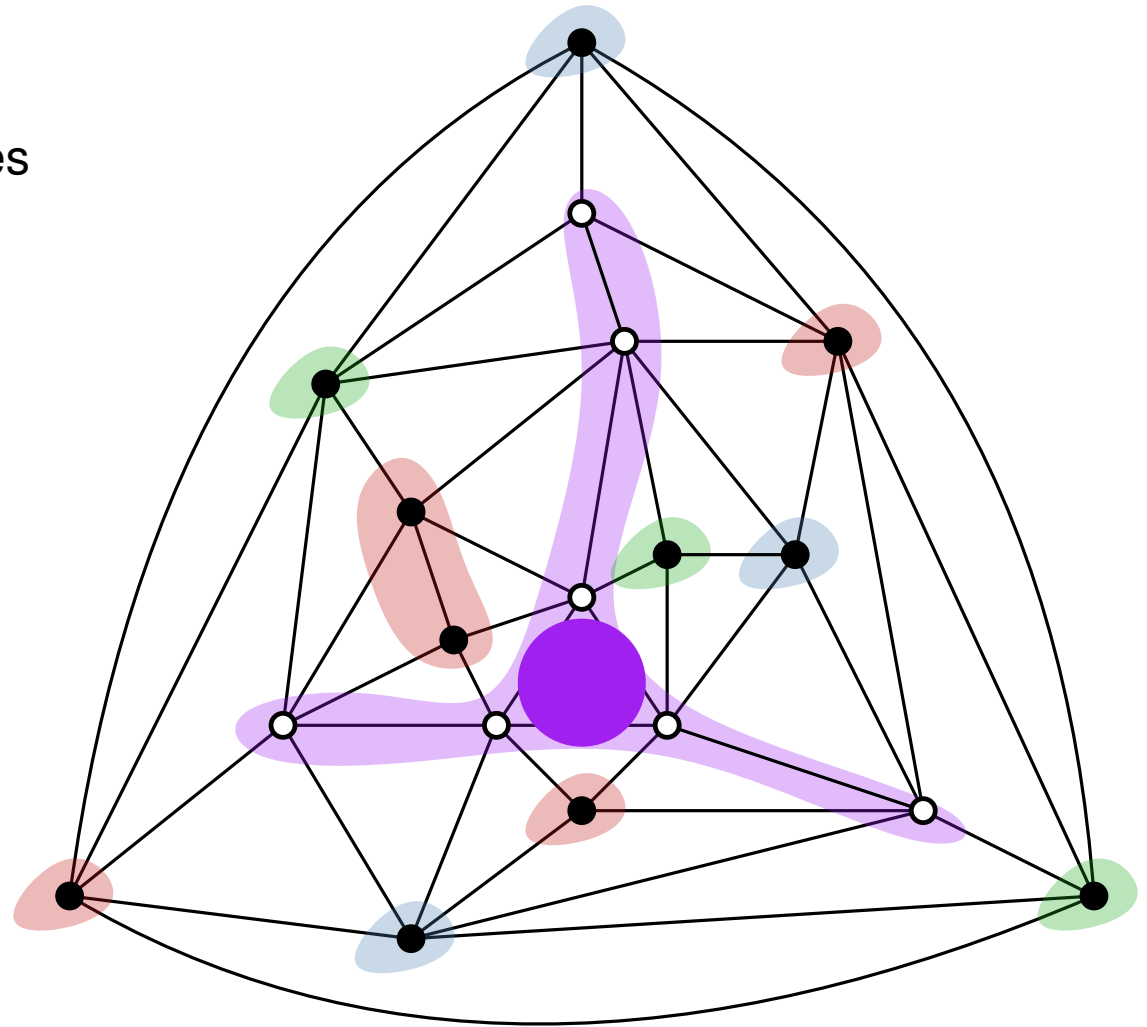
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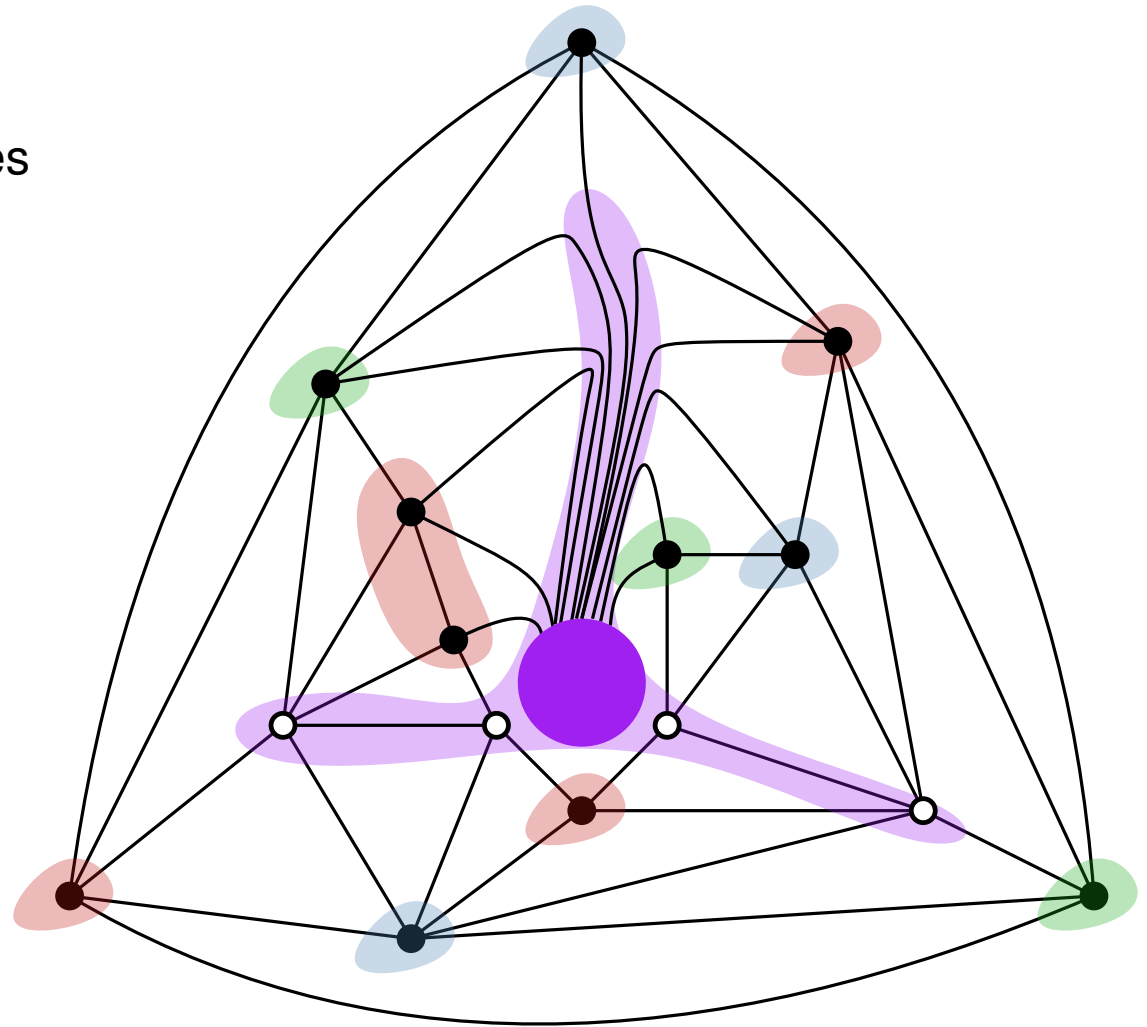
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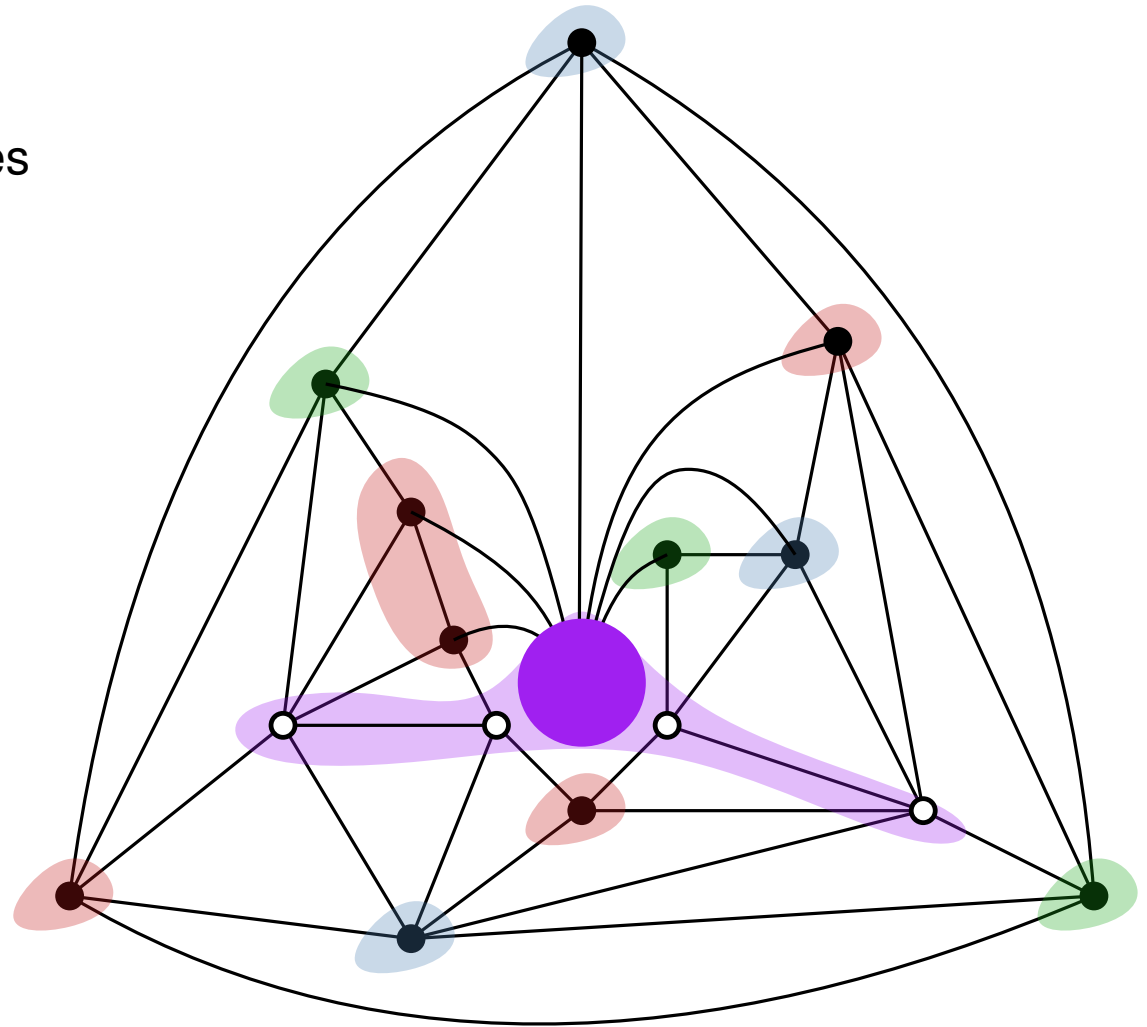
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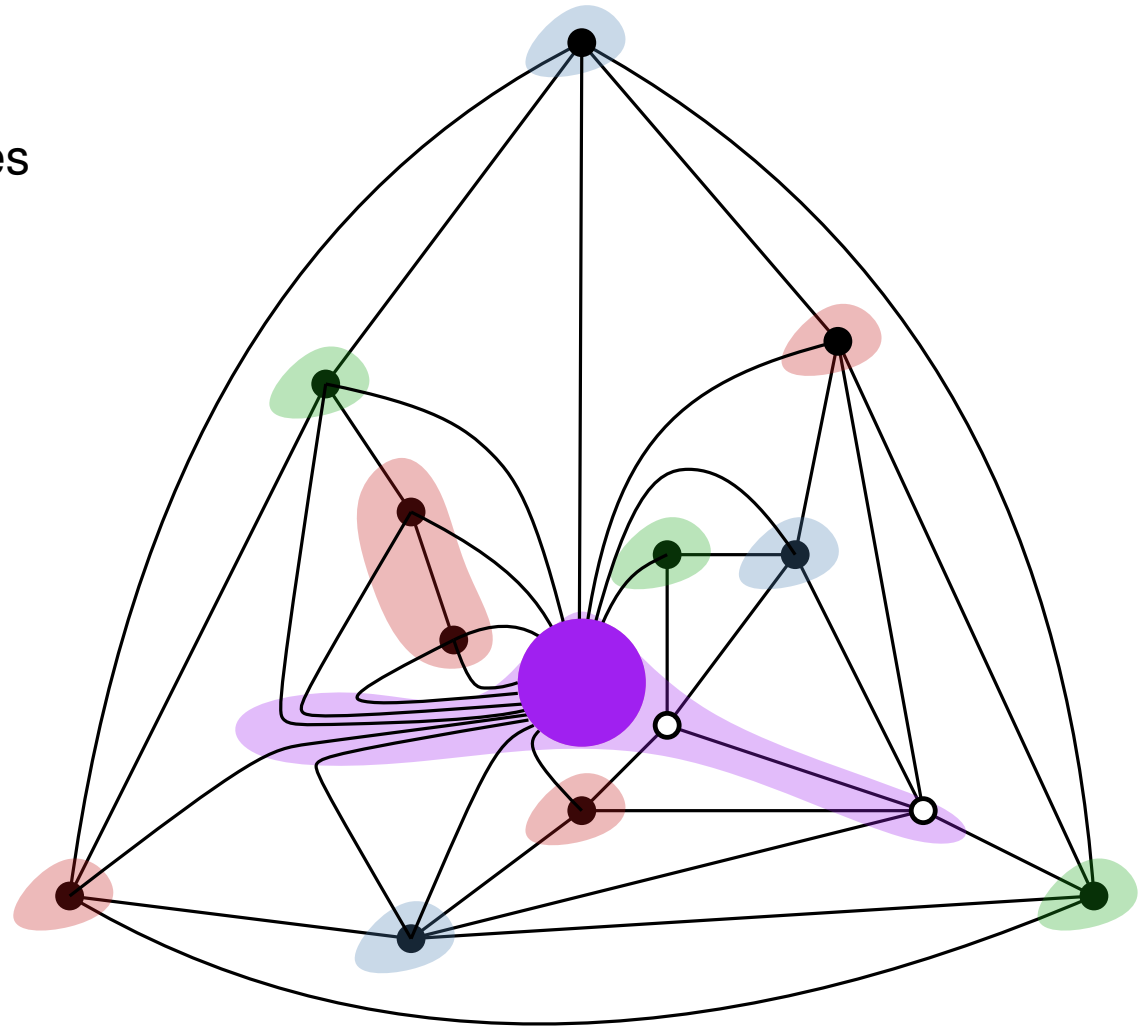
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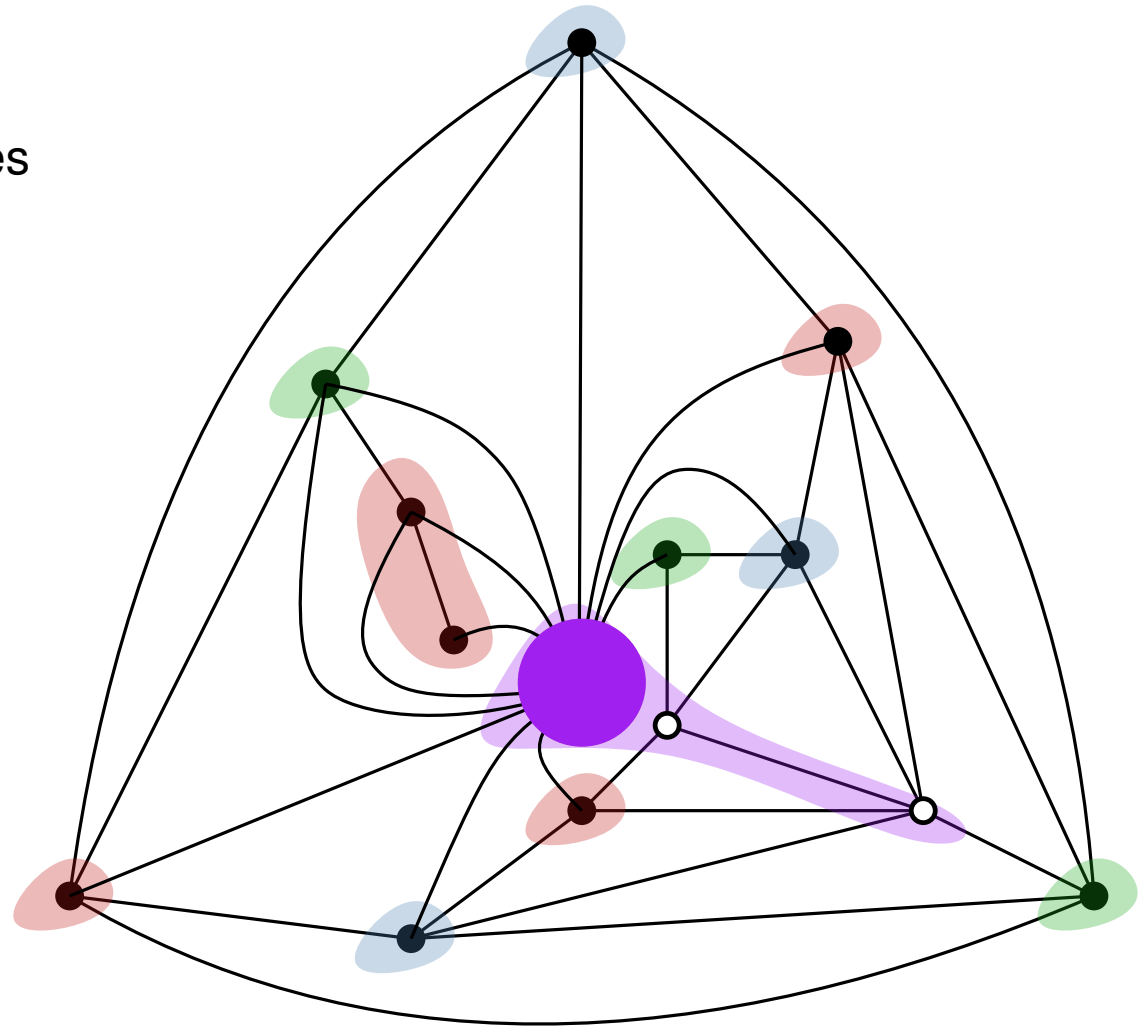
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# Improvement

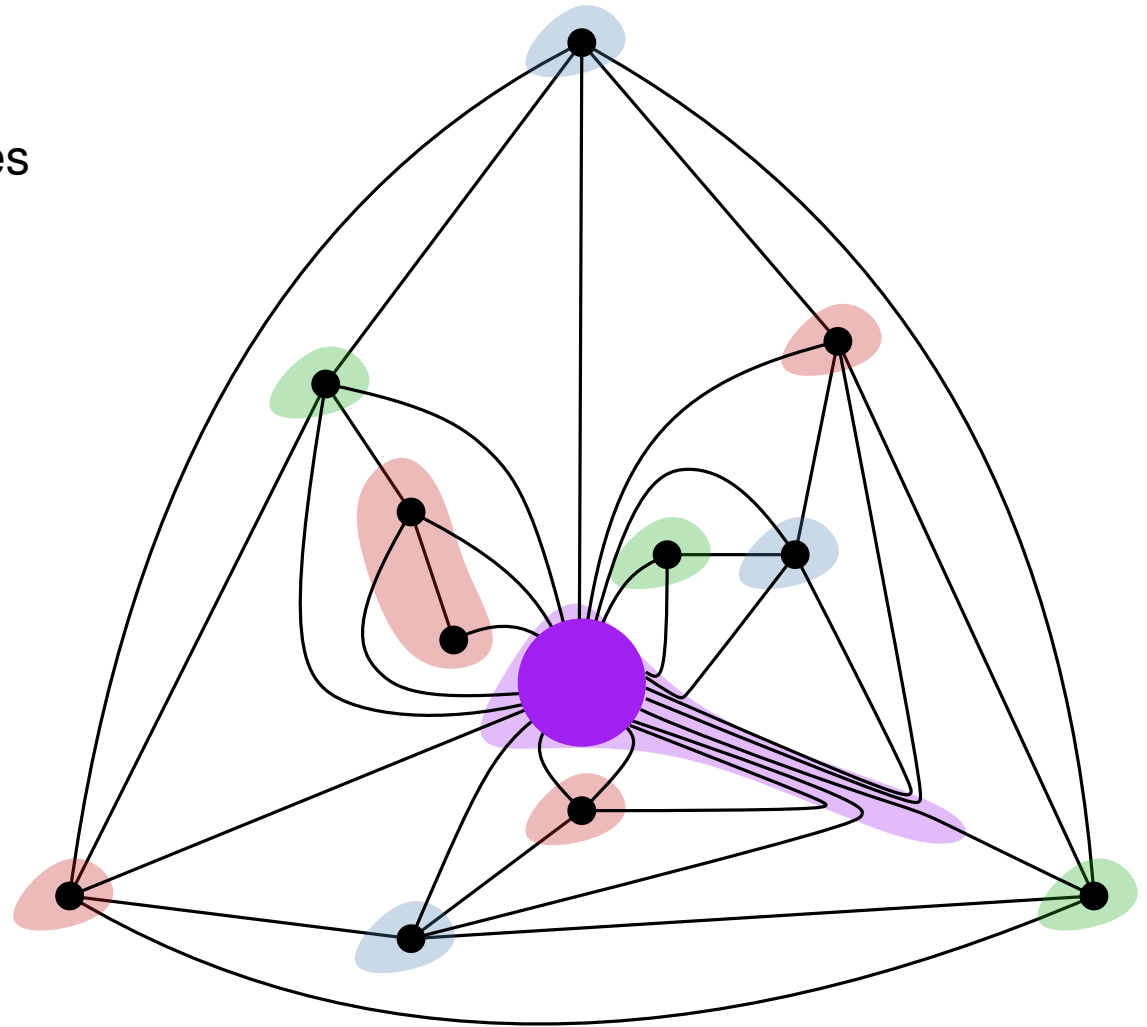
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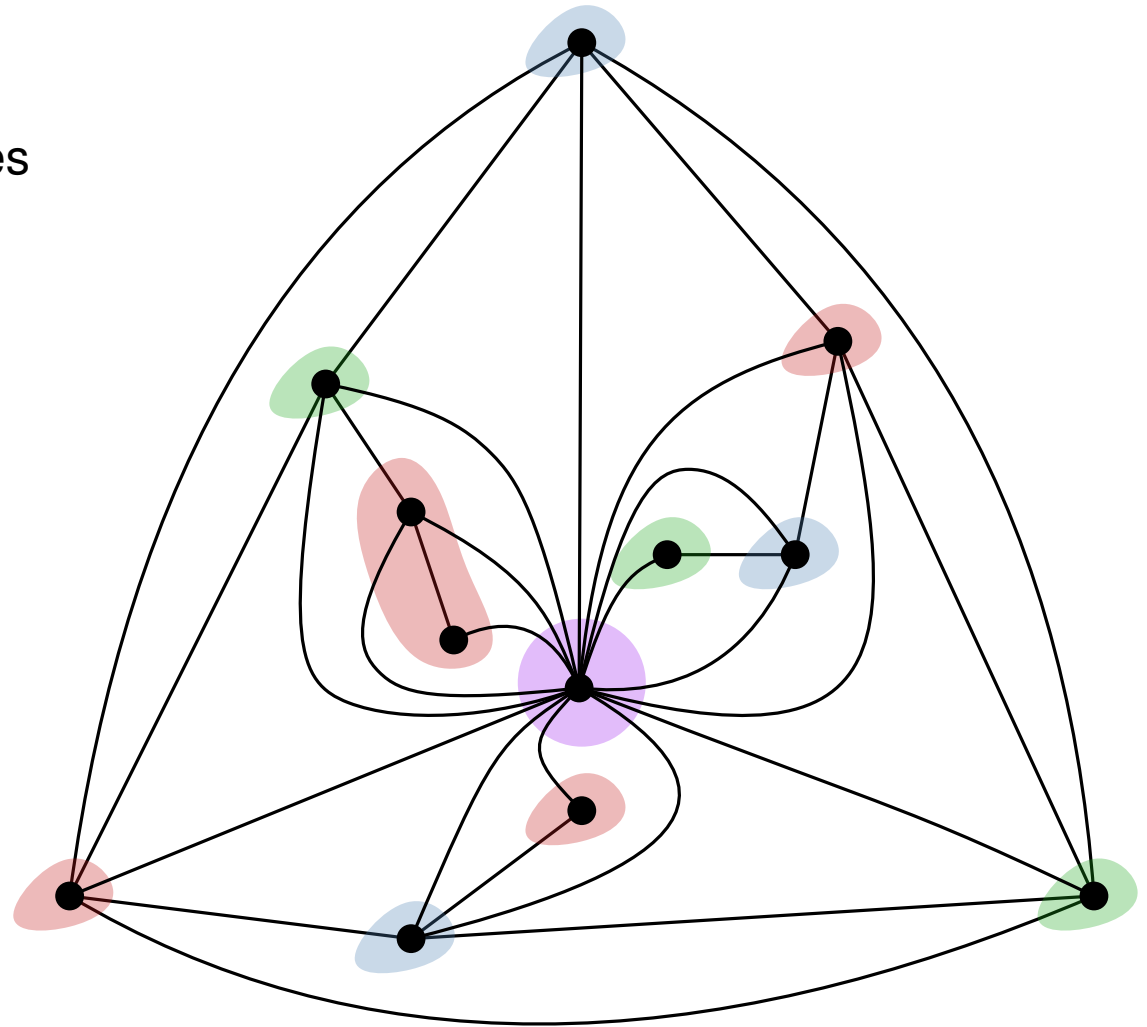
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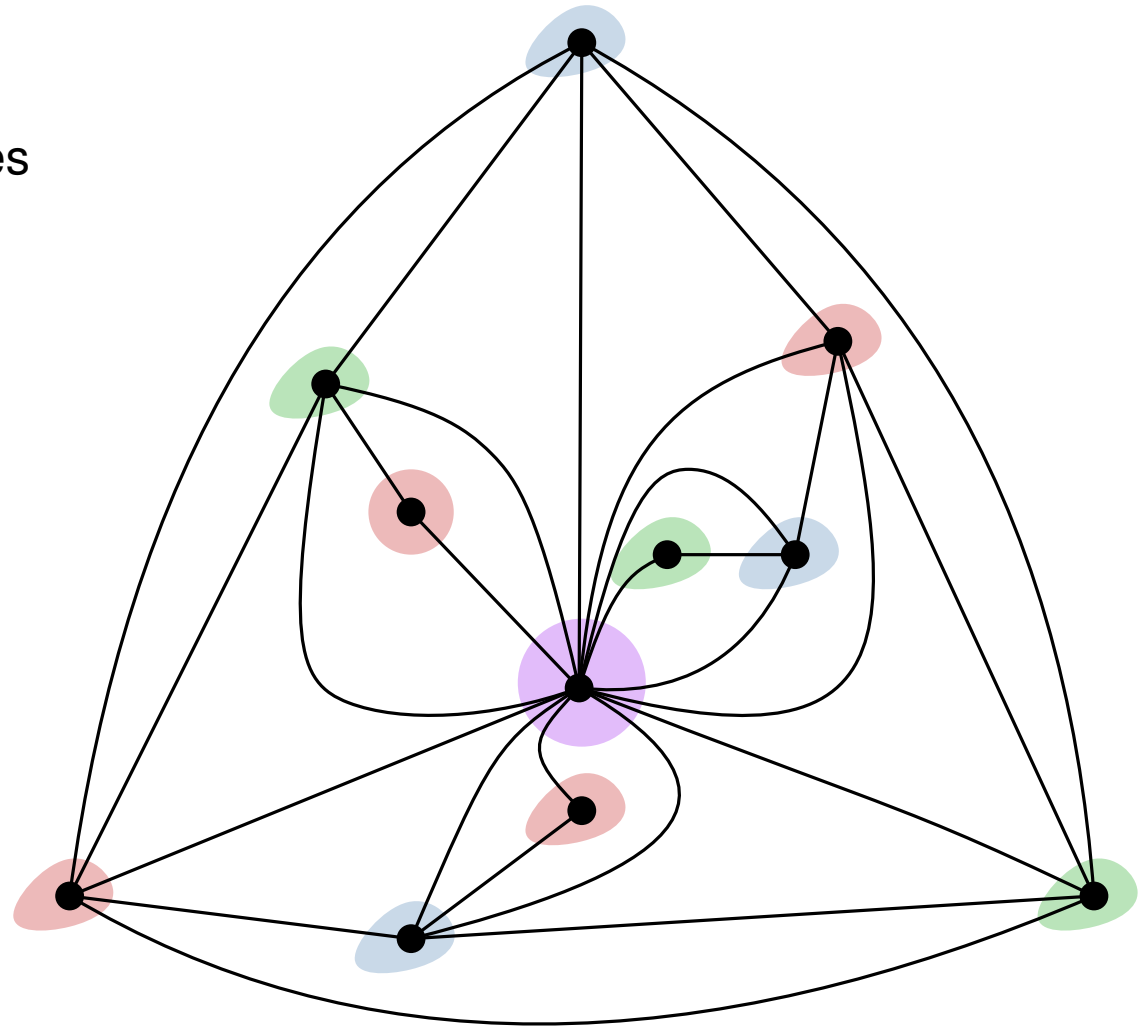
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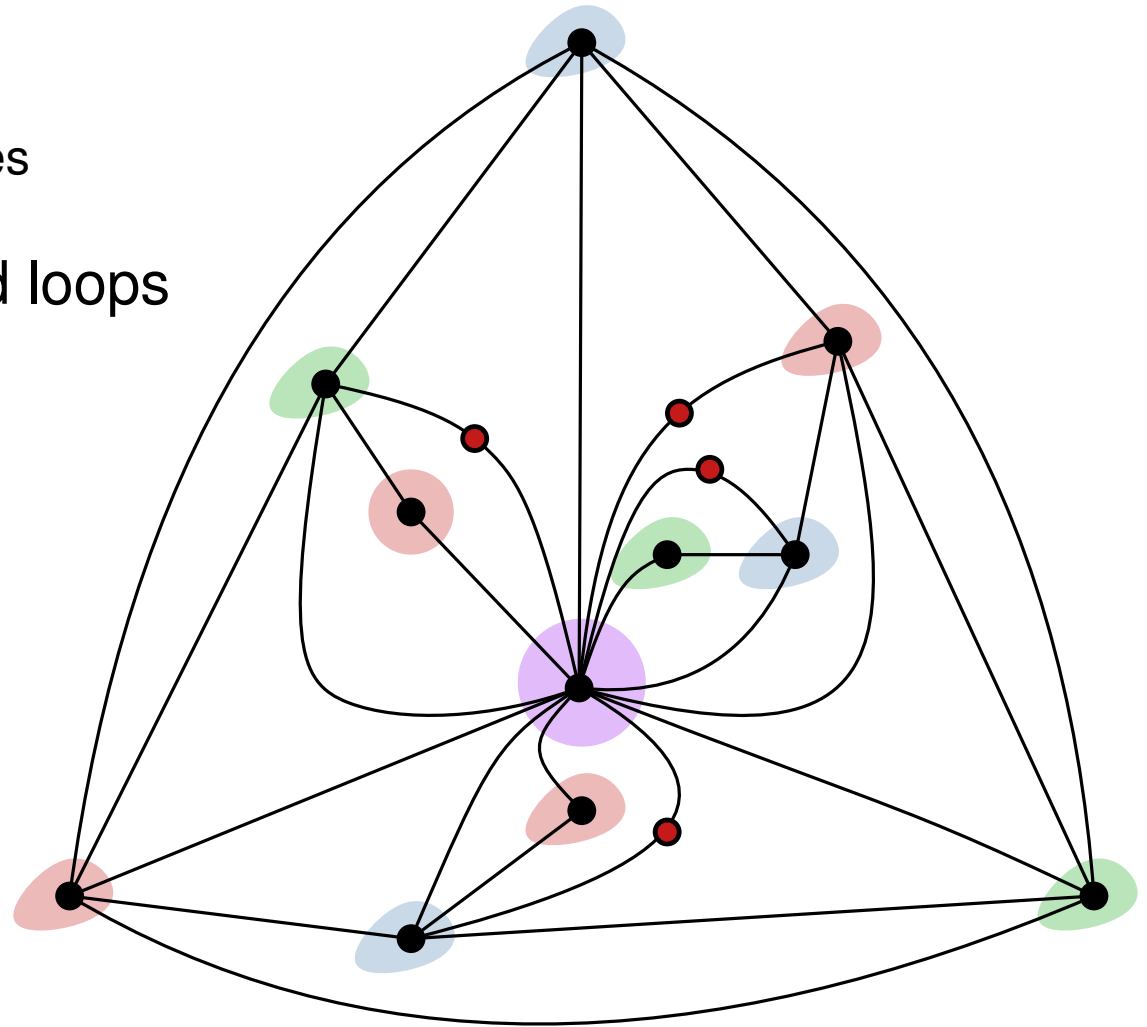
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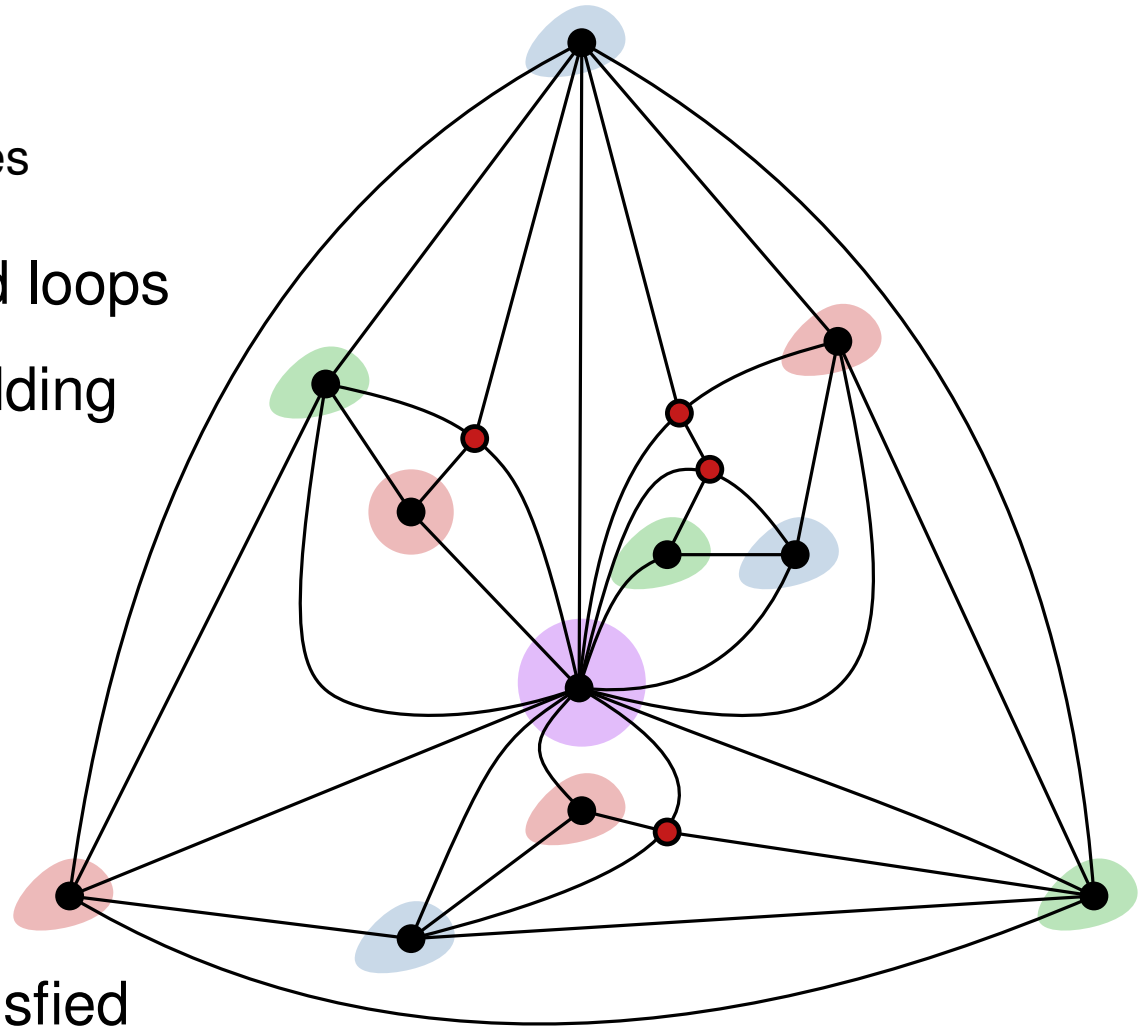
# Improvement

- Contract tripods in  $G$ 
  - preserve embedding
  - remove homotopic parallel edges
- Subdivide parallel edges and loops



# Improvement

- Contract tripods in  $G$ 
  - preserve embedding
  - remove homotopic parallel edges
- Subdivide parallel edges and loops
- Extend by preserving embedding



- All three restrictions are satisfied
- The paths can be ordered with no 3-rainbows

# Summary

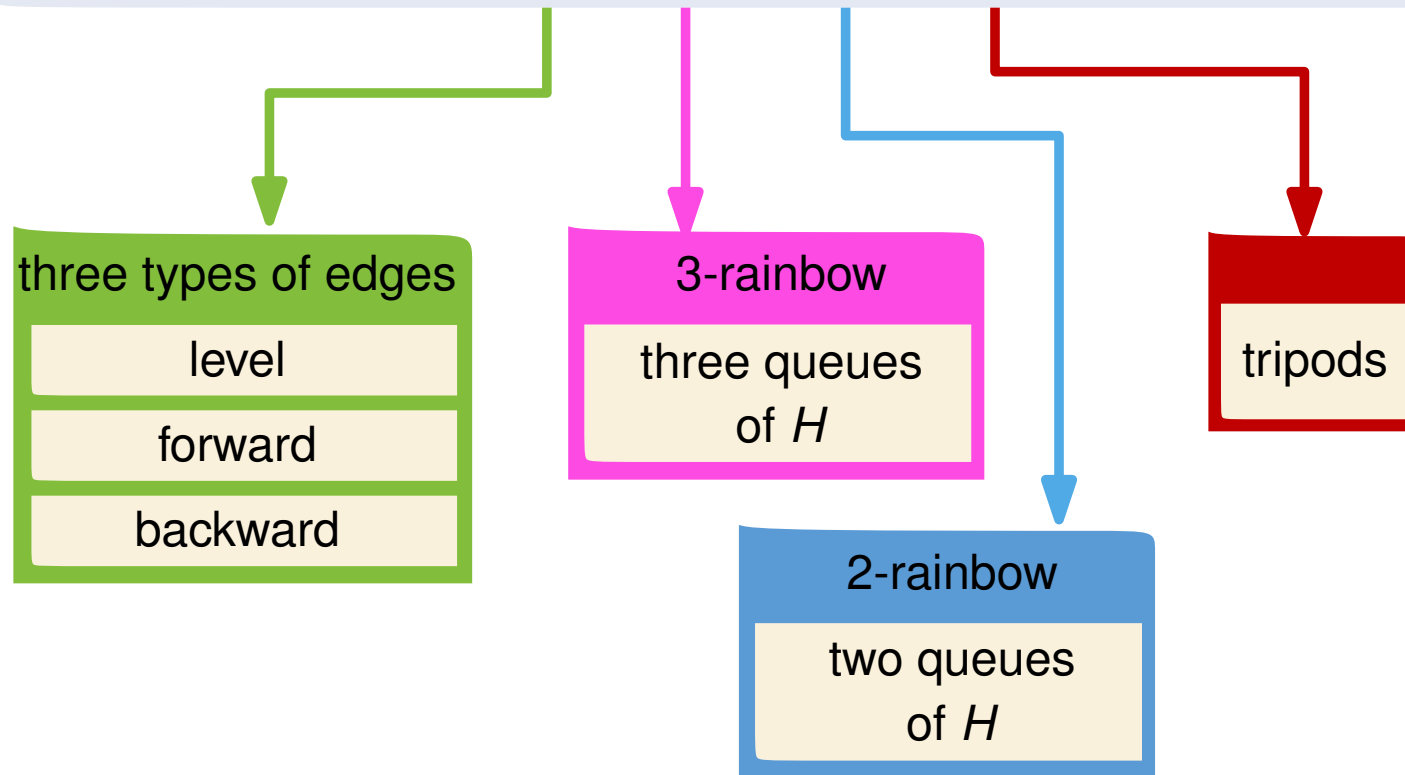
Improved bound:

$$qn(G) \leq 3 \cdot (3 \cdot 3 + 2 \cdot 2) + 3 = 42$$

# Summary

Improved bound:

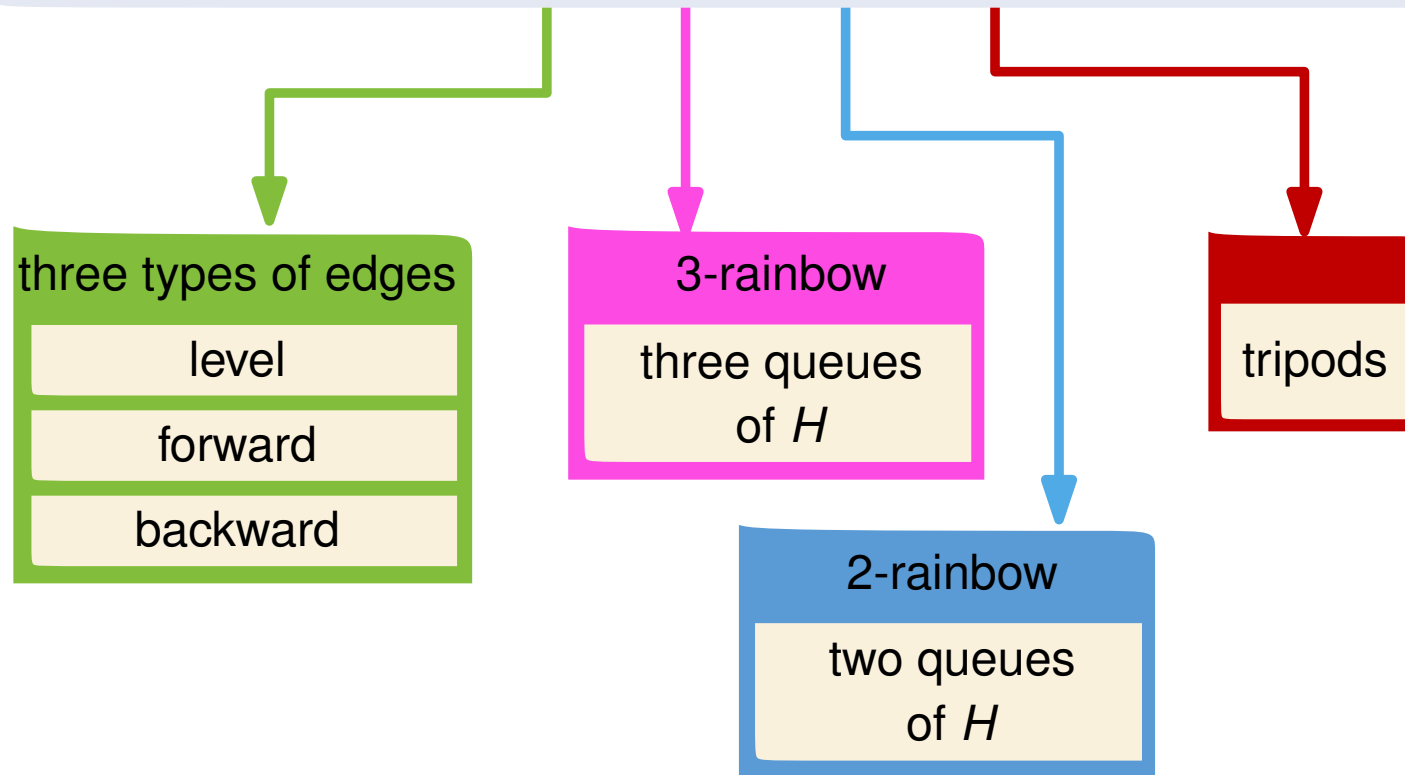
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# Summary

Improved bound:

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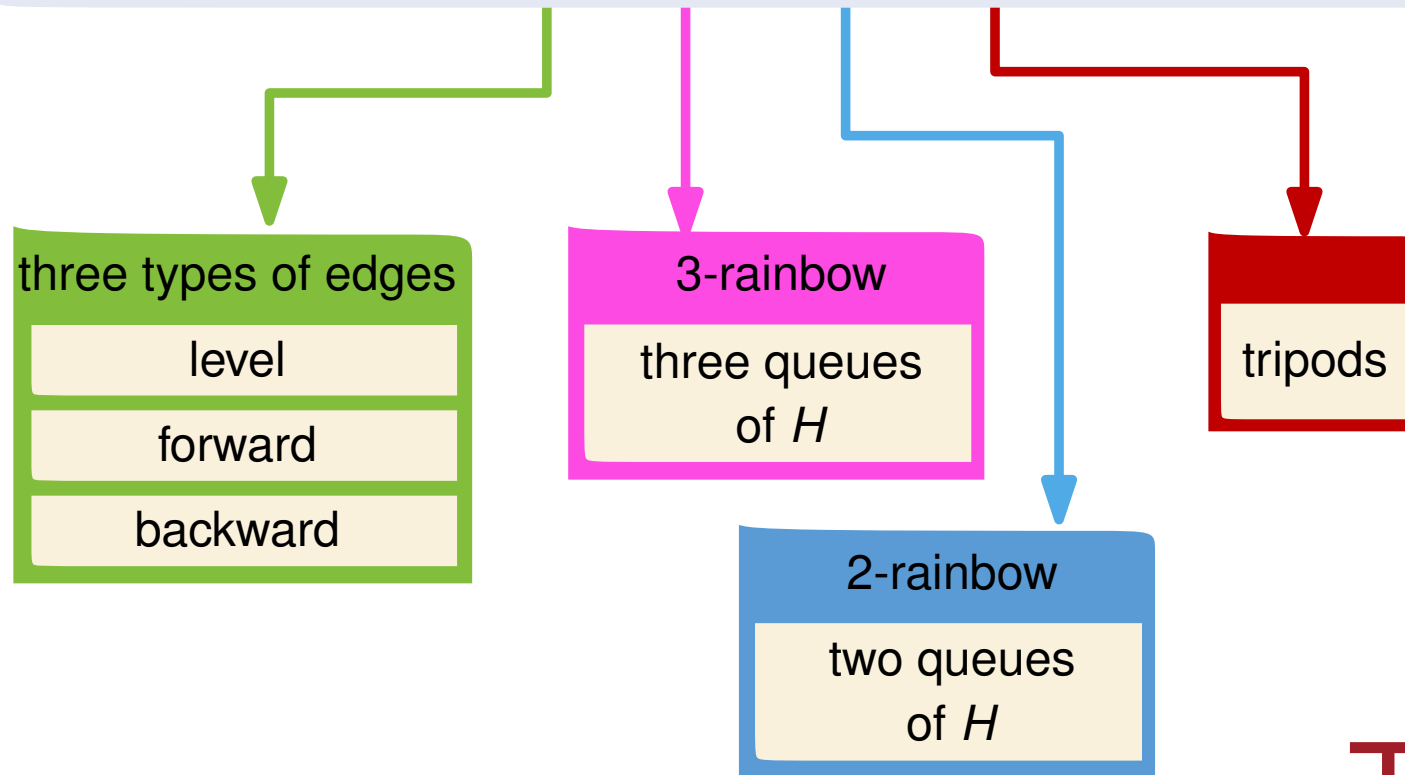
- Further reduce
- Subfamilies



# Summary

## Improved bound:

$$qn(G) \leq 3 \cdot (3 \cdot 3 + 2 \cdot 2) + 3 = 42$$



- Further reduce
- Subfamilies

Thank you